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博士論文

應用於無線-有線通訊之微波  
CMOS 積體放大器  
**Microwave CMOS Integrated  
Amplifiers for Wireless/Wireline  
Communications**

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# **Microwave CMOS Integrated Amplifiers for Wireless/Wireline Communications**

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# Abstract

This study proposed new circuit design techniques to achieve high-performance CMOS integrated amplifiers for wireless/line communications at microwave frequencies. The design concepts were demonstrated by one narrowband and one broadband amplifiers, which were both realized in the standard 0.18- $\mu\text{m}$  RF CMOS technology. The measured results presented superior performances compared with other published works using a similar or even more advanced CMOS technology.

The designed narrowband amplifier is a 24-GHz balanced amplifier (BA) with a gain up to 45 dB. An effective technique,  $\pi$ -type parallel resonance (PPR), was proposed to boost the high frequency gain of a MOSFET by resonating out the inherent capacitances. The miniaturized lumped-element coupler in the circuit occupies a chip area of only  $\sim 2\%$  compared to that of the conventional transmission-line coupler. The BA consumes 123 mW from a supply voltage of 1 V. The proposed CMOS BA presents the highest gain of 45.0 dB with a chip area of  $0.97 \times 0.63 \text{ mm}^2$  (core area:  $0.78 \times 0.43 \text{ mm}^2$ ) among the published narrowband amplifiers with similar technologies and operation frequencies.

The designed broadband amplifier is a 40-Gb/s transimpedance amplifier (TIA). From the measured S-parameters, a transimpedance gain of  $51 \text{ dB}\Omega$  and a 3-dB bandwidth up to 30.5 GHz were observed. A gain-bandwidth product (GBW) enhancement technique,  $\pi$ -type inductor peaking (PIP), is proposed to achieve a bandwidth enhancement ratio (BWER) of 3.31. In addition, the PIP topology used at the input stage decreases the noise current as the operation frequency increases. Under a 1.8 V supply voltage, the TIA consumes 60.1 mW with a chip area of  $1.17 \times 0.46 \text{ mm}^2$ . The proposed CMOS TIA presents a GBW per DC power figure-of-merit ( $GBW/P_{dc}$ ) of  $180.1 \text{ GHz}\Omega/\text{mW}$ .

# 摘要

本文針對微波頻段的無線-有線通訊系統提出了二個創新的技巧用於增加 CMOS 積體電路放大器的效能。我們將這二個方法分別展示在一個窄頻放大器和一個寬頻放大器中，且這第二個放大器都使用了標準的 0.18- $\mu\text{m}$  RF CMOS 製程。與使用相同或更先進製程的文獻相比，這二個放大器的效能皆優於或可與其相提並論。

所設計的窄頻放大器為操作在 24 GHz、增益為 45 dB 的平衡式放大器 (Balanced amplifier, BA)。此放大器使用了本文所提出的窄頻電路技術： $\pi$  型並聯共振器 ( $\pi$ -type parallel resonance, PPR)。藉由共振掉電晶體天生的寄生電容，PPR 可有效的增加電晶體的高頻增益。在耦合器的設計方面，我們使用了微小式的集總元件耦合器因為此面積只有傳統的傳輸線耦合器的 2%。所設計的 BA 特性為：操作電壓 1 V、消耗功率 123 mW、增益 45 dB、晶片面積  $0.97 \times 0.63 \text{ mm}^2$ 、主要電路面積  $0.78 \times 0.43 \text{ mm}^2$ 。跟其它使用相同製程和操作頻率的窄頻放大器所比，此放大器的增益為最高。

所設計的寬頻放大器為 40-Gb/s 的轉阻放大器 (Transimpedance amplifier, TIA)。此放大器使用了本文所提出的寬頻電路技巧： $\pi$  型電感式 peaking ( $\pi$ -type inductor peaking, PIP)。對一個共源級放大器而言，PIP 可增加頻寬達 3.31 倍。另外，PIP 用於輸入級也可使得雜訊電流隨著頻率增加而減少。所設計的 TIA 特性為：操作電壓 1.8 V、消耗功率 60.1 mW、轉阻增益 51 dB $\Omega$ 、頻寬 30.5 GHz、晶片面積  $1.17 \times 0.46 \text{ mm}^2$ 、增益頻寬積除以直流功率 180.1 GHz $\Omega$ /mW。

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我的實驗室生涯可以追溯到我在五專時期的第五年。當時一同渡過辛苦但有趣的日子有小明、吳元吉、歷蘇、和周蘇豪等。常常為了買零件而一起穿梭在光華商場、寧夏商場、景美等地。晚上八點以後回家是基本的，有時因為無法完成實驗而要徹夜待在實驗室。第一次體驗到實驗室的苦日子但後來的成果相對之下也就更甜美了。

後來升學到了崑山科大。第一次離開台北到了台南，有陳其倫常常帶我趴趴走體驗台南這個古都。學業上的伙伴則有嘉健、育達等。

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# Chapter I: Introduction

The dramatically increased demand on the data capacity has pushed the operation frequency of the wireless system toward 24- and 60-GHz and the data rate of the wireline system toward 40- and 100-Gb/s. Traditionally, the circuit blocks of these systems were built by using III-V [1]-[5] or SiGe [6]-[10] technologies due to the superior transistor performances in the microwave frequency range. The continuous scaling also makes CMOS technology an excellent candidate for microwave applications, which owns the advantages of high integration level, high yield, low power consumption, and low cost compared with other technologies. However, the ultimate limitations for the operation frequency of MOSFETs (unity current gain cut-off frequency  $f_T$  and maximum oscillation frequency  $f_{max}$ ) and the CMOS-based circuits are still the inherent capacitances of the transistors, which include gate-source capacitance  $C_{gs}$ , gate-drain capacitance  $C_{gd}$ , and drain-source capacitance  $C_{ds}$  [11]. The relations between  $f_T, f_{max}$  and the parasitic capacitances can be expressed as [12]:

$$f_T = g_m / (2\pi(C_{gs} + C_{gd})) \quad (1.1)$$

$$f_{max} \propto \sqrt{f_T / C_{gd}} \quad (1.2)$$

where  $g_m$  is the transconductance of MOSFET.

To improve the transistor speed, several circuit techniques have been reported for narrowband and broadband applications. For narrowband circuits, the basic idea is using the inductor to resonate out the parasitic capacitances in parallel [13]-[16]. The number of the  $LC$  resonators is usually one or two. In this study, the  $\pi$ -type parallel resonance

(PPR) is proposed which employs three resonators to further enhance the frequency response [17]-[18].

To demonstrate the proposed PPR, a 24-GHz 45-dB gain CMOS balanced amplifier (BA) with a noise figure (NF) of 10.8 dB was designed and implanted by 0.18- $\mu\text{m}$  CMOS technology [17]. The proposed high-gain BA can be employed as a gain block for the post-stage amplification to further increase the signal level, as shown in Fig. 1.1. In this case, its contribution to the total noise figure is not significant if a low-noise amplifier (LNA) is used as the previous stage. Linearity is also an important consideration, and there is typically a trade-off between linearity and gain. For the high-gain design here, a relatively lower input 1-dB gain compression point  $P_{1dB,in}$  is expected. This amplifier may find suitable applications in a communication system where the received signal level is low at the front-end, thus the low  $P_{1dB,in}$  point is not a major concern. With the high-gain amplifier used, the overall signal level can be boosted substantially to relax the requirement for other stages in the system. For example, a mixer with a small conversion gain or even a passive type can be used to maintain an overall signal linearity.

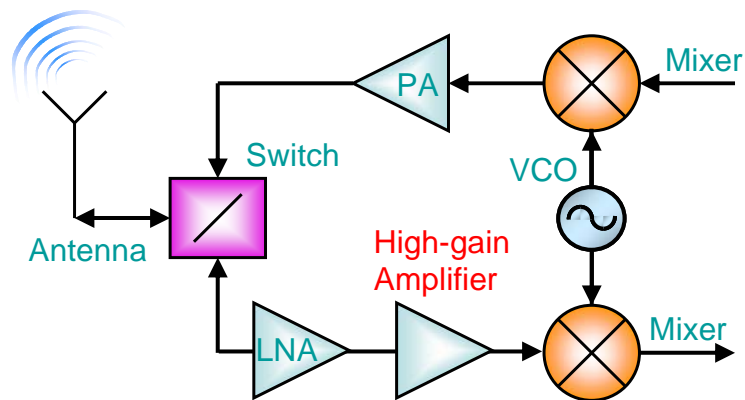


Fig. 1.1. Block diagram of a typical wireless communication system with a high-gain amplifier inserted between the LNA and mixer..

For broadband circuits, there are many strategies such as  $f_T$  doubler [19], negative Miller capacitance [19]-[20], negative impedance converter [19], distributed amplifier (DA) [21]-[25], and inductive peaking technique [26]-[34], as shown in Fig. 1.2. The first three techniques can only be realized in a differential configuration, which often limits their applications. The DA configuration is a popular technique but the power consumption and chip area are usually large. This is because each gain stage is connected in parallel instead of cascaded together. Another popular choice is the inductive peaking technique. The basic idea is that the inductor introduces a zero to cancel the original  $RC$  pole to extend the circuit bandwidth. Here, an effective technique of  $\pi$ -type inductor peaking (PPR) is proposed which presents a bandwidth enhancement ratio (BWER) up to 3.31 [29]-[30].

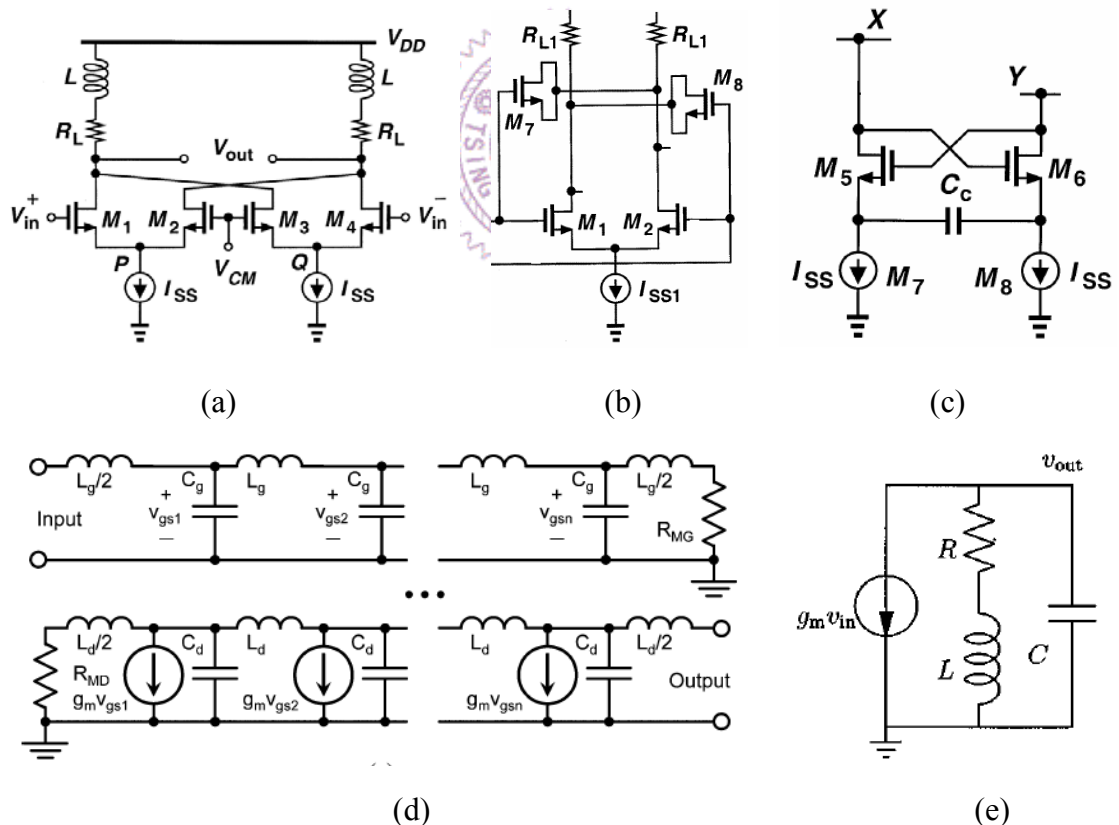


Fig. 1.2. Reported gain-bandwidth product (GBW) enhancement techniques for broadband circuits: (a)  $f_T$  doubler, (b) negative Miller capacitance, (c) negative impedance converter, (d) distributed amplifier, and (e) inductive peaking technique.

For the wireline communication system, transimpedance amplifier (TIA) plays an important role since it is the first gain stage of the receiver chain, as shown in Fig. 1.3. A 40-Gb/s TIA is realized in a 0.18- $\mu\text{m}$  CMOS technology to demonstrate the proposed PIP technique [29]-[30]. In addition to the bandwidth enhancement, TIA designed with PIP presents a trend of decreasing input-referred noise current as the operation frequency increases in the desired bandwidth.

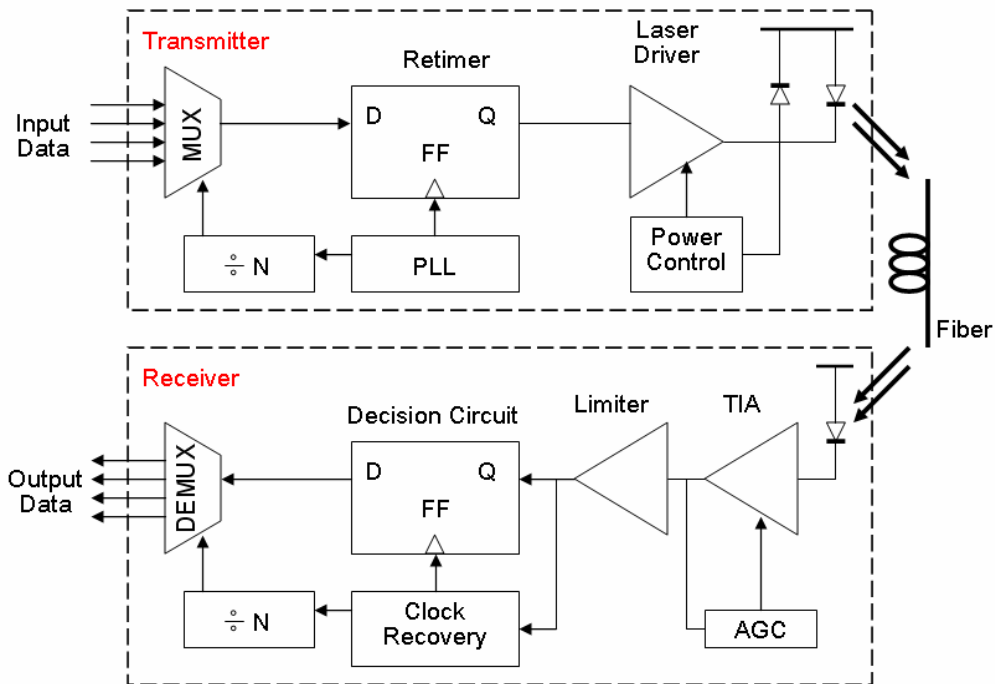


Fig. 1.3. Block diagram of the wireline communication system.

## 1.1 Overview of Thesis

The remaining chapters in this thesis include the analysis and design method of PPR and PIP in Chapter II and III, respectively. The design details, simulation results, and measurement results of the 24-GHz BA using PPR technique are presented in Chapter IV, and those of the 40-Gb/s TIA using PIP technique are described in Chapter V. Finally, Chapter VI concludes this thesis.

# Chapter II: Performance Boosting Techniques for Narrowband Amplifiers

To improve the transistor speed for narrowband amplifiers, the basic idea is using inductors to resonate out the parasitic capacitances in parallel [13]-[16]. The number of the  $LC$  resonators is usually one or two. Here, the  $\pi$ -type parallel resonance (PPR) is proposed which employs three resonators to have a further enhanced frequency response [17]-[18].

## 2.1 $\pi$ -type Parallel Resonance (PPR)

From the modeling point of view, a detailed equivalent circuit model of a RF MOSFET can be represented as shown in Fig. 2.1 [35]-[36]. The core transistor is a BSIM model for logic MOSFET, and the resistors ( $R_{gm}$ ,  $R_{dm}$ , and  $R_{sm}$ ) and capacitors ( $C_{gsm}$ ,  $C_{gdm}$ , and  $C_{dsm}$ ) account for the parasitics from the external metal routing. The junction diode  $D_{dbf}$  is the area and field-edge sidewall diode from drain to bulk, and  $D_{dbg}$  is the gate-edge. In addition,  $D_{sbf}$  and  $D_{sbg}$  are for those from source to bulk. The resistors ( $R_{dbm}$ ,  $R_{sbm}$ , and  $R_{bm}$ ) and capacitors ( $C_{dbm}$ ,  $C_{sbm}$ , and  $C_{bm}$ ) account for the effects from Si substrate. For a common-source (CS) amplifier, a simplified equivalent circuit model can be used, as shown in Fig. 2.2, where the bulk and source are connected to the ground. Based on this simplified circuit model, the RF performance of a MOSFET is ultimately limited by the inherent capacitances including gate-source capacitance  $C_{gs}$ , gate-drain capacitance  $C_{gd}$ , and drain-source capacitance  $C_{ds}$ . A simple yet effective approach, PPR, is proposed here to improve the device frequency response [17]-[18]. By adopting inductors in parallel with the intrinsic capacitances, the parallelly resonated  $LC$  networks become an open circuit at the desired operation frequency  $f_o$ . As

a consequence, the capacitance limited high frequency response of the MOSFET can be improved significantly.

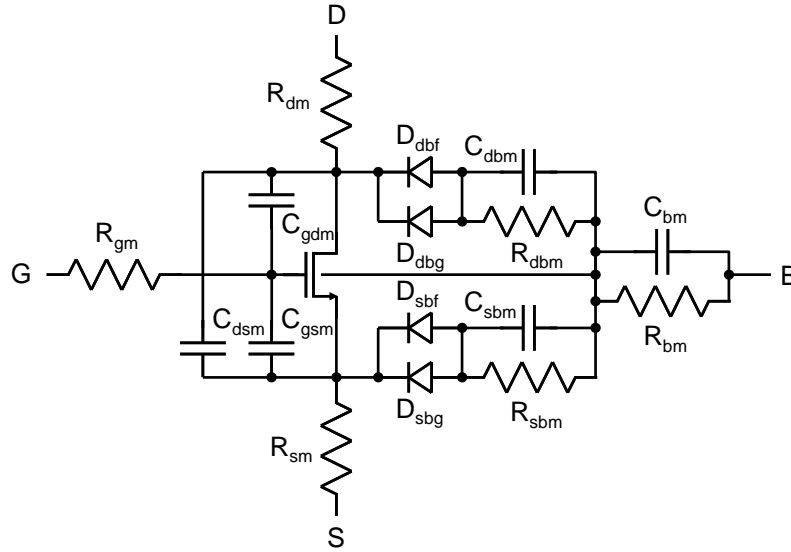


Fig. 2.1. Detailed equivalent circuit model of a RF MOSFET.

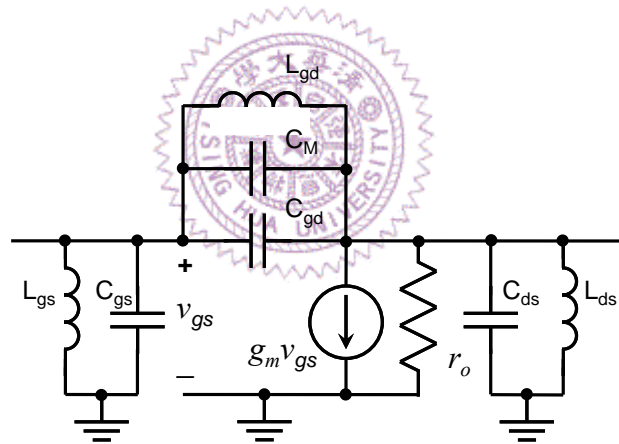


Fig. 2.2. Simplified small-signal equivalent circuit model of a MOSFET with  $\pi$ -type parallel resonance (PPR).

As shown in Fig. 2.2, the PPR inductors are the gate-source inductor  $L_{gs}$ , gate-drain inductor  $L_{gd}$ , and drain-source inductor  $L_{ds}$ , and  $C_M$  is an intentional Miller capacitor. Using the simple resonant equation for a parallel  $LC$  network, the inductances can be determined by:

$$L_{gs} = 1/(f_o^2 C_{gs}) \tag{2.1}$$



$$L_{ds} = 1/(f_o^2 C_{ds}) \quad (2.2)$$

$$L_{gd} = 1/(f_o^2 (C_{gd} + C_M)) \quad (2.3)$$

With the inductors properly designed, the devices can achieve a maximum voltage gain  $A_0$  of  $g_m r_o$  at  $f_o$ , where  $g_m$  and  $r_o$  are the transconductance and the output resistance of the MOSFET, respectively. It has been reported that using  $L_{gd}$  as the neutralization technique is impractical because a large inductance is required [16]. In this design, an additional capacitor  $C_M$  is inserted between the gate and the drain to lower the required  $L_{gd}$ . At the resonant frequency  $f_o$ , the  $L$  and  $C$  cancel each other thus only a parallel resistor  $R_p$  exists between the two terminals, where  $R_p$  is mainly originated from the parasitic series resistance of an on-chip spiral inductor. These parasitic resistances, especially the one resulting from  $L_{gd}$ , can severely degrade the gain  $A_0$ . A simple method to reduce the undesired resistance in the  $LC$  resonant circuit is to use a smaller inductor by increasing the capacitance. With a capacitor  $C_M$  connected between the gate and the drain intentionally, the required  $L_{gd}$  to resonate at  $f_o$  can be effectively reduced.

## 2.2 Effectiveness of PPR

Fig. 2.3 compares different cases to illustrate the merit of using the proposed PPR technique. For a CS stage biased at  $V_{GS} = V_{DS} = 1\text{V}$ , the simulated power gain  $S_{21}$  is 4.2 dB at 24 GHz. In addition, the maximum available gain  $G_{ma}$  and the unilateral power gain  $U$  are also calculated, which can be written as [37]:

$$G_{ma} = \left| \frac{S_{21}}{S_{12}} \right| \left( k \pm \sqrt{k^2 - 1} \right) \quad (2.4)$$

$$U = \frac{\left| \frac{S_{21}}{S_{12}} - 1 \right|^2}{2k \left| \frac{S_{21}}{S_{12}} \right| - 2 \operatorname{Re} \left( \frac{S_{21}}{S_{12}} \right)} \quad (2.5)$$

where

$$k = \frac{1 - |S_{11}|^2 - |S_{22}|^2 + |S_{11}S_{22} - S_{12}S_{21}|^2}{2|S_{12}||S_{21}|} \quad (2.6)$$

At 24 GHz, the simulated  $G_{ma}$  and  $U$  are 9.5 dB and 10.0 dB, respectively. By employing three ideal PPR inductors,  $S_{21}$  can be improved up to 7.9 dB. The boosted performance is only 1.6 dB and 2.1 dB smaller than  $G_{ma}$  and  $U$ , respectively. With the real inductors and  $C_M$  in the CMOS process,  $S_{21}$  is enhanced to 5.9 dB.

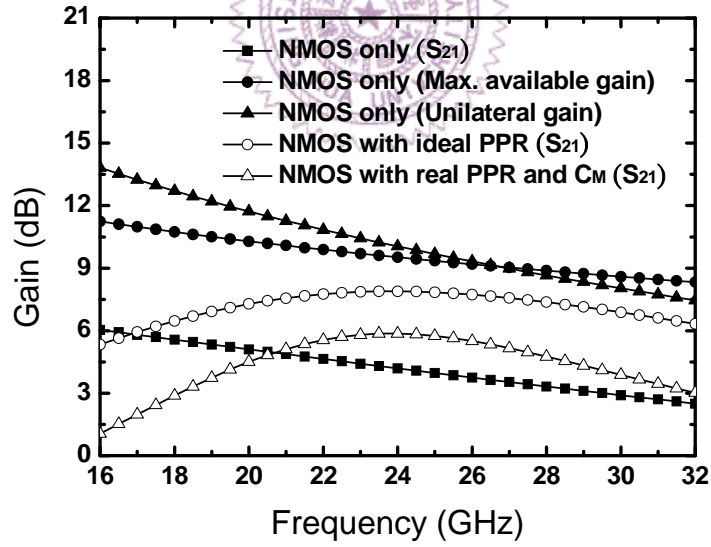


Fig. 2.3. Simulated power gain of a common-source (CS) stage without and with ideal/real PPR inductors.

### 2.3 Noise Analysis

At the resonant frequency, the circuit in Fig. 2.2 can be simplified as a

voltage-controlled current source and  $r_o$ . In this case, the only noise source is the drain thermal noise current. The derived input-referred noise voltage and current can be written as:

$$\overline{v_{n,in}^2} = 4kT\gamma / g_m \quad (2.7)$$

$$\overline{i_{n,in}^2} = 0 \quad (2.8)$$

where  $\gamma$  is the noise factor of the drain thermal noise. Therefore, the noise figure (NF) can be written as:

$$NF = 1 + \frac{\left( \sqrt{\overline{i_{n,in}^2}} + \sqrt{\overline{v_{n,in}^2} Y_s} \right)^2}{4kT / R_s} = 1 + \frac{\gamma}{g_m R_s} \quad (2.9)$$

where  $R_s$  and  $Y_s$  are the resistance and admittance of the source impedance, respectively. For a typical  $\gamma$  value of 1, a source impedance of 50  $\Omega$ , and a  $g_m$  of 30 mS, a low  $NF$  of 2.2 dB can be expected. However, the parasitic effects of NMOS, PPR inductors, and  $C_M$  introduce more noise sources. A higher simulated  $NF$  of 4.9 dB is obtained at 24 GHz for the case of NMOS with real PPR and  $C_M$ .

## 2.4 Summary

With three external inductors, the proposed PPR technique can increase the gain of the MOS transistors and circuits effectively. This promising technique can be used in many building blocks of narrowband communication systems to boost the performances. A high-gain 24-GHz balanced amplifier employs the PPR technique will be demonstrated in Chapter IV.

# Chapter III: GBW Enhancement Techniques for Broadband Amplifiers

For the small-signal equivalent circuit model of a cascaded CS amplifier, as shown in Fig. 3.1, we can assume that the 3-dB bandwidth of each stage is determined by the drain resistance  $R_d$ , equivalent drain capacitance  $C_d$ , and equivalent gate capacitance  $C_g$  of the next stage. The ratio of  $C_g$  to  $C_d$  can be determined from the BSIM 3 model provided by the foundry for a more practical estimation. The extracted  $C_g/C_d$  is frequency dependent, varying between 2.5 and 3.5 (0.5 ~ 60 GHz). Note that the  $f_T$  of 0.18- $\mu\text{m}$  MOSFETs is  $\sim 60$  GHz (estimated from the foundry provided transistor model). To simplify the circuit analysis,  $C_g/C_d$  is set to be 3 here. Based on this small-signal circuit model, three different inductor peaking techniques and the proposed  $\pi$ -type inductor peaking technique will be compared in the following sections.

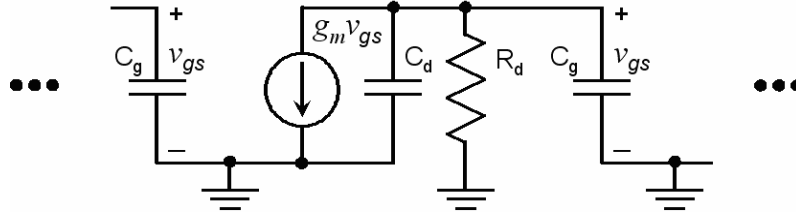


Fig. 3.1. Small-signal equivalent circuit model of a cascaded CS amplifier.

## 3.1 Shunt Peaking

The most straightforward bandwidth enhancement technique is probably shunt peaking [26]. By placing an inductor  $L_d$  in series with  $R_d$ ,  $C_d$  and  $C_g$  of the next stage can be canceled out by a shunt  $LC$  resonance. A different explanation is that the peaking inductor introduces a zero to extend the circuit bandwidth. Based on the transimpedance transfer function, the design equation for  $L_d$  can be derived and written as:

$$L_d = m_d R_d^2 (C_d + C_g) \quad (3.1)$$

With an  $m_d$  of 0.71, the maximum achievable BWER is 1.85 with a gain peaking of 1.5 dB, as shown in Fig. 3.2, curve *b*. Note that curve *a* shows the normalized frequency response of this circuit without any bandwidth enhancement method applied.

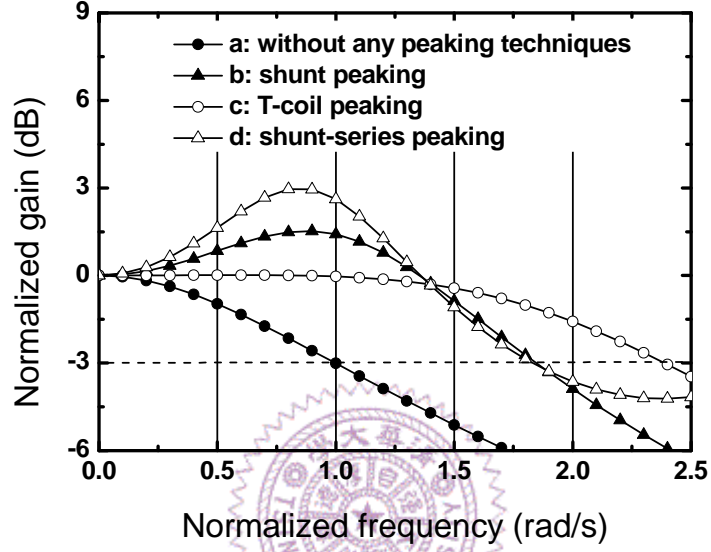


Fig. 3.2. Bandwidth improvement by three previously published wideband techniques. [26]-[28]

### 3.2 T-coil Peaking

A more effective technique is the T-coil peaking which utilizes one transformer and one capacitor [27]. The primary coil  $L_{dp}$  is connected between the drain node and  $C_g$ , and the secondary coil  $L_{ds}$  is between  $R_d$  and  $C_g$ . In addition, the bridge capacitor  $C_B$  is connected between drain node and  $R_d$ . Without considering  $C_d$ , the design equations for the transformer and capacitor can be written as:

$$L_{dp} = L_{ds} = \frac{C_g R_d^2}{4} \left( 1 + \frac{1}{4\zeta^2} \right) \quad (3.2)$$

$$k = \frac{4\zeta^2 - 1}{4\zeta^2 + 1} \quad (3.3)$$

$$C_B = \frac{C_g}{16\zeta^2} \quad (3.4)$$

For a flat group delay response, a  $\zeta$  of  $\sqrt{3}/2$  was designed which results in a BWER of 2.82 if  $C_d$  is neglected. Note that the BWER obtained in Fig. 3.2, curve *c* is 2.40 since  $C_d$  is taken into account for a fair comparison.

### 3.3 Shunt-Series Peaking

The third technique is shunt-series peaking which employs two inductors, one inductor  $L_d$  is in series with  $R_d$  and the other inductor  $L_s$  is with  $C_g$  [28]. The design equation for both inductors can be written as:

$$L_d = \frac{L_s}{2} = \frac{R_d^2(C_d + C_g)}{4} \quad (3.5)$$

The original circuit analysis presented in [28] shows a BWER of 3.46 with a gain peaking of 1.8 dB based on the assumption that the ratio of  $C_g$  to  $C_d$  is one. However, the value is reduced to 1.83 when a more practical ratio of three is used, as shown in Fig. 3.2, curve *d*.

### 3.4 $\pi$ -type Inductor Peaking (PIP)

Here, a more effective bandwidth extension technique is proposed. On the basis of including the drain capacitance  $C_d$ , and with a  $C_g/C_d$  ratio of 3, an improved BWER up to 3.31 can be obtained. The details will be discussed in the following sections.

#### 3.4.1 Design Concept of PIP

Fig. 3.3 shows the small-signal equivalent circuit model of a cascaded CS stage

including the PIP inductors ( $L_{d1}$ ,  $L_{s1}$ , and  $L_{d2}$ ), where  $R_{d1}$  and  $R_{d2}$  are the drain bias resistors. The progressive bandwidth improvement by adding each peaking inductor is described as follows.

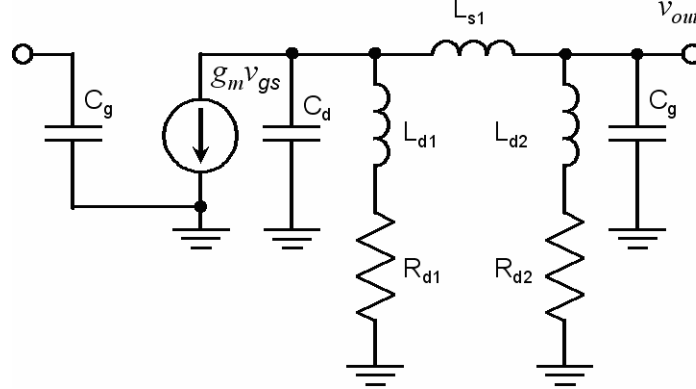


Fig. 3.3. The equivalent circuit model of one gain stage with the  $\pi$ -type inductor peaking (PIP) technique.

Without the PIP inductors, the drain current  $g_m v_{gs}$  flows into  $C_d$ ,  $C_g$ ,  $R_{d1}$ , and  $R_{d2}$ , and generates the output voltage  $v_{out}$ . In this case, the 3-dB bandwidth  $\omega_0$  is limited by the resistive and capacitive loads. By inserting  $L_{d2}$  in series with  $R_{d2}$ , the bandwidth is increased by a parallel resonance with  $C_d$  and  $C_g$ . An alternative explanation is that the inductor delays the transient current into  $R_{d2}$  and forces more current to flow into the loading capacitor, which improves the speed of the output transient signal and results in an increased circuit bandwidth. If  $L_{s1}$  is also employed, the bandwidth can be further enhanced by a series resonance with  $C_g$  at higher frequencies, which forces more drain current to flow through  $L_{s1}$  and reach the output terminal. In time domain, the transient current charges the two capacitors separated by  $L_{s1}$  at different times. As a result, the charging time is reduced leading to an improved bandwidth. Finally, by introducing one more inductor  $L_{d1}$ ,  $C_d$  and  $C_g$  can be resonated in parallel with  $L_{d1}$  at even higher frequencies to obtain a further enhanced bandwidth. Based on the circuit shown in Fig. 3.3, Fig. 3.4 shows the frequency response of the above four conditions, where  $\omega_0$  and the DC gain are both normalized. The gradually improved bandwidth can be observed

as adding the three peaking inductors step by step.

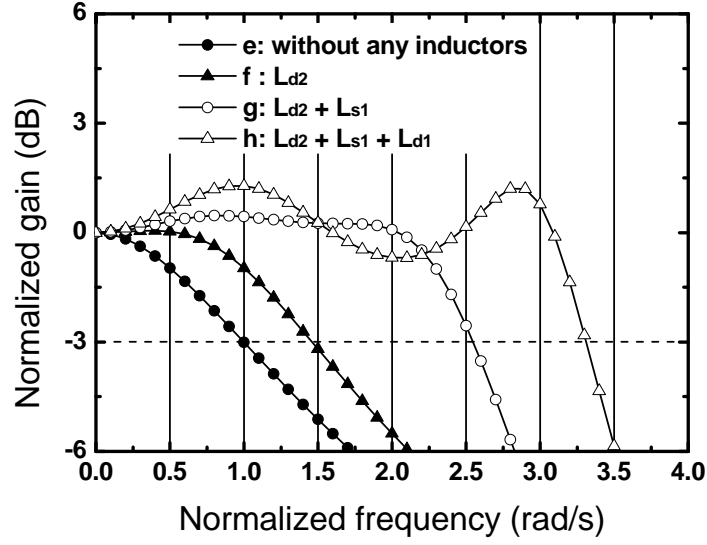


Fig. 3.4. Comparison of the bandwidth enhancement results using PIP technique under different numbers of peaking inductors, where  $C_g = 3C_d$  and  $R_{d1} = R_{d2}$ .

### 3.4.2 Transfer Function of PIP

To obtain a more comprehensive understanding of the frequency response, the transimpedance transfer function  $Z_{PIP}(s)$  of the circuit in Fig. 3.3 is derived as:

$$Z_{PIP}(s) = \frac{v_{out}}{-g_m v_{gs}} = R_{d1} R_{d2} \frac{1 + s \left( \frac{L_{d1}}{R_{d1}} + \frac{L_{d2}}{R_{d2}} \right) + s^2 \frac{L_{d1} L_{d2}}{R_{d1} R_{d2}}}{D_0 + s D_1 + s^2 D_2 + s^3 D_3 + s^4 D_4 + s^5 D_5} \quad (3.6)$$

where

$$\begin{aligned} D_0 &= R_{d1} + R_{d2} \\ D_1 &= L_{d1} + L_{d2} + L_{s1} + R_{d1} R_{d2} (C_d + C_g) \\ D_2 &= (C_d + C_g) (R_{d1} L_{d2} + R_{d2} L_{d1}) + R_{d1} L_{s1} C_d + R_{d2} L_{s1} C_g \\ D_3 &= L_{d1} C_d (L_{d2} + L_{s1}) + L_{d2} C_g (L_{d1} + L_{s1}) + R_{d1} R_{d2} L_{s1} C_d C_g \\ D_4 &= L_{s1} C_d C_g (R_{d1} L_{d2} + R_{d2} L_{d1}) \\ D_5 &= L_{d1} L_{d2} L_{s1} C_d C_g \end{aligned} \quad (3.7)$$



As can be clearly observed, two zeros  $R_{d1}/L_{d1}$  and  $R_{d2}/L_{d2}$  existed in  $Z_{PIP}(s)$ . By an appropriate design, the zeros can be employed to enhance the bandwidth. The required inductances for bandwidth improvement are determined one by one analytically as follows.

To derive  $L_{d2}$ , the effects of  $L_{d1}$  and  $L_{s1}$  are first neglected by setting  $L_{d1} = L_{s1} = 0$  in (3.6). Normalized by the DC impedance  $R_{d1}/R_{d2}$ , the transfer function  $z_{Ld2}(s)$  becomes:

$$z_{Ld2}(s) = \frac{1 + sL_{d2}/R_{d2}}{1 + s \frac{(L_{d2} + R_{d1}R_{d2}(C_d + C_g))}{R_{d1} + R_{d2}} + s^2 \frac{R_{d1}L_{d2}(C_d + C_g)}{R_{d1} + R_{d2}}} \quad (3.8)$$

The equation indicates that the numerator includes a zero  $\omega_{z1} = R_{d2}/L_{d2}$  and the denominator contains a pair of complex conjugate poles  $\omega_{Ld2,p1}$  and  $\omega_{Ld2,p2}$ , which can be written as:

$$\begin{aligned} & s^2 + s \left( \frac{1}{R_{d1}(C_d + C_g)} + \frac{R_{d2}}{L_{d2}} \right) + \frac{R_{d1} + R_{d2}}{R_{d1}L_{d2}(C_d + C_g)} \\ &= (s + \omega_{Ld2,p1}) \cdot (s + \omega_{Ld2,p2}) \\ &= s^2 + s2\xi\omega_n + \omega_n^2 \end{aligned} \quad (3.9)$$

where  $\xi$  and  $\omega_n$  are the damping factor and the corner frequency of the complex poles, respectively. Note that the frequency response can be affected by the value of  $\xi$ . For  $\xi$  smaller than  $1/\sqrt{2}$ , a gain-peaking characteristic can be observed at around  $\omega_n$ . Therefore, the bandwidth can be enhanced not only by zero but also complex poles. Under  $R_{d1} = R_{d2}$  and  $C_g = 3C_d$ , the required inductance  $L_{d2}$  and the maximum achievable 3-dB bandwidth  $\omega_{Ld2}$  can be derived from the equation  $|z_{Ld2}(\omega_{Ld2})|^2 = 1/2$  with  $\omega_0 = 1/(2R_{d1}C_d)$  [38]:

$$L_{d2} = m_{d2} \cdot R_{d1}^2 \cdot C_d \quad (3.10)$$

where  $m_{d2}$  is 1.50, and the resulted  $\omega_{Ld2}$  equals 1.46, as shown in Fig. 3.4, curve *f*. The improved bandwidth mainly results from the in-band  $\omega_{z1}$  of 1.33, since the complex

poles have a  $\zeta_{Ld2,p1}$  of 0.79 which is larger than  $1/\sqrt{2}$ . Based on (3.8) ~ (3.10),  $\omega_{z1} = 1/(1.5R_{d1}C_d) = 1.33$ ,  $\omega_{Ld2,p1} = \omega_{Ld2,p2} = \sqrt{1/(2L_{d2}C_d)} = 1.15$ , and  $\zeta_{Ld2,p1} = (1/(4R_{d1}C_d) + R_{d2}/L_{d2})/(2\omega_n) = 0.79$ . The properties of the poles and zeros as adding the three peaking inductors step by step are summarized in Table 3.1.

	without PIP	$L_{d2}$	$L_{d2} + L_{s1}$	$L_{d2} + L_{s1} + L_{d1}$
<b>Zero</b>	—	$\omega_{z1} = 1.33$	$\omega_{z1} = 1.33$	$\omega_{z1} = 1.33$ $\omega_{z2} = 2.50$
<b>Pole</b>	$\omega_{p1} = 1.00$	—	—	$\omega_{Ld1,p3} = 1.39$
<b>Complex pole</b>	—	$\omega_{Ld2,p1} = \omega_{Ld2,p2}$ $= 1.15$	$\omega_{Ls1,p1} = \omega_{Ls1,p2}$ $= 1.21$ $\omega_{Ls1,p3} = \omega_{Ls1,p4}$ $= 2.37$	$\omega_{Ld1,p1} = \omega_{Ld1,p2}$ $= 1.28$ $\omega_{Ld1,p4} = \omega_{Ld1,p5}$ $= 3.01$
<b>Damping factor</b>	—	$\zeta_{Ld2,p1} = 0.79$	$\zeta_{Ls1,p1} = 0.82$ $\zeta_{Ls1,p3} = 0.28$	$\zeta_{Ld1,p1} = 0.63$ $\zeta_{Ld1,p4} = 0.14$

Table 3.1. Properties of the poles and zeros of one gain stage with PIP under different numbers of peaking inductors.

After obtaining the required  $L_{d2}$ , the inductance  $L_{s1}$  can be derived from (3.6) by setting  $L_{d1} = 0$ . The normalized transfer function  $z_{Ls1}(s)$  includes additional complex poles of  $\omega_{Ls1,p3}$  and  $\omega_{Ls1,p4}$ . To derive the required inductance and the maximum enhanced bandwidth  $\omega_{Ls1}$ , (3.10) is used. A similar equation for  $L_{s1}$  can be obtained as:

$$L_{s1} = m_{s1} \cdot R_{d1}^2 \cdot C_d \quad (3.11)$$

where  $m_{s1}$  is 0.86, and the associated  $\omega_{Ls1}$  equals 2.55 with a gain variation of 0.5 dB, as shown in Fig. 3.4, curve g. The bandwidth is improved mainly by both the in-band  $\omega_{z1}$  of 1.33, and the additional complex poles with a  $\zeta_{Ls1,p3}$  of 0.28 and a  $\omega_{Ls1,p3}$  ( $\omega_{Ls1,p4}$ ) of 2.37. The above values are determined based on the denominator of  $z_{Ls1}(s)$ .

To derive the inductance  $L_{d1}$  for a maximum achievable bandwidth  $\omega_{Ld1}$ , the

previously obtained  $L_{d2}$  and  $L_{s1}$  are both taken into account. With the normalized (3.6) by the DC impedance  $R_{d1}/R_{d2}$  and (3.10) ~ (3.11), the derived result is:

$$L_{d1} = m_{d1} \cdot R_{d1}^2 \cdot C_d \quad (3.12)$$

where  $m_{d1}$  is 0.80, and the resulted  $\omega_{Ld1}$  equals 3.31 with a gain variation of 2.0 dB, as shown in Fig. 3.4 curve *h*. The first gain peaking at around  $\omega_0$  is due to the complex poles with a  $\zeta_{Ld1,p1}$  of 0.63 and the in-band zero  $\omega_{z1}$  of 1.33, while the second peaking at around  $3\omega_0$  results from the complex poles with a  $\zeta_{Ld1,p4}$  of 0.14 and the in-band zero  $\omega_{z2}$  of 2.50. The zero  $\omega_{z2}$  of 2.50 is calculated from  $R_{d1}/L_{d1}$ .

### 3.4.3 Design Trade-Offs in PIP Configuration

The above analysis illustrates the impact of each PIP inductor on the BWER and gain variation under the condition  $R_{d1} = R_{d2}$  and  $C_g = 3C_d$ . It is also of interest to investigate the circuit performance if using different values of  $m_{d2}$ ,  $m_{s1}$ ,  $m_{d1}$ ,  $C_g/C_d$ , and  $R_{d1}/R_{d2}$ , which provides guidelines toward the optimal design and a deeper understanding of the PIP configuration.

Fig. 3.5 shows the impact of each PIP inductor on the frequency response under  $R_{d1} = R_{d2}$  and  $C_g = 3C_d$ . Under a fixed  $m_{s1}$  of 0.86 and  $m_{d1}$  of 0.80, the BWER is not a strong function of  $m_{d2}$  in the range of 0.2 ~ 2.0, as shown in Fig. 3.5(a). The highest BWER of 3.33 can be obtained at  $m_{d2} = 0.8$  with a gain variation of 2.2 dB. In Fig. 3.5(b), with an  $m_{s1}$  of 0.6, the BWER and the gain variation both reach the highest values of 3.85 and 5.0 dB, respectively. Although the bandwidth can be greatly improved, the signal distortion may be serious because of the large gain variation. In the range of 0.8 ~ 1.2, the gain variation is kept below 2.5 dB with a BWER larger than 2.84, which is more suitable for a practical design. The dependence of the BWER and gain variation on  $m_{d1}$  is illustrated in Fig. 3.5(c). For a lower gain variation while

maintaining a high BWER, a better choice of  $m_{d1}$  should be around 0.8. Considering the trade-offs between a large BWER and a small gain variation, the previously obtained values of  $m_{d2}=1.50$ ,  $m_{s1}=0.86$ , and  $m_{d1}=0.80$  are very close to the optimal result.

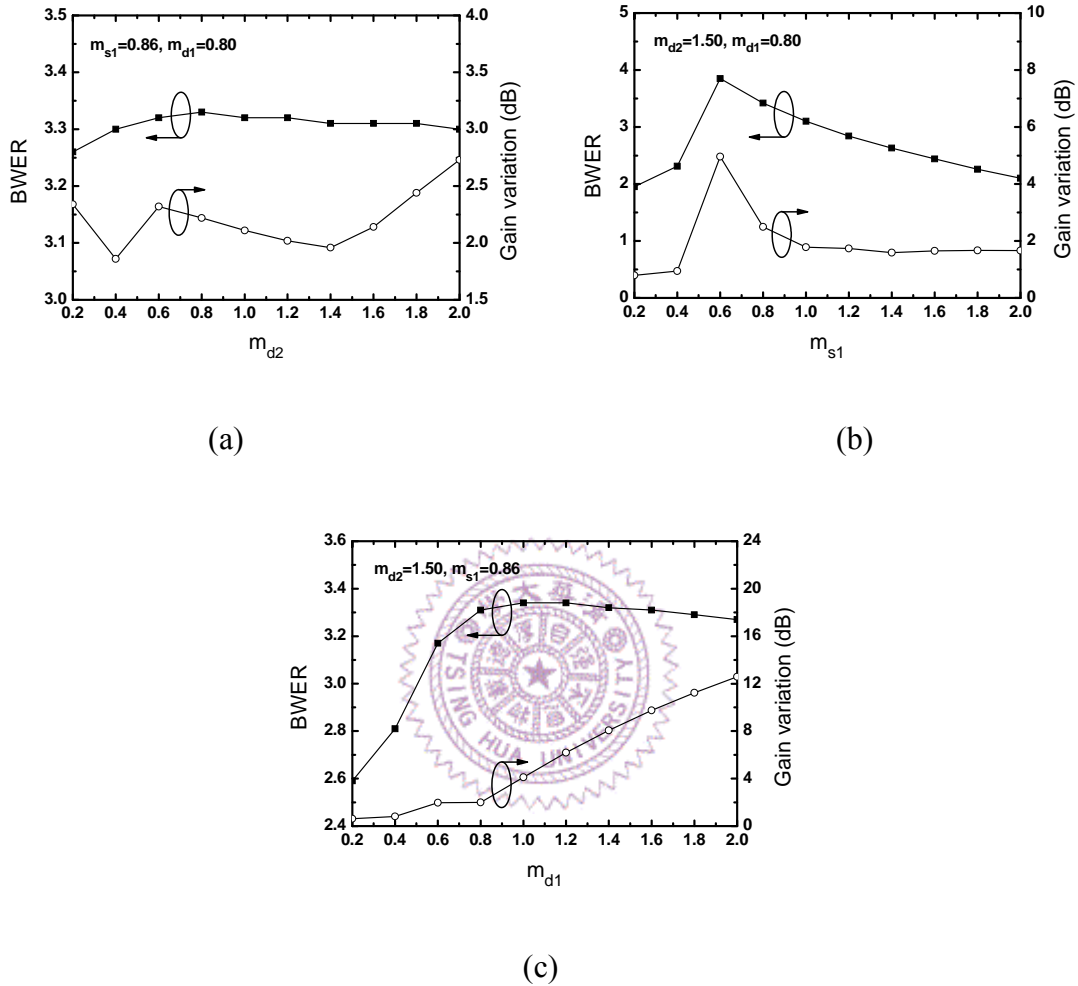


Fig. 3.5. The BWER and gain variation with different PIP inductors (a)  $m_{d2}$ , (b)  $m_{s1}$ , and (c)  $m_{d1}$ .

Fig. 3.6 plots the BWER and gain variation as a function of  $C_g/C_d$  and  $R_{d1}/R_{d2}$ . In more general cases,  $C_g/C_d$  could vary from 1 to 10 for different circuit topologies or extra source/load capacitances [31]. Within the range of 2.5 to 3.5 of  $C_g/C_d$ , high BWER values in a range of 3.15 ~ 3.46 can be achieved in a gain variation between 2.0 dB and 3.0 dB, as shown in Fig. 3.6(a). On the other hand, the BWER reduced monotonically as  $R_{d1}/R_{d2}$  increases as shown in Fig. 3.6(b). For a small  $R_{d1}/R_{d2}$  of 0.2, the BWER can be

as high as 3.46 but with a gain variation up to 4.94 dB. The gain variation can be reduced to 1.68 dB with a smaller BWER of 3.26 by choosing a  $R_{d1}/R_{d2}$  of 1.4. The selected  $R_{d1}/R_{d2}$  of 1 in the final design is simple and around the optimal value for both BWER and gain flatness.

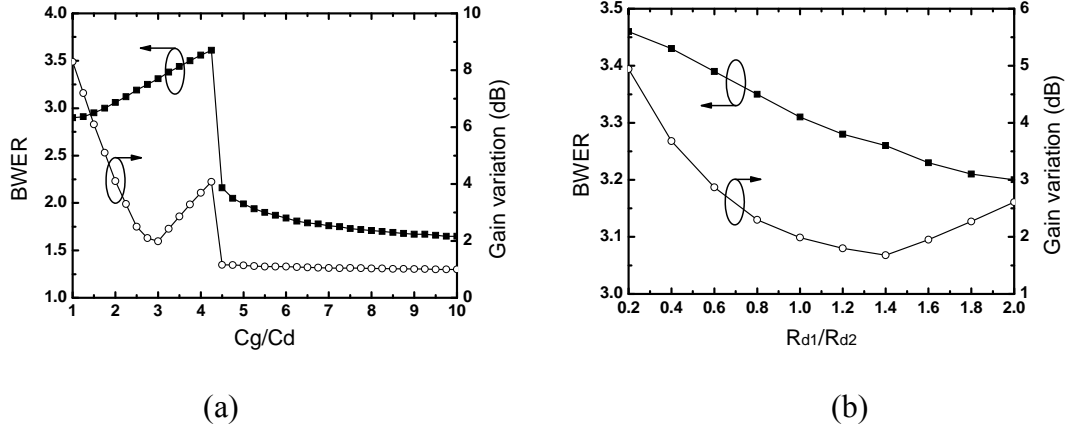


Fig. 3.6. The BWER and gain variation for different values of (a)  $C_g/C_d$  and (b)  $R_{d1}/R_{d2}$ .

### 3.5 Summary

An effective wideband technique, PIP, was proposed, and the design concept and methodology were also presented in detail. With three inductors, a large BWER of 3.31 can be obtained based on considering the parasitic capacitance ratio in a practical transistor. This promising technique will be employed to design a 40-Gb/s TIA using 0.18- $\mu\text{m}$  CMOS technology, and the details are shown in Chapter V.

# Chapter IV: Design of a 24-GHz Balanced Amplifier

The proposed PPR technique with three external inductors is employed here to design a 24-GHz balanced amplifier. The design details and results will be shown as follows.

## 4.1 Circuit Topology

To achieve a high-gain performance, eight cascaded CS stages are adopted, as shown in Fig. 4.1. The PPR technique is incorporated into each stage to boost the amplifier gain up to  $A_0^8$ . In this cascade configuration,  $L_{ds}$  and  $L_{gs}$  from the next stage (see Fig. 2.2) can be combined to be one inductor  $L_{DD}$ , as shown in the figure. To simplify the circuit design and layout complexities, each CS stage is designed to be identical. Note that the required PPR inductor  $L_{gs}$  at the gate terminal of  $M_1$  is removed, while one additional  $L_{gs}$  is inserted at the drain terminal of  $M_8$ . In this manner, the overall gain is comparable, and the layout of each CS stage is exactly the same. By connecting  $L_{DD}$  to the power supply voltage  $V_{DD}$ , each transistor is biased at  $V_{GS} = V_{DS} = V_{DD}$ . For the operation frequency  $f_o$  designed at 24 GHz, the component values are listed as follows:  $L_{DD} = 1.08$  nH,  $L_{GD} = 0.54$  nH,  $C_M = 52$  fF, and the gate width  $W_g = 64$   $\mu\text{m}$ .

The capacitor  $C_M$  is implemented by a metal-insulator-metal (MIM) capacitor with a chip area of  $6 \mu\text{m} \times 6 \mu\text{m}$ . By using the EM simulator [39],  $L_{GD}$  was designed with a top metal width ( $W$ ) of  $1.5 \mu\text{m}$ , metal spacing ( $S$ ) of  $1.5 \mu\text{m}$ , number of turns ( $N$ ) of 4.75, and inner radius ( $IR$ ) of  $5 \mu\text{m}$ , as shown in Fig. 4.2(a). The inductor shown in Fig. 4.2(b) features a  $W = 1.5 \mu\text{m}$ ,  $S = 1.5 \mu\text{m}$ ,  $N = 4.5$ , and  $IR = 5 \mu\text{m}$ , and two identical inductor are connected in series to form  $L_{DD}$ . By designing  $L_{DD}$  in this manner, the interconnects

between two stages can be shortened. The signal loss of the line can be reduced, and then the gain of the amplifier can be increased.

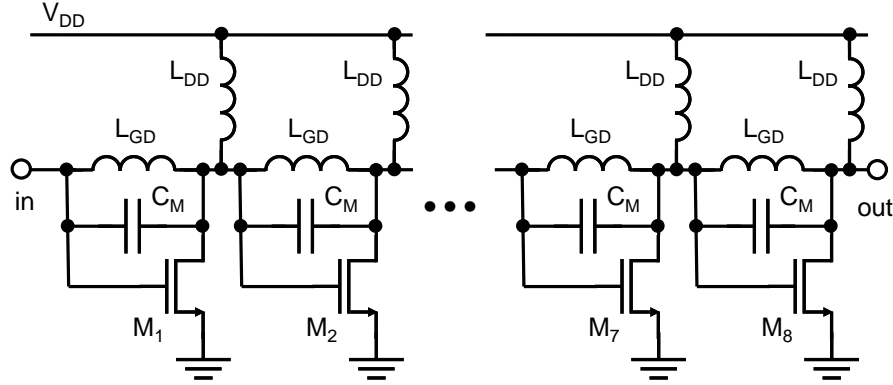


Fig. 4.1. Circuit topology of the single amplifier of each branch in the balanced amplifier (BA) configuration.

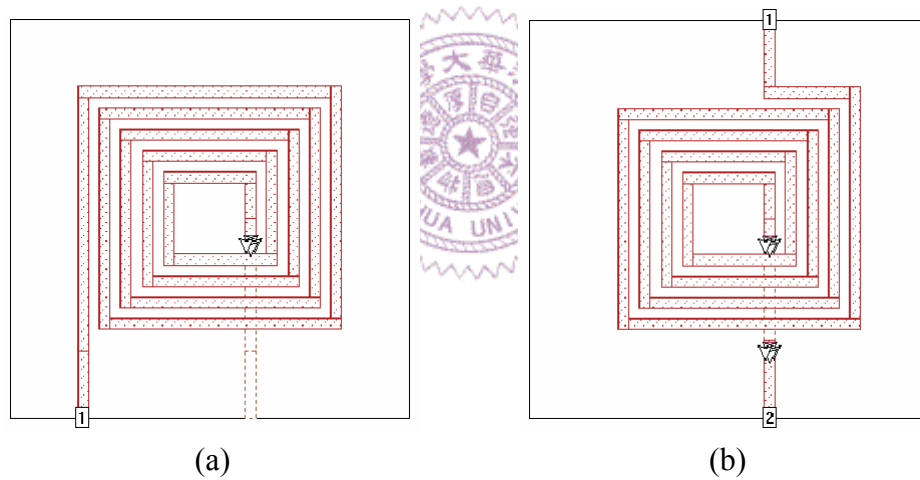


Fig. 4.2. Top-view of the on-chip spiral inductors for (a)  $L_{GD}$  and (b)  $L_{DD}/2$ .

At the resonant frequency, the input and output impedances of the amplifier can be very large due to the PPR design. Therefore, the matching network designed by  $LC$  or transmission line becomes difficult for such a high transformation ratio. In this design, the BA configuration is adopted [40]-[41], which can not only match the input and output impedances to  $50 \Omega$  but also improve the circuit stability.

A standard BA is composed of two 90-degree couplers and two identical amplifiers

(Amp1 and Amp2), as illustrated in Fig. 4.3, where the input signal is divided into two parts by the input coupler with an equal power splitting but a 90-degree phase difference. Both signals are amplified separately in each path and then combined by the output coupler with a reversed 90-degree phase shift to obtain the overall output. In principle, the gain of a BA is the same as a single amplifier. However, the stability and input/output impedance matching can be improved by the balanced design even if the single amplifier of each branch is highly mismatched and with a very high gain. Therefore, the single amplifier of each branch can be intentionally mismatched to achieve a better circuit performance. In addition, the 90-degree couplers ensure excellent isolation from the previous and/or the following stages for easy system integration. As shown in Fig. 4.3, the input power from port *in* is divided to be half with a 90-degree phase difference and delivered to ports *out1* and *out2*. Part of the signal can be reflected back due to impedance mismatch. After passing through the 90-degree coupler again, the reflected signals from both paths appearing at port *in* have a 180-degree phase difference, which can cancel each other resulting in an unconditionally matched condition at the input. On the other hand, the reflected signals with a 0-degree phase difference are superimposed at port *isolated* and terminated by a 50-Ω resistor  $R_M$ . Similarly, the output port also has a minimum reflection to guarantee the matching and stability. Compared with a single amplifier, the BA configuration needs two couplers and two amplifiers, resulting in larger power consumption and chip area. However, the output 1-dB gain compression point  $P_{1dB,out}$  is 3-dB higher than that obtained from a single amplifier. In addition, even with one of the amplifiers fails, the circuit can still operate with a reduced gain by 6 dB. Note that the resistor  $R_M$  was realized by silicided P+ poly with a length of 13 μm and a width of 2 μm. The capacitor  $C_C$  was realized by four MIM capacitors connected in parallel, and each of them with a chip area of 10 μm × 10 μm.



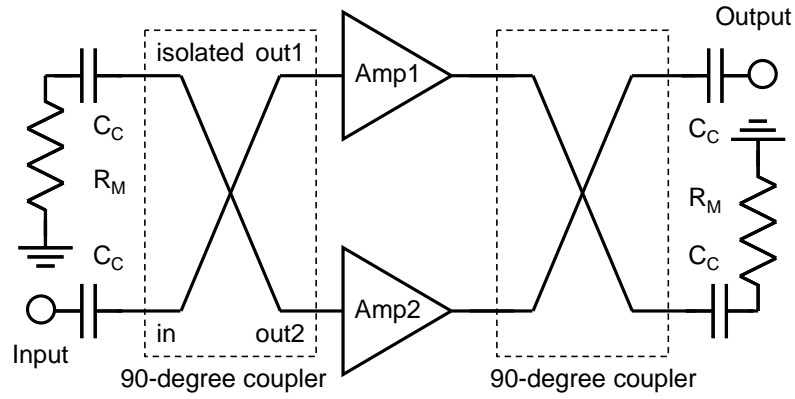


Fig. 4.3. Circuit topology of a BA.

## 4.2 Lumped-Element Coupler

The 90-degree couplers used for BA applications are usually realized by transmission lines, such as the branch-line coupler, as depicted in Fig. 4.4(a). The quarter-wavelength  $\lambda/4$  transmission lines provide a 90-degree phase delay from port 1 to port 2, and a 180-degree delay from port 1 to port 3. The characteristic impedances of the series  $Z_r$  and the shunt  $Z_p$  transmission lines can determine the delivered power ratio of the two output ports. For an equal power splitting,  $Z_r$  and  $Z_p$  should be designed as  $Z_0/\sqrt{2}$  and  $Z_0$ , respectively, where  $Z_0$  is the characteristic impedance of the system, and is typically  $50 \Omega$ . For a design at 24 GHz, the calculated physical length of a quarter-wave microstrip line is about  $1560 \mu\text{m}$  in the CMOS technology used here, which makes the balanced design with two couplers consuming a large chip area.

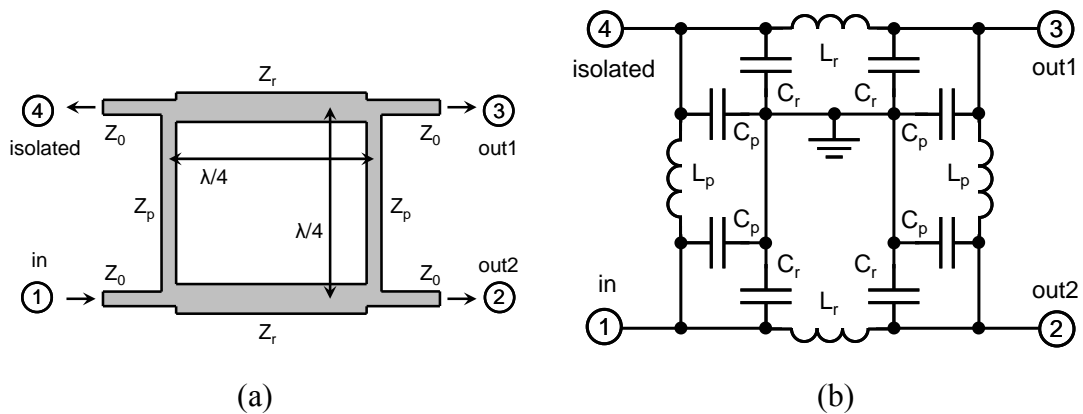


Fig. 4.4. The 90-degree couplers in (a) branch-line and (b) lumped-element topologies.

In this work, the lumped-element coupler constructed from spiral inductors and MIM capacitors as shown in Fig. 4.4(b) is adopted [42]-[43]. Compared to the transmission-line coupler, this design is more area-efficient but has a smaller bandwidth. With the same function of the branch-line coupler, each  $\lambda/4$  transmission line section can be replaced by a  $LC \pi$ -network including one inductor  $L$  and two capacitors  $C$  in the miniaturized lumped-element coupler. Using ABCD-parameters, the required  $L$  and  $C$  can be determined by the following equations for both series and shunt lines, where the matrix at the left-side is for a lossless  $\lambda/4$  transmission line, and the matrix at the right-side is for the equivalent  $LC \pi$ -network. For the series line:

$$\begin{bmatrix} \cos \theta & jZ_r \sin \theta \\ j\frac{1}{Z_r} \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 1 - \omega_o^2 L_r C_r & j\omega_o L_r \\ j\omega_o C_r (2 - \omega_o^2 L_r C_r) & 1 - \omega_o^2 L_r C_r \end{bmatrix} \quad (4.1)$$

where  $\theta$  is 90-degree, and for the shunt branch line, a similar equation can be constructed as shown below:

$$\begin{bmatrix} \cos \theta & jZ_p \sin \theta \\ j\frac{1}{Z_p} \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 1 - \omega_o^2 L_p C_p & j\omega_o L_p \\ j\omega_o C_p (2 - \omega_o^2 L_p C_p) & 1 - \omega_o^2 L_p C_p \end{bmatrix} \quad (4.2)$$

By solving the above two equations, the values of the lumped elements can be obtained as follows:

$$L_r = Z_r / \omega_o \quad (4.3)$$

$$L_p = Z_p / \omega_o \quad (4.4)$$

$$C_r + C_p = \frac{1}{\omega_o} \left( \frac{1}{Z_r} + \frac{1}{Z_p} \right) \quad (4.5)$$

Note that  $C_r$  and  $C_p$  can be combined as one capacitor in circuit implementation since

these two capacitors are connected in parallel.

By considering the parasitic effects of both the  $L$  and  $C$ , the finally optimized component values of the 24-GHz lump-element coupler are listed as follows:  $L_r = 0.23$  nH,  $L_p = 0.33$  nH, and  $C_r + C_p = 110$  fF, where  $C_r$  and  $C_p$  are implemented by a MIM capacitor with a chip area of  $9.5 \mu\text{m} \times 9.5 \mu\text{m}$ . The inductor  $L_r$  features a  $W = 2 \mu\text{m}$ ,  $S = 2 \mu\text{m}$ ,  $N = 1.5$ , and  $IR = 10 \mu\text{m}$ , as shown in Fig. 4.5(a), and  $L_p$  features a  $W = 2 \mu\text{m}$ ,  $S = 2 \mu\text{m}$ ,  $N = 1.5$ , and  $IR = 14 \mu\text{m}$ , as shown in Fig. 4.5(b). The total chip area is  $\sim 200 \mu\text{m} \times 200 \mu\text{m}$ , which occupies an area of only  $\sim 2\%$  compared to that of the conventional branch-line coupler using the same technology.

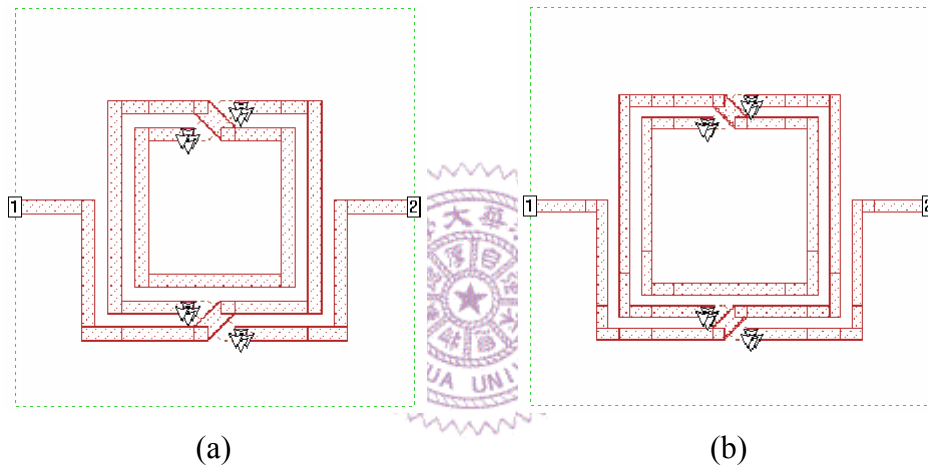


Fig. 4.5. Top-view of the on-chip spiral inductors for (a)  $L_r$  and (b)  $L_p$ .

The simulated S-parameters based on the actual layout of the lumped-element coupler are shown in Fig. 4.6. At 24 GHz, the insertion losses from port 1 to port 2 and port 3 are 6.4 dB and 6.2 dB, respectively. The loss is higher than the desired value of 3 dB due to the resistive loss introduced from the spiral inductors. The reflection coefficients of port *in* and the isolation from port *in* to port *isolated* are both below -15 dB. The phase difference between the two output ports is 89.6 degree.

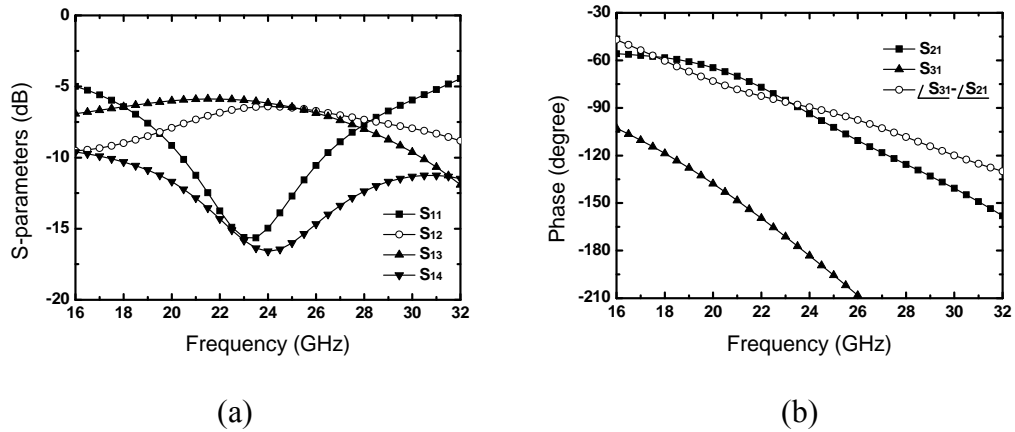


Fig. 4.6. Simulated S-parameters of the 24-GHz lumped-element coupler for (a) magnitude and (b) phase.

### 4.3 Design of Interconnects

Special care had been taken for the layout of the circuit. For high-frequency circuits, the commonly used interconnect structures are microstrip (MS) line and coplanar waveguide (CPW), as shown in Fig. 4.7(a) and (b) respectively. However, these two structures can suffer either from severe signal crosstalk or significant signal loss from the lossy silicon substrate [44]. As shown in Fig. 4.7(c), the grounded-CPW (GCPW) configuration can be employed to prevent the above problems [45]-[46]. The sidewall and bottom ground planes realized by various metal layers are utilized for a better shielding of the signal paths.

To further improve the signal loss, a new transmission line structure, semi-coaxial (SC) line, is proposed, which demonstrates a superior low-loss performance [47]. By using a semi-rounded ground plane, as shown in Fig. 4.7(d), the SC lines also provide a perfect shielding of the signal lines from the crosstalk and the lossy substrate to achieve a low-loss characteristic over a wide frequency range. A lower signal loss characteristic is expected since the semi-coaxial structure can support a wave propagation more close to the TEM mode. The measured attenuation constant of the SC line presented the lowest value of 0.90 dB/mm at 50 GHz compared to 5.04 dB/mm of MS line [48], 1.22

dB/mm of CPW [48], and  $\sim 1.00$  dB/mm of GCPW [45].

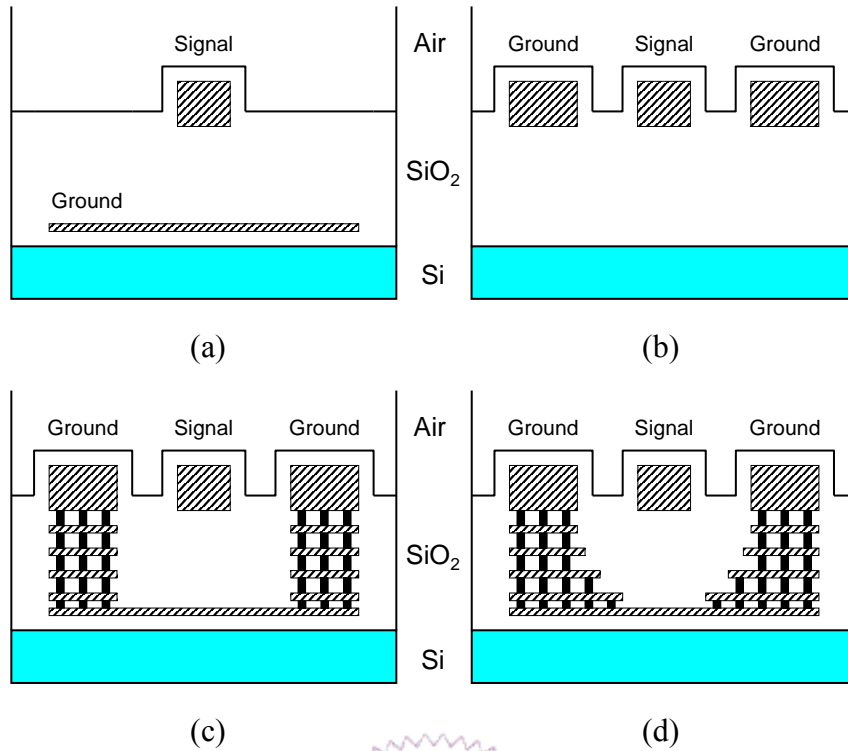


Fig. 4.7. RF interconnect structures for (a) MS line, (b) CPW, (c) GCPW, and (d) SC line in a standard 1P6M CMOS process.

#### 4.4 Stability Issues

For such a high gain amplifier, stability is a critical design consideration. To achieve unconditional stability, the stability factor  $K$  and the stability measure  $B_1$  should be larger than 1 and 0, respectively [49]. The simulation results indicate that each inter-stage and the whole circuit are unconditionally stable over a wide frequency range. The amplifier also shows unconditional stability under the  $V_{DD}$  varying in a range of 0.6 V to 1.8 V, as shown in Fig. 4.8. Note that the inter-stage stability is verified by the S-probe in the simulation tool ADS [50]. For an unconditional inter-stage stability, StabIndex1 and StabIndex2 should both be smaller than 1, as shown in Fig. 4.9. The simulation results indicate that each inter-stage is unconditionally stable over a wide frequency range, as shown in Fig. 4.10. Note that eight CS stages were employed for a high-gain amplification.

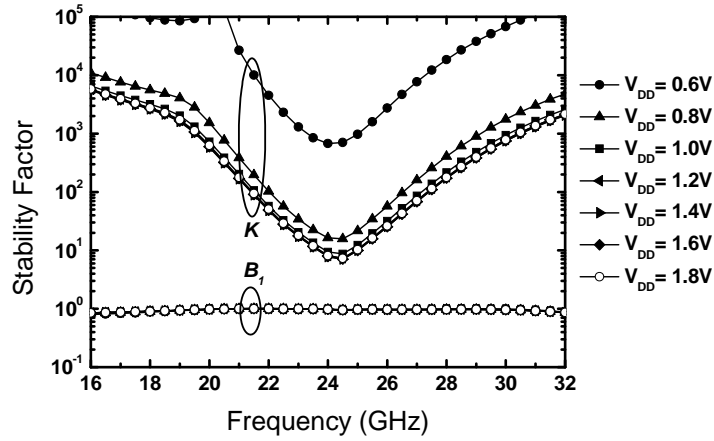


Fig. 4.8. Simulated stability factor and stability measure of the whole BA with different supply voltages.

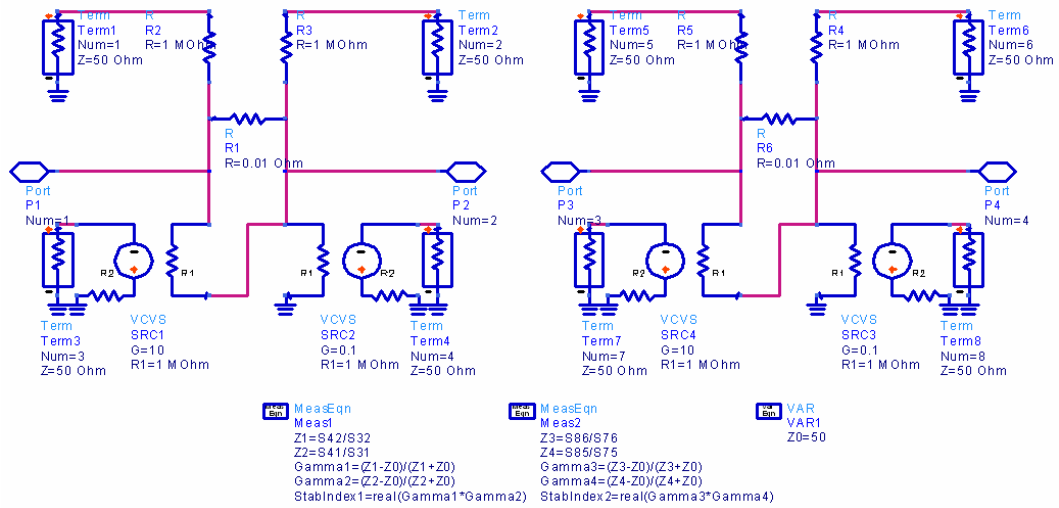


Fig. 4.9. Circuit schematic of S-probe for measuring the inter-stage stability.

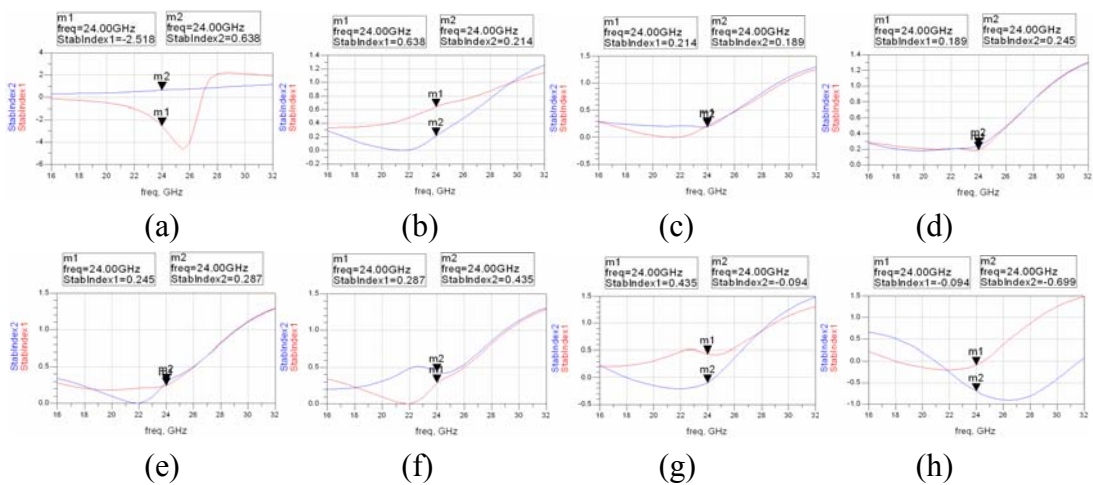


Fig. 4.10. Frequency responses of the inter-stage stability for (a) 1<sup>st</sup>, (b) 2<sup>nd</sup>, (c) 3<sup>rd</sup>, (d) 4<sup>th</sup>, (e) 5<sup>th</sup>, (f) 6<sup>th</sup>, (g) 7<sup>th</sup>, and (h) 8<sup>th</sup> stage of the amplifier shown in Fig. 4.1.

## 4.5 Measured Frequency Responses

The fully-integrated BA was fabricated in the 0.18- $\mu\text{m}$  CMOS technology with a chip area of  $0.97 \times 0.63 \text{ mm}^2$  including the probing pads (core area:  $0.78 \times 0.43 \text{ mm}^2$ ), as shown in Fig. 4.11. The chip was measured on-wafer by using coplanar ground-signal-ground (GSG) probes (Picoprobe 67A-GSG-125-C-W). Fig. 4.12 shows the measured S-parameters, where the gain  $S_{21}$  at 24 GHz is 41.6 dB, and the peak gain  $G_p$  is 45.0 dB at the frequency  $f_p$  of 23.7 GHz. The  $S_{11}$  and  $S_{22}$  at  $f_p$  are -10.8 dB and -9.1 dB, respectively, which indicate a good input/output matching. From the measured S-parameters, the amplifier is unconditionally stable over the measured frequency range from 16 GHz to 32 GHz, as shown in Fig. 4.13.

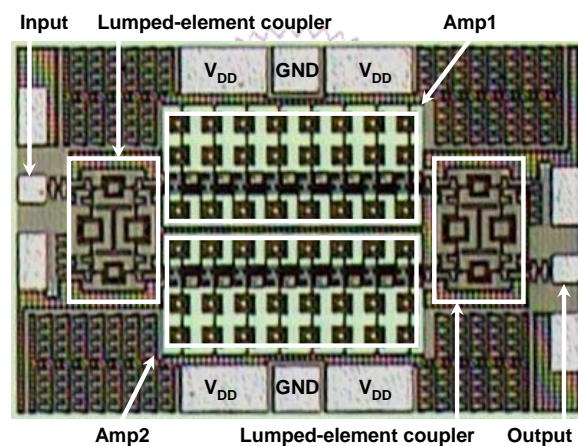


Fig. 4.11. Chip micrograph for the 24-GHz BA, and the chip size including the probing pads is  $0.97 \times 0.63 \text{ mm}^2$  (core area:  $0.78 \times 0.43 \text{ mm}^2$ ).

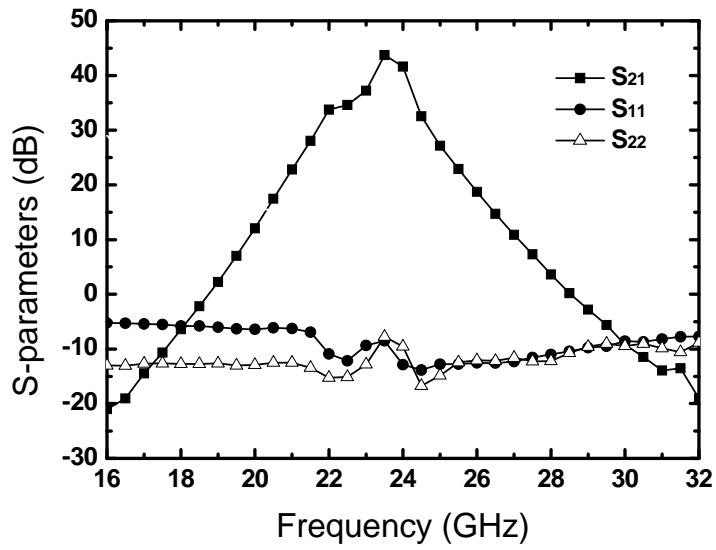


Fig. 4.12. Measured S-parameters as a function of frequency.

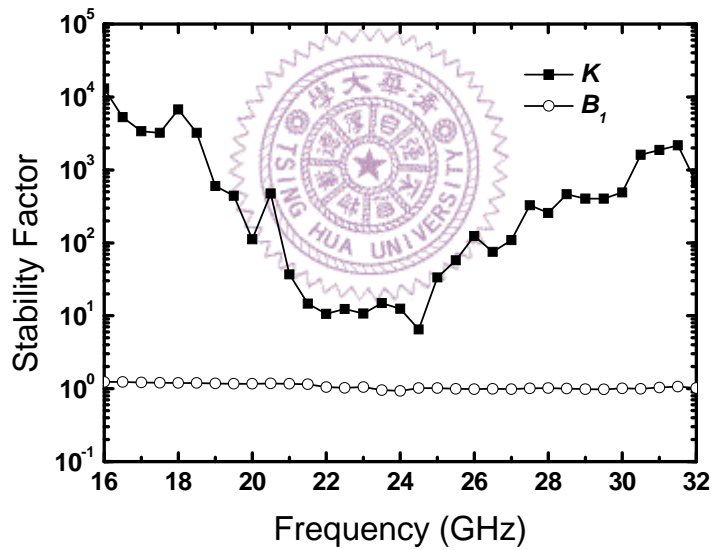


Fig. 4.13. Measured stability factors as a function of frequency.

The noise figure ( $NF$ ) of BA was measured and simulated from 16 GHz to 26.5 GHz as shown in Fig. 4.14. A good agreement between measured and simulated  $NF$  is obtained. As can be seen, the amplifier shows relatively large  $NF$  of 9.4 dB and 10.8 dB respectively for the simulated and measured values at  $f_p$ . The  $NF$  of the coupler and the single amplifier are also presented for further analysis, which are 3.3 dB and 5.8 dB (at



$f_p$ ), respectively. The 3.3 dB can be attributed to the insertion loss of the lumped-element coupler ( $\sim 6.3$  dB), which is 3.3 dB higher than that of an ideal coupler. A possible solution for reducing  $NF$  of the proposed BA is to optimize the lossy lumped-element coupler. If an ideal insertion loss of 3 dB can be achieved, the measured  $NF$  can be reduced to  $\sim 7.5$  dB. The output power level as a function of the input power was measured at  $f_p$ , which indicated a  $P_{1dB, out}$  of -2.3 dBm, as shown in Fig. 4.15. Under a supply voltage of 1 V, the power consumption ( $P_{DC}$ ) is 123 mW. By employing the proposed PPR technique, a high peak gain-frequency product per DC power ( $G_p f_p / P_{DC}$ ) figure-of-merit of 34.3 GHz/mW and a high  $G_p f_p / (NF \times P_{DC})$  of 2.9 GHz/mW can be achieved.

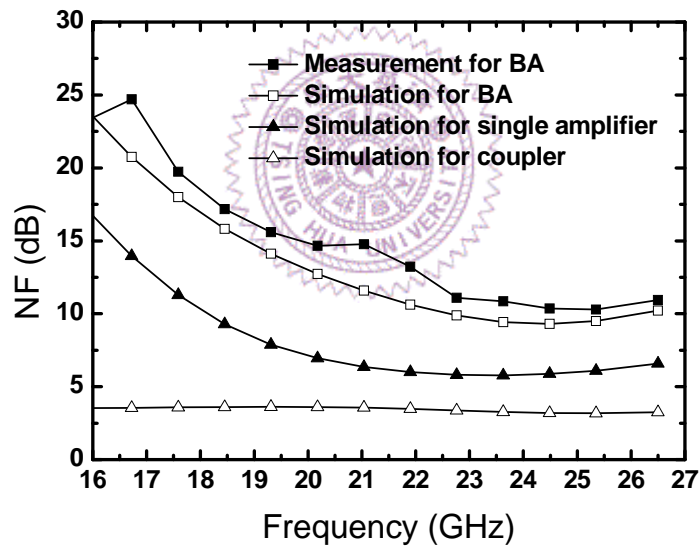


Fig. 4.14. Measured and simulated  $NF$  as a function of frequency.

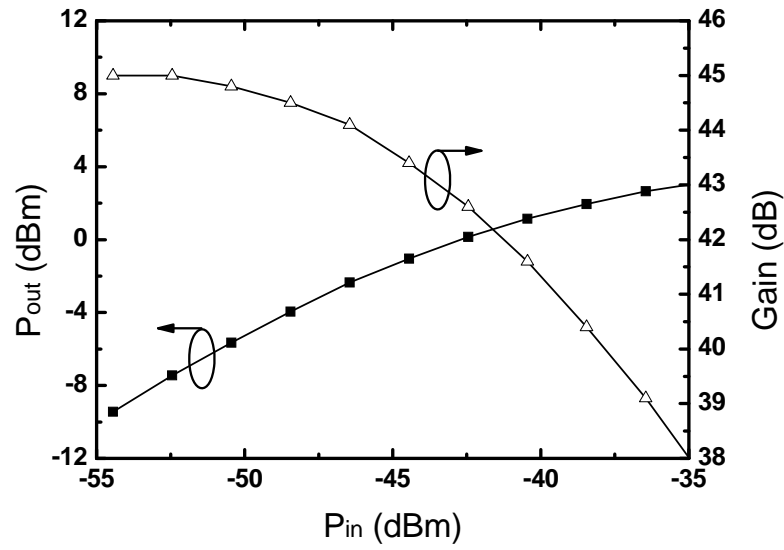


Fig. 4.15. Measured output power and gain versus input power at the peak gain frequency ( $f_p$ ).

The circuit performances of the proposed BA are summarized in Table 4.1 together with other works at similar operation frequencies [51]-[53]. Although the balanced-type design requires two amplifiers and couplers, the core area in this design is still very small ( $\sim 0.34 \text{ mm}^2$ ) owing to the miniaturized lumped-element coupler. The proposed BA presented the highest gain and  $G_p f_p / P_{DC}$  among the published results with similar technologies and operation frequencies.

Ref.	This work	[51]	[52]	[53]
$G_p$ (dB)	45.0	15.0	10.0	8.9
$f_p$ (GHz)	23.7	21.8	24.0	25.7
$S_{11}$ (dB)	-10.8	-21.0	-14.0	-14.0
$S_{22}$ (dB)	-9.1	—	—	-12.0
NF (dB)	10.8	6.0	6.0*	6.9
$P_{1dB,out}$ (dBm)	-2.3	-9.0	—	-2.3
$V_{DD}$ (V)	1	1.5	—	1.8
$P_{DC}$ (mW)	123	24	47	54
Chip area (mm <sup>2</sup> )	0.97×0.63	—	—	1.05×0.7
Core area (mm <sup>2</sup> )	0.78×0.43	0.2×0.25	—	—
$G_p f_p / P_{DC}$ (GHz/mW)	34.3	5.1	1.6	1.3
$G_p f_p / (NF \times P_{DC})$ (GHz/mW)	2.9	1.3	0.4	0.3
Process	0.18- $\mu$ m CMOS	0.18- $\mu$ m CMOS	0.18- $\mu$ m CMOS	0.18- $\mu$ m CMOS

\* Extrapolated from measured results up to 20 GHz.

Table 4.1. BA Performance summary and comparison with other works.

#### 4.6 Summary

A fully-integrated CMOS BA was presented, and demonstrated a gain of 45.0 dB at around 24 GHz with an unconditional stability. The input and output ports were both matched well. Under a supply voltage of 1 V,  $NF$  and  $P_{1dB, out}$  were 10.8 dB and -2.3 dBm, respectively. With the proposed PPR design technique and the employment of the lumped-element couplers, the proposed BA showed the highest  $G_p f_p / P_{DC}$  figure-of-merit of 34.3 GHz/mW among the published results.

# Chapter V: Design of a 40-Gb/s Transimpedance Amplifier

Being the first block of a receiver chain, TIA plays an important role to amplify the weak high-speed signal from the photo detector. With a target speed of 40-Gb/s, the proposed PIP technique is utilized to boost the performance of the transistor with a gate length of 0.18  $\mu\text{m}$ . The design details and results are addressed as follows.

## 5.1 Circuit Topology

To demonstrate the proposed PIP technique, a TIA targeting at 40-Gb/s is realized in 0.18- $\mu\text{m}$  CMOS technology. The 40-Gb/s TIA composes of four cascaded CS stages, as shown in Fig. 5.1. For a cascaded amplifier with identical 1<sup>st</sup>-order gain stages, the optimal stage number  $n_{opt}$  can be estimated by a simple equation of  $2 \times \ln(A_{tot})$  to achieve a maximized circuit bandwidth, where  $A_{tot}$  is the total voltage gain [54]. Note that  $A_{tot}$  is equivalent to the overall  $S_{21}$  under the matched input and output impedances of 50  $\Omega$ . For the proposed TIA with an  $A_{tot}$  of 16.7 dB, the finally designed stage number is 4. Identical resistance for the drain bias resistors  $R_D$  of each stage is employed, and the input and output impedances are designed as 50  $\Omega$  through the resistors  $R_{M1} \sim R_{M4}$ . Note that the 50- $\Omega$  input impedance is mainly for high-frequency measurement consideration, which may not be the optimal design if considering the electrical characteristics of the photodiode.

For a high-gain characteristic, a large  $R_D$  is preferred. However, the required peaking inductances for PIP topology, as derived in section 3.4.2, are proportional to  $R_D^2$ . It can be seen that a trade-off exists here since a large inductor not only occupies a large chip area but also causes difficulties to maintain an inductive characteristic up to

the circuit bandwidth. In addition, the resistive parasitics of the inductors can degrade the circuit performance. This effect is more obvious for the series-connected inductors  $L_{sI}$  in PIP configuration. In practical design, these inductors are designed to be smaller than the calculated values to reduce the resistive loss. The optimized  $R_D$  obtained for reasonable inductances while still providing high gain is 200  $\Omega$ . The adopted device width of  $M_1 \sim M_3$  is 48  $\mu\text{m}$  with a  $f_T$  of  $\sim 60$  GHz and a  $f_{\text{max}}$  of  $\sim 90$  GHz (estimated from the foundry provided transistor model), while a larger width of 64  $\mu\text{m}$  is employed for  $M_4$  to increase the gain and the output signal swing under a 50- $\Omega$  load. The inductances ( $L_{P1} \sim L_{P9}$ ) are designed based on the derived equations (3.10)  $\sim$  (3.12), while some optimizations are essential due to the frequency dependence of  $C_g/C_d$  and the parasitic effects of the on-chip inductors. The finally designed values are  $L_{P1} = L_{P2} = 0.85$  nH,  $L_{P3} = 0.48$  nH,  $L_{P4} = L_{P5} = L_{P7} = L_{P8} = 1.6$  nH,  $L_{P6} = 0.42$  nH, and  $L_{P9} = 0.2$  nH. Compared with the theoretical value, a smaller BWER of 2.88 (simulated) for the single-stage amplifier using PIP (one of the three identical stages in the final design, see Fig. 5.1) is obtained in actual implementation.

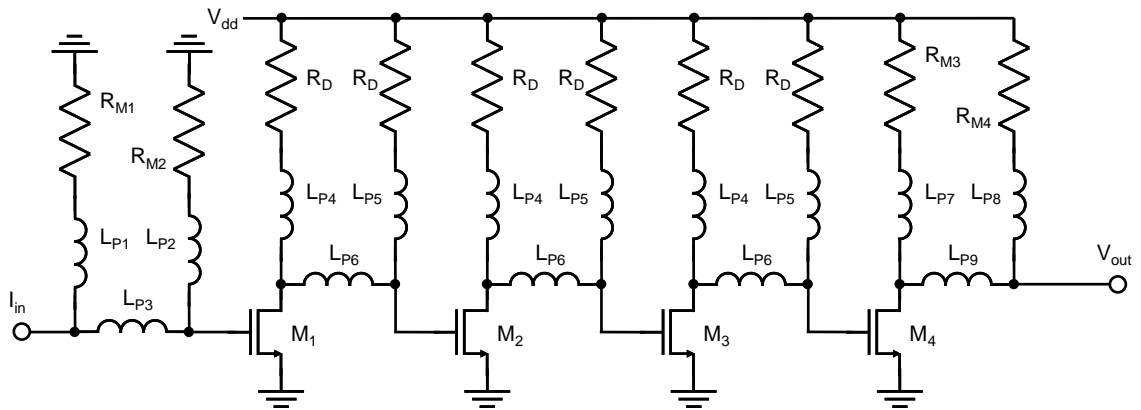


Fig. 5.1. Circuit topology of the proposed 40-Gb/s CMOS TIA with PIP.

The resistor  $R_D$  was realized by silicided P+ poly with a length of 47.2  $\mu\text{m}$  and a width of 2  $\mu\text{m}$ , and  $R_{M1} \sim R_{M4}$  with a length of 47.2  $\mu\text{m}$  and a width of 4  $\mu\text{m}$ . The

inductor  $L_{P1}$  and  $L_{P2}$  were designed with a  $W=2\ \mu\text{m}$ ,  $S=4\ \mu\text{m}$ ,  $N=4.5$ , and  $IR=8\ \mu\text{m}$ , as shown in Fig. 5.2(a). The inductor  $L_{P3}$  features a  $W=5\ \mu\text{m}$ ,  $S=5\ \mu\text{m}$ ,  $N=2.5$ , and  $IR=15\ \mu\text{m}$ , as shown in Fig. 5.2(b). The inductor  $L_{P4}$ ,  $L_{P5}$ ,  $L_{P7}$ , and  $L_{P8}$  feature a  $W=1.5\ \mu\text{m}$ ,  $S=3\ \mu\text{m}$ ,  $N=4.5$ , and  $IR=15\ \mu\text{m}$ , as shown in Fig. 5.2(c). The inductor  $L_{P6}$  features a  $W=2\ \mu\text{m}$ ,  $S=4\ \mu\text{m}$ ,  $N=3.5$ , and  $IR=8\ \mu\text{m}$ , as shown in Fig. 5.2(d). The inductor  $L_{P9}$  features a  $W=5\ \mu\text{m}$ ,  $S=5\ \mu\text{m}$ ,  $N=2.5$ , and  $IR=10\ \mu\text{m}$ , as shown in Fig. 5.2(e).

Fig. 5.3 compares the design of a TIA with and without using PIP technique. With a transimpedance gain  $Z_T$  of 51 dB $\Omega$ , the simulated bandwidth for the TIA with PIP is improved by a factor up to  $\sim 11$  (33.8 GHz/ 3.1 GHz) compared to that without PIP. It is worth to point out that a photodiode capacitance  $C_{pd}$  of 50 fF is incorporated at the TIA input monolithically by the MIM capacitor in CMOS process, which is also the main limitation for the TIA bandwidth. A value of 50 fF was determined by the following manner. For a high-speed operation, it is essential to use a photodiode with a smaller  $C_{pd}$ . From the datasheet of two commercial photodiodes operating up to 50 GHz, the parasitic capacitance can be extracted from the output reflection coefficient  $S_{22}$  [55]. With an output impedance of 50 ohm, the capacitance of the photodiode is  $\sim 42$  fF (u2t XPDV2020R,  $S_{22}=-10$  dB) and 64 fF (u2t XPDV2040R,  $S_{22}=-7$  dB). Therefore, a  $C_{pd}$  of 50 fF is a reasonable value to be used as the input loading of the TIA. By employing the PIP configuration ( $L_{P1} \sim L_{P3}$ ) at the input stage, the capacitive loading from  $C_{pd}$  can be effectively resonated to achieve a wide bandwidth.

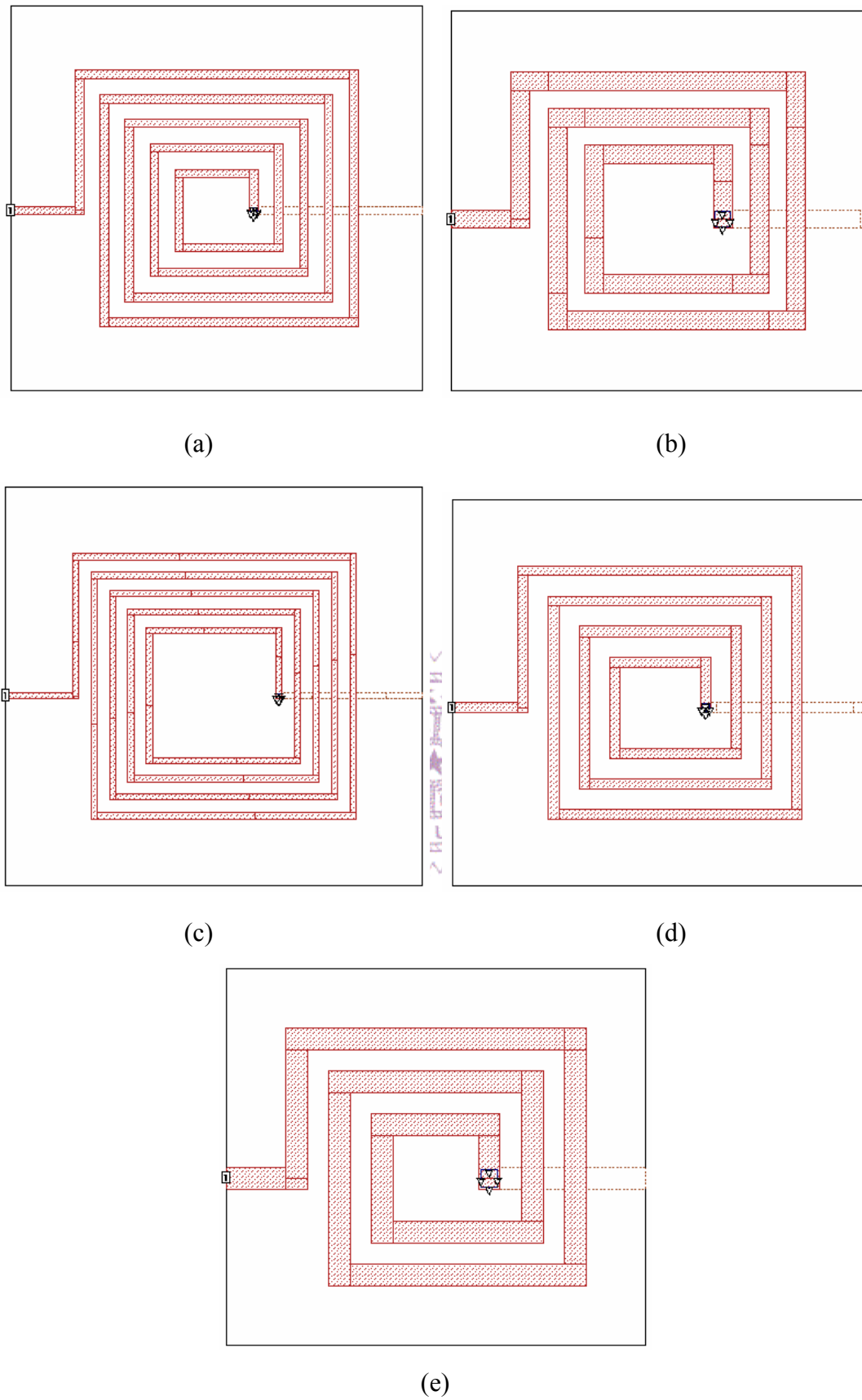


Fig. 5.2. Top views of the spiral inductors for (a)  $L_{P1}$  and  $L_{P2}$ , (b)  $L_{P3}$ , (c)  $L_{P4}$ ,  $L_{P5}$ ,  $L_{P7}$ , and  $L_{P8}$ , (d)  $L_{P6}$ , and (e)  $L_{P9}$ .

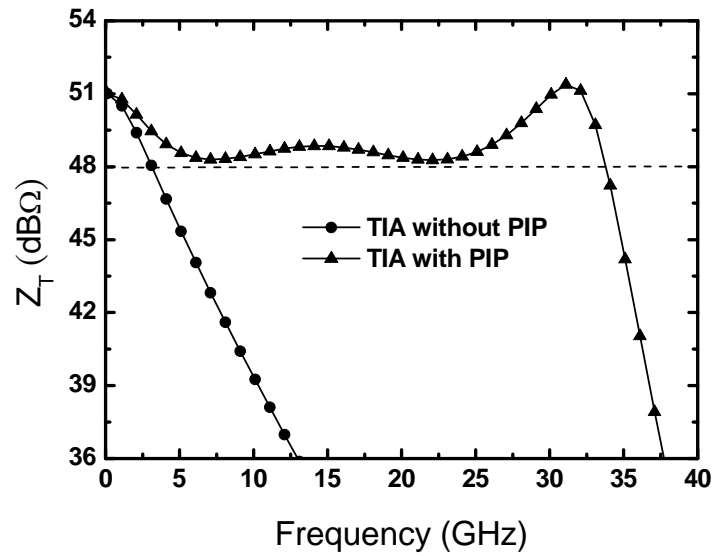


Fig. 5.3. Simulated frequency response for the TIA with and without PIP.

The impact of the corner-case transistors (slow and fast) on the frequency response of the TIA is simulated and shown in Fig. 5.4. For the slow case, the gain is reduced to 47.8 dBΩ and the bandwidth is increased to 34.1 GHz. On the other hand, the gain is increased to 52.2 dBΩ and the bandwidth is decreased to 33.7 GHz for the fast case.

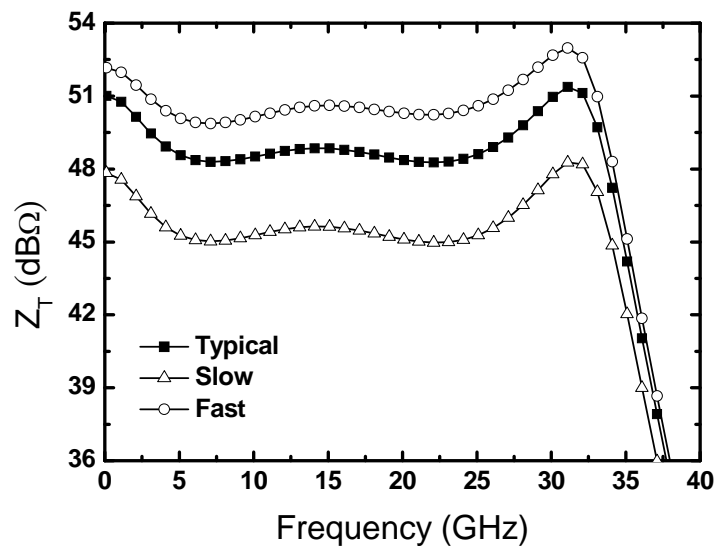


Fig. 5.4. Simulated impact of corner-case transistors on the frequency response of the proposed TIA.



In this design, GCPW configuration was employed for the interconnects. The total length of the signal paths in the designed TIA is about 500  $\mu\text{m}$ , which has an insertion loss of only 1.1 dB at 33.8 GHz estimated using the EM simulator. In addition, the lines were all designed as 50- $\Omega$  to alleviate the additional capacitive loading effect on the circuit.

## 5.2 Noise Analysis

The input-referred noise current  $i_{n,in}$  is an important issue for TIA design, which determines the sensitivity of the circuit. For the cascaded configuration, the input-referred noise is dominated by the first stage, since the impact of the noise from the later stages is reduced through the gain of the previous stages. In the following analysis, only the first transistor  $M_1$  and the input PIP network ( $L_{P1} \sim L_{P3}$  and  $R_{M1} \sim R_{M2}$ ) are considered, as shown in Fig. 5.5.

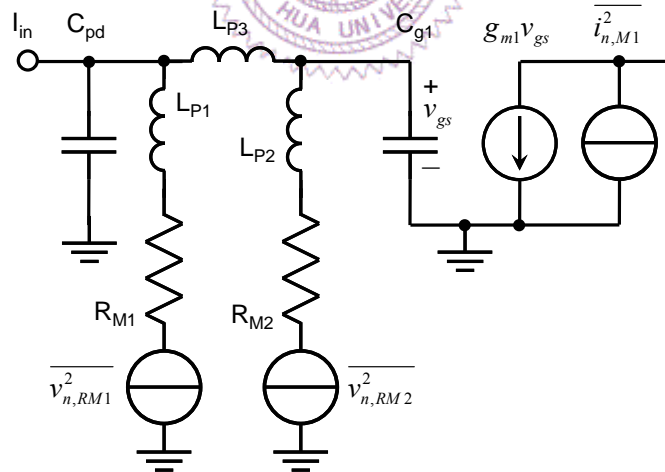


Fig. 5.5. Noise equivalent circuit model for the TIA input stage as shown in Fig. 5.1.

For 0.18- $\mu\text{m}$  CMOS technology, previous studies indicate that the drain thermal noise dominates the device noise characteristics [56]-[57]. Based on this conclusion, the mean-square noise current spectral density can be derived as:

$$\begin{aligned} \overline{i_{n,in}^2} = & 4kTR_{M1} \left| \frac{1}{Z_{RL1}} \right|^2 + 4kTR_{M2} \left| \frac{1}{Z_{RL2}} + sL_{P3} \left( \frac{1}{Z_{RL1}Z_{RL2}} + \frac{sC_{pd}}{Z_{RL2}} \right) \right|^2 \\ & + \frac{4kT\gamma}{g_{m1}} \left| \frac{1}{Z_{RL1}} + \frac{1}{Z_{RL2}} + s(C_{pd} + C_{g1}) + sL_{P3} \left( \frac{1}{Z_{RL1}Z_{RL2}} + \frac{sC_{g1}}{Z_{RL1}} + \frac{sC_{pd}}{Z_{RL2}} + s^2C_{pd}C_{g1} \right) \right|^2 \end{aligned} \quad (5.1)$$

where

$$\begin{aligned} Z_{RL1} &= R_{M1} + sL_{P1} \\ Z_{RL2} &= R_{M2} + sL_{P2} \end{aligned} \quad (5.2)$$

where  $\gamma$  is the noise factor of the drain thermal noise, and  $g_{m1}$  and  $C_{g1}$  are the transconductance and the equivalent gate capacitance of  $M_1$ , respectively. As can be seen from the equation, the capacitance related terms increase the noise current as the frequency increases, while the rest of the terms result in an opposite trend owing to the inductive reactance in the denominator. The measured results as will be shown in section 5.3 indicate that the in-band noise current decreases with increased frequency. In other words, the capacitance related terms in (5.1) are not significant in the desired bandwidth. This trend can be attributed to the increased reactance of  $L$  with frequency, which provides relatively high impedances to block the noise currents generated from  $R_{M1}$ ,  $R_{M2}$ , and  $M_1$  to flow into the input terminal. Based on the above analysis, the PIP inductors at the input stage not only improve the bandwidth but also the noise performance in the desired band.

In addition to the noise current, the input-referred noise voltage is also derived. Since the input node is shorted to ground in this case, the noise contribution from  $R_{M1}$  and the impact from  $C_{pd}$  are both neglected. The derived equation can be written as:

$$\overline{v_{n,in}^2} = 4kTR_{M2} \left| \frac{sL_{P3}}{Z_{RL2}} \right|^2 + \frac{4kT\gamma}{g_{m1}} \left| 1 + sL_{P3} \left( \frac{1}{Z_{RL2}} + sC_{g1} \right) \right|^2 \quad (5.3)$$

By combining the noise current and voltage, the derived  $NF$  can be written as:

$$NF = 1 + \frac{\left( \sqrt{i_{n,in}^2} + \sqrt{v_{n,in}^2 Y_s} \right)^2}{4kT / R_s} \quad (5.4)$$

Since the above equation is too complex to simplify, the simulated result will be shown later.

### 5.3 Measured Frequency Responses

The TIA was fabricated in 0.18- $\mu\text{m}$  CMOS technology with a chip area of  $1.17 \times 0.46 \text{ mm}^2$ , as shown in Fig. 5.6. The TIA was measured on-wafer with coplanar ground-signal-ground (GSG) probes (Picoprobe 67A-GSG-125-C-W) for S-parameters, noise figure, and eye-diagram measurements.

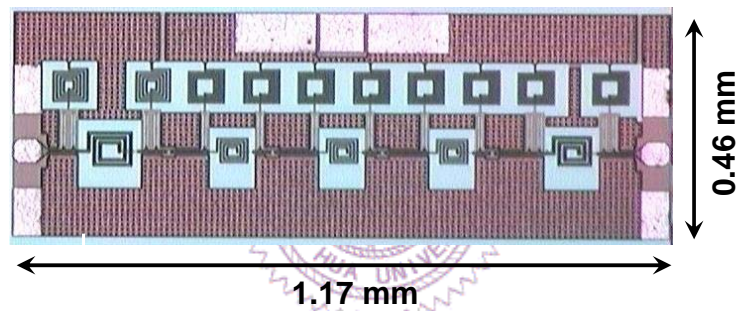


Fig. 5.6. Chip micrograph.

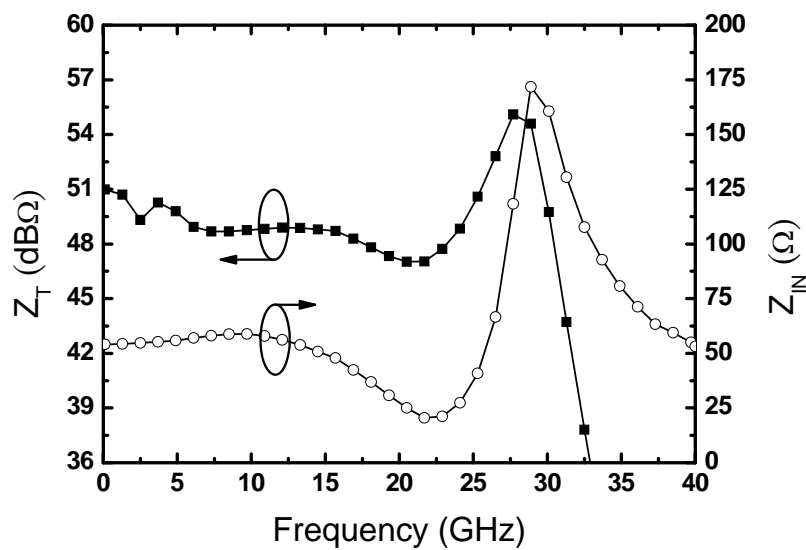


Fig. 5.7. Measured  $Z_T$  and  $Z_{IN}$ .

Using the network analyzer 8510C, the S-parameters were taken from 0.1 GHz to 40 GHz. The measured response of  $Z_T$  is shown in Fig. 5.7. The gain and the 3-dB bandwidth  $f_{3-dB}$  are 51 dB $\Omega$  and 30.5 GHz in the presence of an on-chip  $C_{pd}$  of 50 fF at the input, respectively. The magnitude of the input impedance  $Z_{IN}$  is 54  $\Omega$  at low frequencies, but increases due to the PIP inductors at around  $f_{3-dB}$ . The measured  $S_{22}$  within the  $f_{3-dB}$  is all below -10 dB, and  $S_{21}$  at low frequencies is up to 16.7 dB, as shown in Fig. 5.8.

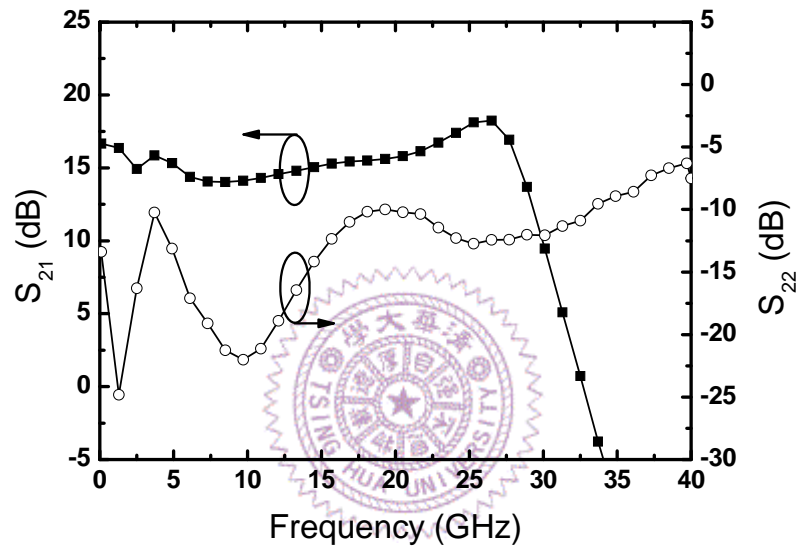


Fig. 5.8. Measured  $S_{21}$  and  $S_{22}$ .

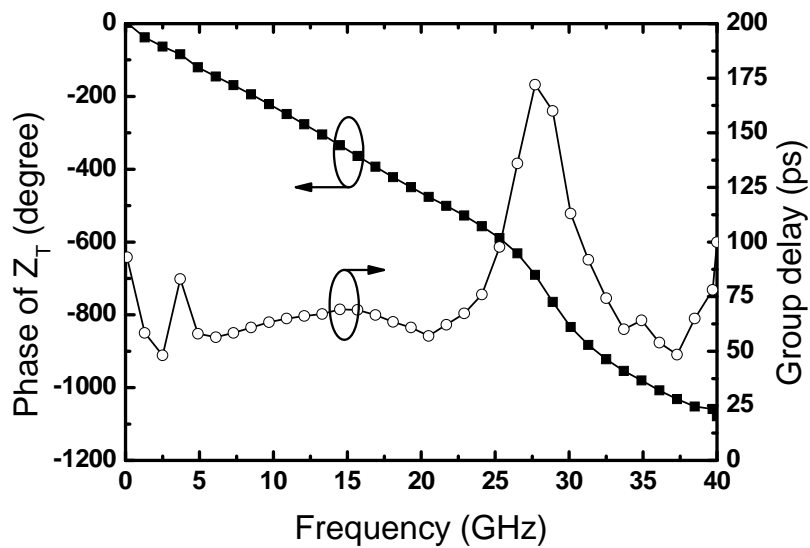


Fig. 5.9. Measured phase and group delay.

The phase of  $Z_T$  is linearly decreased with frequency and the group delay variation is below 45 ps up to 24 GHz, as illustrated in Fig. 5.9. Note that a trade-off exists between the bandwidth enhancement and the phase linearity. In this study, we mainly focus on bandwidth enhancement and thus the group delay variation increases. As will be observed from the eye diagrams of the TIA especially the one at 40-Gb/s (Fig. 5.12(d)), the signal smears and the rising and falling edges broaden due to the group delay variation with frequency, i.e. the phase velocity variation at different frequencies.

Using the noise figure analyzer N8975A, the noise figure ( $NF$ ) was measured from 3.5 GHz to 26.5 GHz, as shown in Fig. 5.10. The value decreases from 11.9 dB to 6.7 dB as the frequency increases, which is in an excellent agreement with the simulated results.

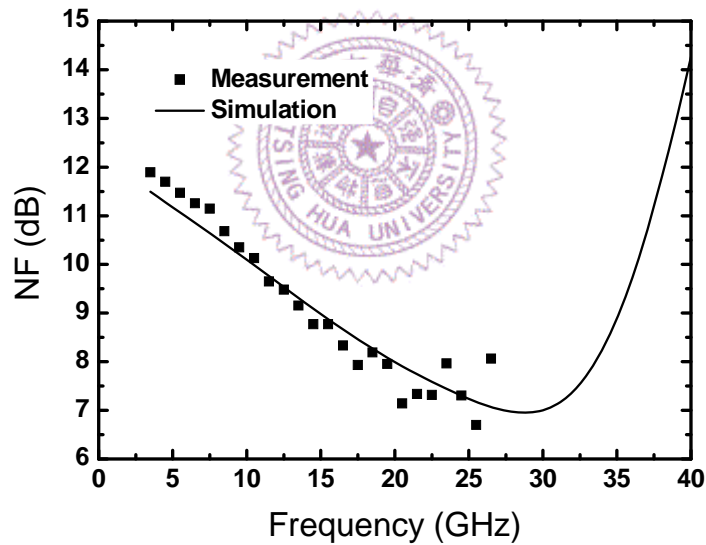


Fig. 5.10. Measured and simulated  $NF$ .

The noise characteristic of the TIA can be represented by a single noise current source referred to the input [58]:

$$\overline{i_{n,in}^2} = \frac{\overline{v_{n,outamp}^2}}{Z_T^2} \quad (5.5)$$

where  $v_{n,outamp}$  is the output noise voltage of the amplifier. Based on the definition of  $NF$ ,

the noise current can be extracted as shown in Fig. 5.11. Note that the calculation is under a 50-Ω condition, which is consistent with the measurement environment. Also, the calculation includes the effect of the input capacitor  $C_{pd}$  connected in front of the TIA. As can be seen, a decreasing noise current with frequency can be observed and a lowest value of 34.3 pA/√Hz at 25 GHz is obtained. Although not measured directly, the simulated results indicate that the capacitance related higher order terms in (5.1) become significant only at above ~ 30 GHz. To investigate the effect of  $C_{pd}$  on the noise characteristic, the simulated  $i_{n,in}$  with different  $C_{pd}$  values is presented in Fig. 5.11. As predicted by (5.1), the capacitance related terms increase the noise current as the frequency increases. When a large  $C_{pd}$  is applied, the  $C_{pd}$ -related terms become dominant and the noise current increases with frequency.

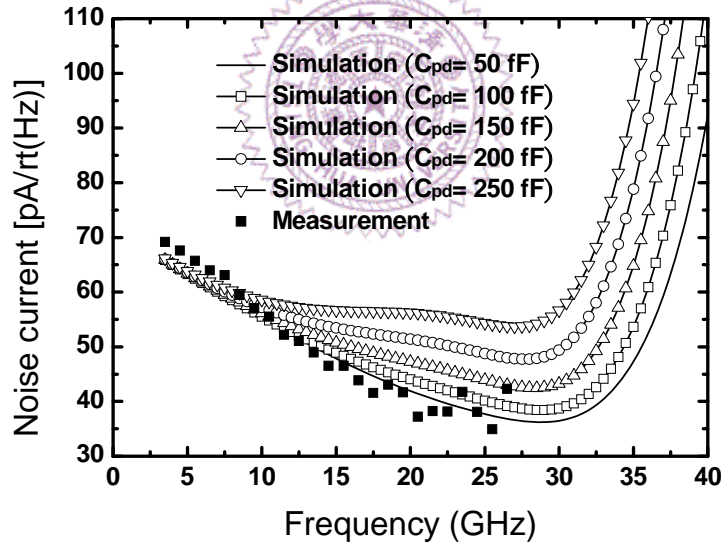


Fig. 5.11. Measured  $i_{n,in}$  and the simulated  $i_{n,in}$  with different values of  $C_{pd}$ .

In addition, the root-mean-square (RMS) noise current can be calculated as [59]:

$$i_{n,in}^{rms} = \frac{1}{R_T} \sqrt{\int_0^{>2f_{3-dB}} |Z_T(f)|^2 \cdot \overline{i_{n,in}^2(f)} df} \quad (5.6)$$

where  $R_T$  is the midband value of  $Z_T$ . By integrating (5.6) up to 61 GHz ( $2f_{3-dB}$ ), the simulated  $i_{n,in}^{rms}$  is 9.7 μA. A corresponding averaged noise current density of 55.7

pA/ $\sqrt{\text{Hz}}$  can be obtained from  $i_{n,in}^{rms}/\sqrt{f_{3-dB}}$ , and the estimated sensitivity of the proposed TIA is 135.8  $\mu\text{A}$  for a bit error rate (BER) of  $10^{-12}$ . The comparison of the averaged noise current density with other 40-Gb/s TIAs is shown in Table 5.1 [60]-[61]. In the proposed TIA, the gain of the first stage is somewhat small ( $\sim 3.5$  dB) resulting in a higher noise level when referred back to the input. The thermal noise generated from  $R_{M1}$  and  $R_{M2}$  which are optimized for wideband matching to a 50- $\Omega$  source termination is also a contributor to the input noise current.

Ref.	This work	[62]	[63]	[64]	[65]	[60]	[61]	[66]
BW (GHz)	30.5	30	9.2	8	7.2	42	47	50
Speed (Gb/s)	40	40	10	10	10	40	40	40
$Z_T$ (dB $\Omega$ )	51	48	54	53	61	59	50	43
$Z_{IN}$ ( $\Omega$ )	54	—	—	—	—	35	—	79*
$S_{22}$ (dB)	-10	—	—	—	—	-8	-10	-12
Noise (pA/ $\sqrt{\text{Hz}}$ )	55.7 (sim.)	—	16.7 (sim.)	18	8.2	34.2	29	—
$C_{pd}$ (fF)	50	—	500	250	250	—	—	—
Chip area (mm <sup>2</sup> )	$1.17 \times 0.46$	$0.8 \times 1.3$	$0.8 \times 0.8$	$0.6 \times 0.6$	0.14	$1 \times 1$	$0.675 \times 0.975$	$0.78 \times 1.18$
$V_{DD}$ (V)	1.8	1.8	2.5	1.8	1.8	5.2	5.2	5.2
$P_{DC}$ (mW)	60.1	50.4	137.5	13.5	70.2	600	458	182
GBW/ $P_{DC}$ (GHz $\Omega$ /mW)	180.1	149.5	33.5	264.7	115.1	62.4	64.7	38.8
Technology	0.18- $\mu\text{m}$ CMOS	0.18- $\mu\text{m}$ CMOS	0.18- $\mu\text{m}$ Bi-CMOS	0.18- $\mu\text{m}$ CMOS	0.18- $\mu\text{m}$ CMOS	SHBT $f_T=150\text{GHz}$	DHBT $f_T=160\text{GHz}$	SiGe $f_T=200\text{GHz}$

\* In the paper,  $S_{11}$ ,  $S_{21}$ , and  $Z_T$  are -13 dB, 6.5 dB, and 43 dB $\Omega$ , respectively. The calculated  $Z_{IN}$  is 79  $\Omega$ .

Table 5.1. TIA Performance summary and comparison with other works.

With a 1.8 V supply voltage, the amplifier consumes 60.1 mW, and a

gain-bandwidth product per DC power figure-of-merit ( $GBW/P_{dc}$ ) of 180.1 GHz $\Omega$ /mW is obtained. The circuit performance of the 40-Gb/s TIA is summarized in Table 5.1 together with four state-of-the-art 0.18- $\mu$ m CMOS TIAs [62]-[65] and three 40-Gb/s TIAs using SiGe and III-V technologies [60]-[61], [66] published recently. As can be seen, the proposed TIA is comparable with those using the technologies with much higher  $f_T$  [60]-[61], [64].

#### 5.4 Measured Transient Responses

To measure the transient response of the 40-Gb/s TIA, a  $2^{31}-1$  PRBS is applied. The high-speed PRBS is generated from the multiplexer MP1803A using the 4-data-output pattern generator MP1758A, and synchronized by the signal generator MG3695B. With an input current swing of 740  $\mu$ A<sub>pp</sub>, the output eye diagrams at 10-, 20-, 30-, and 40-Gb/s are shown in Fig. 5.12 with an output voltage swing of 263 mV<sub>pp</sub>.

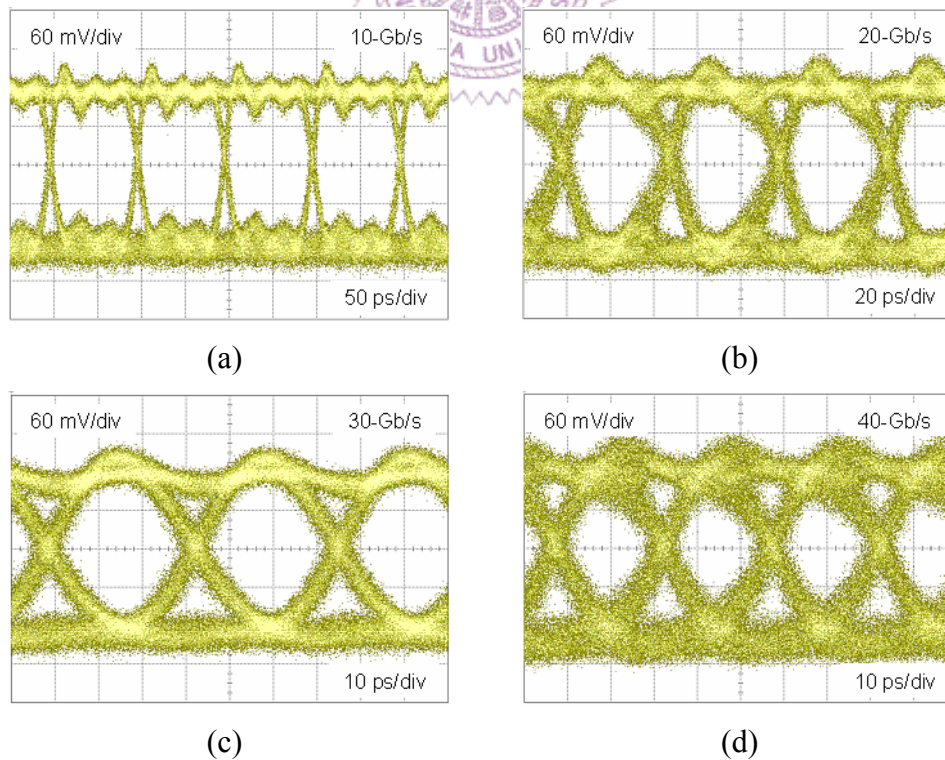


Fig. 5.12. Measure eye-diagram with a  $2^{31}-1$  PRBS input current of 740  $\mu$ A<sub>pp</sub> at (a) 10-Gb/s, (b) 20-Gb/s, (c) 30-Gb/s, and (d) 40-Gb/s.



## 5.5 Summary

An effective bandwidth improvement technique, PIP, has been demonstrated by a 0.18- $\mu\text{m}$  CMOS TIA. Analyses about the noise current characteristics in the PIP configuration were also provided. From the measured results, the proposed circuit presents a circuit bandwidth of 30.5 GHz and a  $GBW/P_{dc}$  up to 180.1 GHz $\Omega$ /mW



# Chapter VI: Conclusions and Future Work

In this dissertation, a fully-integrated CMOS BA was presented, and demonstrated a gain of 45.0 dB at around 24 GHz with an unconditional stability. The input and output ports were both matched well. Under a supply voltage of 1 V,  $NF$  and  $P_{1dB, out}$  were 10.8 dB and -2.3 dBm, respectively. With the proposed PPR design technique and the employment of the lumped-element couplers, the proposed BA showed the highest  $G_{pf}/P_{DC}$  figure-of-merit of 34.3 GHz/mW among the published results.

For the broadband application, an effective bandwidth improvement technique PIP has been demonstrated by a 0.18- $\mu\text{m}$  CMOS TIA. The PIP technique can enhance the bandwidth of a cascaded CS stage by a factor of 3.31. The design concept was discussed in detail and the related equations were derived. Analyses about the noise current characteristics in the PIP configuration were also provided. From the measured results, the proposed circuit presents a circuit bandwidth of 30.5 GHz and a  $GBP/P_{dc}$  of 180.1 GHz $\Omega$ /mW.

## 6.1 Future Work

The successfully demonstrated design techniques for enhancing the CMOS integrated amplifiers at microwave frequencies enable further studies for various applications. The PPR technique can be implanted for different RF building blocks such as mixers, oscillators, power amplifiers, and synthesizer etc. The PIP technique can also be utilized for high-speed building blocks for wideband applications such as limiting amplifier, laser/modulator driver, clock and data recovery, multiplexer, and de-multiplexer.

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# Vita

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1999-2001 Kun Shan University, Tainan, Taiwan  
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## Academic Experience:

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2006/10-2008/02 Intern  
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2001/03	義隆盃單晶片微控制器 應用製作大賽	義隆電子	特優
2001/12	影像伺服即時 追蹤控制應用	教育部顧問室伺服電機 工業教學資源中心	團隊創意獎
2003/01	台灣區溫度感應器 設計大賽	美國國家半導體	亞軍
2006/07	TSMC Outstanding Student Research Award	台灣積體電路	第三名
2007/05	晶片製作成果發表會	國家晶片系統設計中心	特別設計獎
2007/05	晶片製作成果發表會	國家晶片系統設計中心	佳作設計獎
2007/07	7th 旺宏金矽獎	旺宏電子	評審團鑽石大賞
2007/12	補助博士生赴國外研究	國科會	入選
2008/05	晶片製作成果發表會	國家晶片系統設計中心	優良設計獎
2008/07	8th 旺宏金矽獎	旺宏電子	優勝獎
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# Publication List

## Journal papers:

- [1] **Jun-De Jin**, Shawn S. H. Hsu, Ming-Ta Yang, and Sally Liu, "Low-loss differential semicoaxial interconnects in CMOS process," *IEEE Trans. Microw. Theory Tech.*, vol. 54, no. 12, pp. 4333-4340, Dec. 2006.
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- [7] **Jun-De Jin** and Shawn S. H. Hsu, "A 40-Gb/s transimpedance amplifier in 0.18- $\mu\text{m}$  CMOS technology," *IEEE J. Solid-State Circuits*, vol. 43, no. 6, pp. 1449-1457, June 2008.
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- [1] Kuo-Chin Hsueh, **Jun-De Jin**, Yen-Han Lai, and Long-Sheng Fan, "A linear magnetic tweezers for precise particle manipulations," *The 2nd International Symposium on Micro & Nano Technology*, Mar. 2006.
- [2] **Jun-De Jin**, Shawn S. H. Hsu, Ming-Ta Yang, and Sally Liu, "Low-loss single and differential semi-coaxial interconnects in standard CMOS process," in *IEEE MTT-S Int. Microwave Symp. Dig.*, June 2006, pp. 420-423.
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