

Chapter 14 Gaussian Elimination (IV)

Bunch-Kaufman diagonal pivoting (partial pivoting)

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- Reference: [1] James R. *Bunch* and Linda *Kaufman*, Some Stable Methods for Calculating Inertia and Solving Symmetric Linear Systems, *Mathematics of Computation*, volume 31, number 137, January 1977, page 163-179
- [2] Cleve Ashcraft, Roger G. Grimes, and John G. Lewis, Accurate Symmetric Indefinite Linear Equation Solvers, *SIAM J. MATRIX ANAL. APPL.* Vol. 20, No. 2, 1998, pp. 513-561

OutLine

- Review Bunch-Parlett diagonal pivoting
 - expensive pivot-selection strategy
 - pivot induces swapping row/column, not efficient
- Partial pivoting: basic idea
- Implementation of partial pivoting
- Example

Recall Criterion for pivot strategy (complete pivoting) [1]

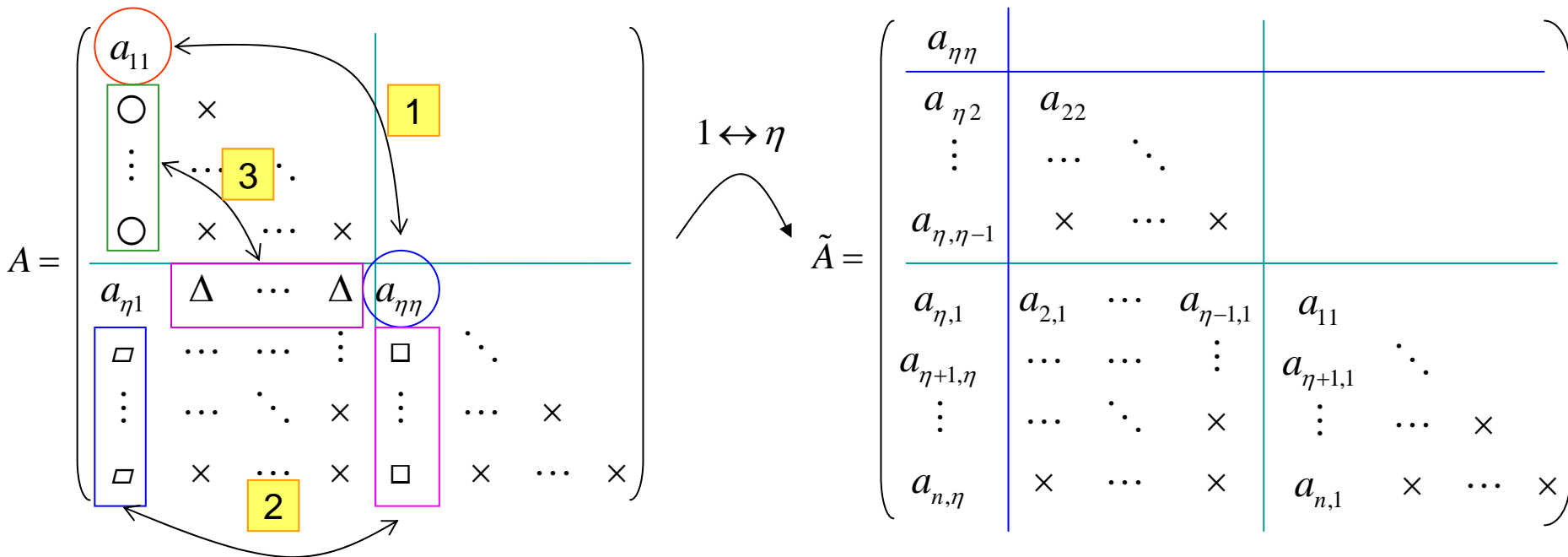
$$A = \begin{pmatrix} a_{11} & & & \\ a_{21} & a_{22} & & \\ \vdots & \dots & \ddots & \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} = A^T$$

$$\mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}| = |A_{rq}| \quad \text{expensive}$$

$$\mu_1 = \max_{1 \leq i \leq n} |A_{ii}| = |A_{\eta\eta}|$$

Case 1: $\mu_1 \geq \alpha \mu_0$

Define permutation matrix $P = (\eta, 2:\eta-1, 1, \eta+1:n)$ and do symmetric permutation



Recall Criterion for pivot strategy (complete pivoting) [2]

Then do LDL^T on \tilde{A} with 1×1 pivot, $\tilde{A} = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix} = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E & \\ & A^{(2)} \end{pmatrix} L^T$, $E = a_{\eta\eta}$

$$c = \begin{pmatrix} A(\eta, 2:\eta-1) \\ a_{\eta,1} \\ A(\eta+1:n,\eta) \end{pmatrix} = \begin{pmatrix} a_{\eta,2} \\ \vdots \\ a_{\eta,\eta-1} \\ \hline a_{\eta,1} \\ \hline a_{\eta+1,\eta} \\ \vdots \\ a_{n,\eta} \end{pmatrix} = \begin{pmatrix} a_{2,\eta} \\ \vdots \\ a_{\eta-1,\eta} \\ \hline a_{1,\eta} \\ \hline a_{\eta+1,\eta} \\ \vdots \\ a_{n,\eta} \end{pmatrix}$$

$$B = \tilde{A}(2:n, 2:n), \quad A^{(2)} = B - cE^{-1}c^T$$

$$cE^{-1} = \frac{c}{a_{\eta\eta}} \rightarrow |cE^{-1}|_\infty \leq \max_{j \neq \eta} \frac{|a_{j\eta}|}{|a_{\eta\eta}|} \leq \frac{1}{\nu} \max_{j \neq \eta} |a_{j\eta}| \leq \frac{\mu_0}{\nu}$$

$$\text{where } \nu = |\det E| = |a_{\eta\eta}|$$

$$\text{Therefore } |L|_\infty = \max\left(1, |cE^{-1}|_\infty\right) \leq \max\left(1, \frac{\mu_0}{\nu}\right) \leq \frac{\mu_0}{\nu}$$

Observation: if we define $\lambda = \max_{j \neq \eta} |A_{j,\eta}| =$ maximum of off-diagonal elements in column η

$$\text{, then } |L|_\infty \leq \max\left(1, \frac{\lambda}{\nu}\right) \leq \frac{\mu_0}{\nu}$$

Recall Criterion for pivot strategy (complete pivoting) [3]

$$A^{(2)} = B - cE^{-1}c^T = \tilde{A}(2:n, 2:n) - L(2:n, 1) \left[\tilde{A}(2:n, 1) \right]^T$$

$$A_{ij}^{(2)} = \tilde{A}_{i+1, j+1} - L_{i+1, 1} \tilde{A}_{j+1, 1} \longrightarrow \boxed{\left| A^{(2)} \right|_{\infty} \leq \mu_0 + |L|_{\infty} \lambda}$$

Question: To compute $\mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}| = |A_{rq}|$ is expensive, if we don't want to compute it, Can we have other choice such that controllability of $|L|_{\infty}$ and $|A^{(2)}|_{\infty}$ holds ?

Observation: It suffices to change pivoting condition $\mu_1 \geq \alpha \mu_0$ to $\mu_1 \geq \alpha \lambda$, then

$$\boxed{|L|_{\infty} \leq \max \left(1, \frac{\lambda}{\nu} \right) \leq \max \left(1, \frac{1}{\alpha} \right) = \frac{1}{\alpha}} \quad \text{and} \quad \boxed{\left| A^{(2)} \right|_{\infty} \leq \mu_0 + \frac{1}{\alpha} \lambda \leq \left(1 + \frac{1}{\alpha} \right) \mu_0}$$

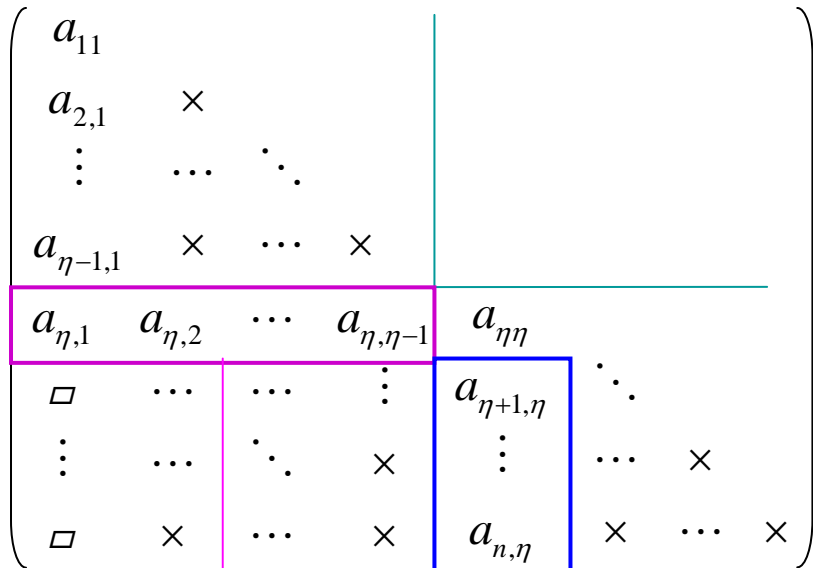
The same as that we do by using pivoting criterion (complete pivoting) $\mu_1 \geq \alpha \mu_0$

However computing $\lambda = \max_{j \neq \eta} |A_{j, \eta}|$ is cheaper than $\mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}|$

since $\lambda = \max_{j \neq \eta} |A_{j, \eta}| = O(n)$ but $\mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}| = O(n^2 / 2)$

Recall Criterion for pivot strategy (complete pivoting) [4]

Technical problem: computing $\lambda = \max_{j \neq \eta} |A_{j,\eta}|$ does not attain optimal.

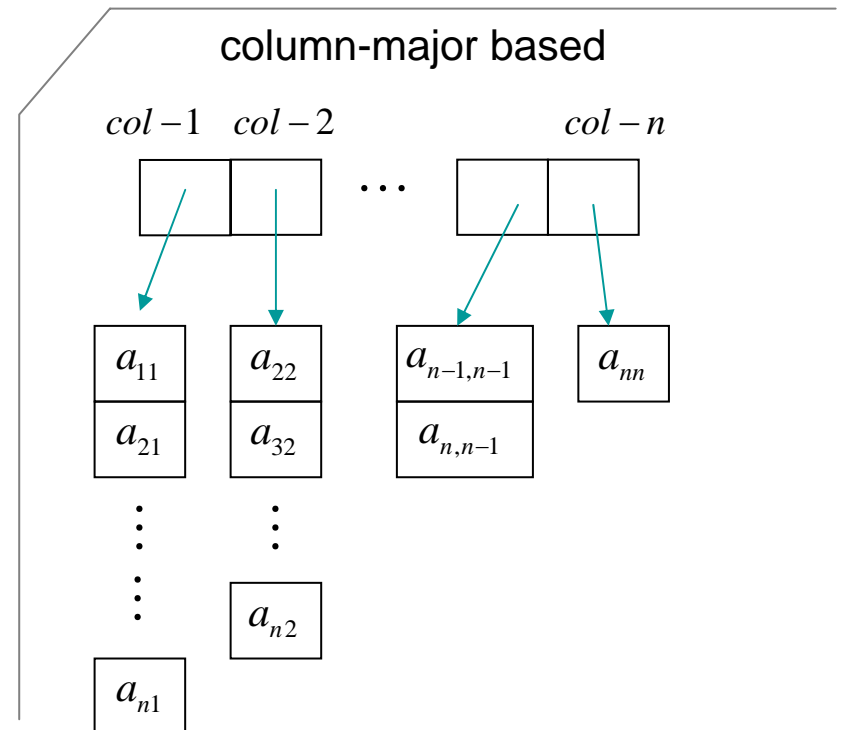


Contiguous memory block, fast

NOT contiguous memory block, **slowly**.

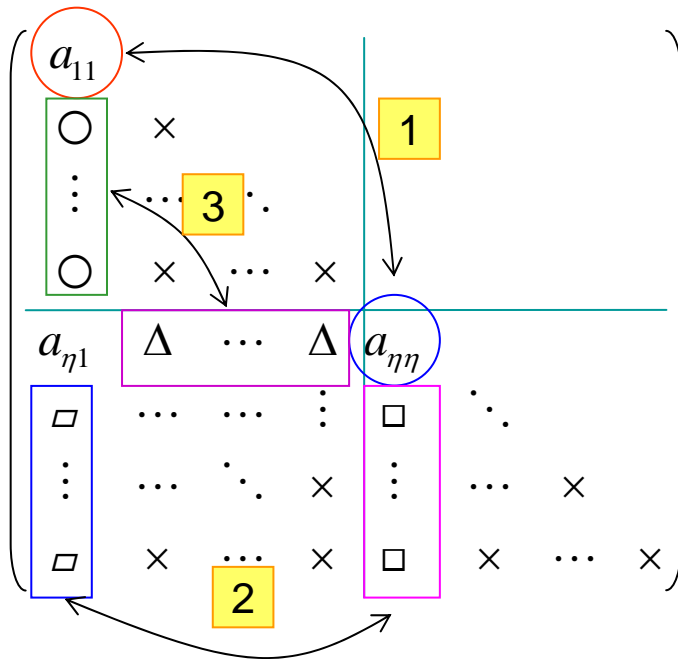
How to improve this ?

$$\lambda = \max_{j \neq \eta} |A_{j,\eta}| = \max \left(\left(|a_{\eta,1}| \quad \dots \quad |a_{\eta,\eta-1}| \right), \begin{pmatrix} |a_{\eta+1,\eta}| \\ \vdots \\ |a_{n,\eta}| \end{pmatrix} \right)$$



Recall Criterion for pivot strategy (complete pivoting) [5]

Second, if $\mu_1 \geq \alpha\lambda$, we need to interchange row/column $\eta \leftrightarrow 1$



3 relates to read/write on row vector $(\Delta \ \dots \ \Delta)$ which is **NOT** contiguous, slowly.

Question: why we persist on computing $\mu_1 = \max_{1 \leq i \leq n} |A_{ii}| = |A_{\eta\eta}|$, why not choose first column?

say $E = a_{11}$ and $\lambda = \max_{j \neq 1} |A_{j,1}| =$ maximum of off-diagonal elements in column 1

Again, if $\nu \geq \alpha\lambda$, then we also have

$$|L|_{\infty} \leq \max\left(1, \frac{\lambda}{\nu}\right) \leq \max\left(1, \frac{1}{\alpha}\right) = \frac{1}{\alpha} \quad \text{and} \quad |A^{(2)}|_{\infty} \leq \mu_0 + \frac{1}{\alpha} \lambda \leq \left(1 + \frac{1}{\alpha}\right) \mu_0$$

OutLine

- Review Bunch-Parlett diagonal pivoting
- **Partial pivoting: basic idea**
 - select pivot by at most computation of two columns
 - potential risk of growth rate of lower triangle matrix
- Implementation of partial pivoting
- Example

Partial pivoting: basic idea [1]

$$A = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix}, \text{ choose } E = a_{11} \text{ and } \lambda_1 = \max |c| = \text{maximum of off-diagonal elements in column 1}$$

If $|a_{11}| \geq \alpha \lambda_1$ [α is determined later], then

$$A = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E & \\ & A^{(2)} \end{pmatrix} L^T \longrightarrow \begin{cases} |L|_\infty \leq \max \left(1, \frac{\lambda_1}{\nu} \right) \leq \frac{1}{\alpha} \\ |A^{(2)}|_\infty \leq \mu_0 + \frac{\lambda_1}{\alpha} \leq \left(1 + \frac{1}{\alpha} \right) \mu_0 \end{cases} \quad \text{where } \mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}|$$

Pros (優點): ~~compute $\mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}|$ and $\mu_1 = \max_{1 \leq i \leq n} |A_{ii}|$~~

Cons (缺點): It is difficult to satisfy $|a_{11}| \geq \alpha \lambda_1$, we need to deal with the case $|a_{11}| < \alpha \lambda_1$ carefully such that controllability of $|L|_\infty$ and $|A^{(2)}|_\infty$ holds.

Comparison with $PA = LU$: suppose $|a_{11}| < \alpha \lambda_1$ for $|a_{r1}| = \lambda_1$

we **CANNOT** move A_{r1} to A_{11} due to symmetric permutation,

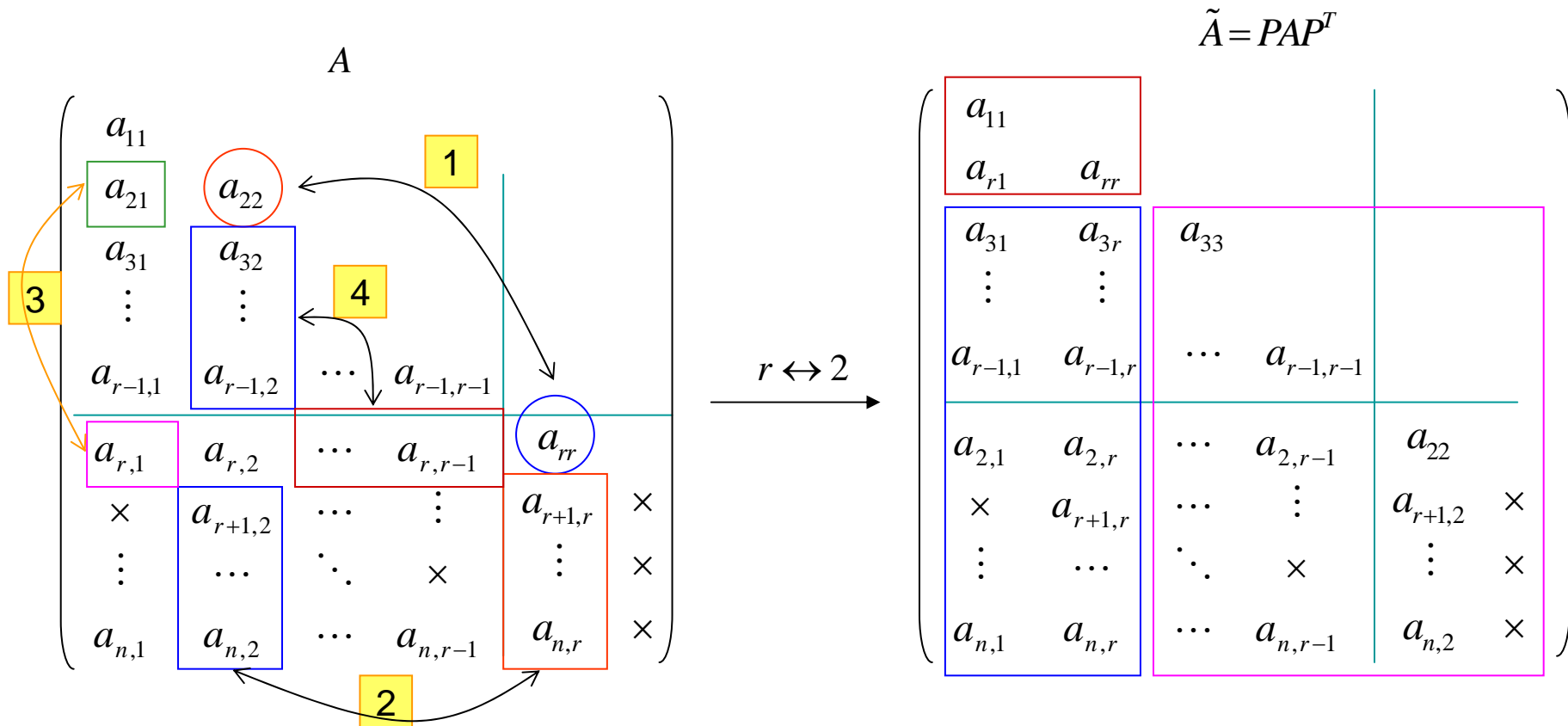
It is impossible to keep stability by just computing one column as we do in $PA = LU$

Partial pivoting: basic idea [2]

Question: how to deal with the case $|a_{11}| < \alpha\lambda_1$ for $|a_{r1}| = \lambda_1$

<ans> from procedure of complete pivoting, we need 2x2 pivot.

define permutation $P = (1, r, 3:r-1, 2, r+1:n)$, change a_{r1} to a_{21}



Partial pivoting: basic idea [3]

$$A = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix} = L \begin{pmatrix} E & \\ & A^{(3)} \end{pmatrix} L^T$$

$$E = \begin{pmatrix} a_{11} & a_{21} \\ a_{21} & a_{22} \end{pmatrix}, \quad c = \begin{pmatrix} a_{31} & a_{32} \\ \vdots & \vdots \\ a_{r-1,1} & a_{r-1,2} \\ a_{r,1} & a_{r,2} \\ a_{r+1,1} & a_{r+1,2} \\ \vdots & \vdots \\ a_{n,1} & a_{n,2} \end{pmatrix}$$

$r \leftrightarrow 2$

$$\tilde{A} = \begin{pmatrix} \tilde{E} & \tilde{c}^T \\ \tilde{c} & \tilde{B} \end{pmatrix} = \tilde{L} \begin{pmatrix} \tilde{E} & \\ & \tilde{A}^{(3)} \end{pmatrix} \tilde{L}^T$$

$$\tilde{E} = \begin{pmatrix} a_{11} & a_{r1} \\ a_{r1} & a_{rr} \end{pmatrix}, \quad \tilde{c} = \begin{pmatrix} a_{31} & a_{3r} \\ \vdots & \vdots \\ a_{r-1,1} & a_{r-1,r} \\ a_{2,1} & a_{2,r} \\ a_{r+1,1} & a_{r+1,r} \\ \vdots & \vdots \\ a_{n,1} & a_{n,r} \end{pmatrix}$$

$$L = \begin{pmatrix} I & \\ cE^{-1} & I \end{pmatrix} = \begin{pmatrix} I & \\ (l_1 | l_2) & I \end{pmatrix}$$

$\forall 3 \leq i \leq n$

$$(l_{i1} \quad l_{i2}) = (a_{i,1} \quad a_{i,2}) \frac{1}{\det E} \begin{pmatrix} a_{22} & -a_{21} \\ -a_{21} & a_{11} \end{pmatrix}$$

$$L = \begin{pmatrix} I & \\ \tilde{c}\tilde{E}^{-1} & I \end{pmatrix} = \begin{pmatrix} I & \\ (\tilde{l}_1 | \tilde{l}_2) & I \end{pmatrix}$$

$\forall i = 3 : r-1, 2, r+1 : n$

$$(l_{i1} \quad l_{ir}) = (a_{i,1} \quad a_{i,r}) \frac{1}{\det \tilde{E}} \begin{pmatrix} a_{rr} & -a_{r1} \\ -a_{r1} & a_{11} \end{pmatrix}$$

we may say $\forall i \neq 1, r$

Partial pivoting: basic idea [4]

$$B = \begin{pmatrix} a_{33} & & & & \\ \vdots & \ddots & & & \\ a_{r3} & a_{r4} & \cdots & a_{rr} & \\ a_{r+1,3} & & & a_{r+1,r} & \\ & & & \vdots & \ddots \\ a_{n,3} & \cdots & & a_{n,r} & \cdots & a_{nn} \end{pmatrix}$$

$$B_{i,j} = a_{i+2,j+2}$$

$$A^{(3)} = B - cE^{-1}c^T$$

$$A_{ij}^{(3)} = B_{ij} - \begin{pmatrix} c_{i,1} & c_{i,2} \end{pmatrix} E^{-1} \begin{pmatrix} c_{j,1} \\ c_{j,2} \end{pmatrix}$$

$$= a_{i+2,j+2} - \begin{pmatrix} a_{i+2,1} & a_{i+2,2} \end{pmatrix} \frac{1}{\det E} \begin{pmatrix} a_{22} & -a_{21} \\ -a_{21} & a_{11} \end{pmatrix} \begin{pmatrix} a_{j+2,1} \\ a_{j+2,2} \end{pmatrix}$$

$r \leftrightarrow 2$

$$\tilde{B} = \begin{pmatrix} a_{33} & & & & \\ \vdots & \ddots & & & \\ a_{23} & a_{24} & \cdots & a_{22} & \\ a_{r+1,3} & & & a_{r+1,2} & \\ & & & \vdots & \ddots \\ a_{n,3} & \cdots & & a_{n,2} & \cdots & a_{nn} \end{pmatrix}$$

$$\tilde{A}^{(3)} = \tilde{B} - \tilde{c}\tilde{E}^{-1}\tilde{c}^T$$

$\forall i+2 \neq 1, r \text{ and } j+2 \neq 1, r$

$$\tilde{A}_{ij}^{(3)} = a_{i+2,j+2} - \begin{pmatrix} a_{i+2,1} & a_{i+2,r} \end{pmatrix} \frac{1}{\det \tilde{E}} \begin{pmatrix} a_{rr} & -a_{r1} \\ -a_{r1} & a_{11} \end{pmatrix} \begin{pmatrix} a_{j+2,1} \\ a_{j+2,r} \end{pmatrix}$$

Partial pivoting: basic idea [5]

Under the case $|a_{11}| < \alpha\lambda_1$, we want to find a condition for a_{rr} such that $|\tilde{L}|_\infty$ is bounded.

$\forall i \neq 1, r$

$$(l_{i1} \quad l_{ir}) = (a_{i,1} \quad a_{i,r}) \frac{1}{\det \tilde{E}} \begin{pmatrix} a_{rr} & -a_{r1} \\ -a_{r1} & a_{11} \end{pmatrix} \longrightarrow \begin{cases} l_{i1} = \frac{1}{\det \tilde{E}} (a_{i,1}a_{rr} - a_{i,r}a_{r1}) \\ l_{ir} = \frac{1}{\det \tilde{E}} (-a_{i,1}a_{r1} + a_{i,r}a_{11}) \end{cases}$$

$$\left\{ \begin{array}{l} |l_{i1}| \leq \frac{|a_{i,1}||a_{rr}| + |a_{i,r}||a_{r1}|}{|\det \tilde{E}|} \leq \frac{\lambda_1|a_{rr}| + |a_{i,r}|\lambda_1}{|\det \tilde{E}|} \\ |l_{ir}| \leq \frac{|a_{i,1}||a_{r1}| + |a_{i,r}||a_{11}|}{|\det \tilde{E}|} \leq \frac{\lambda_1\lambda_1 + |a_{i,r}||a_{11}|}{|\det \tilde{E}|} \end{array} \right. \xrightarrow{|\tilde{L}|_\infty \leq ?} \left\{ \begin{array}{l} \text{Lower bound of } |\det \tilde{E}| \\ \text{upper bound of } |a_{i,r}|, |a_{r,r}| \end{array} \right.$$

define $\lambda_r \equiv \max_{j \neq r} |a_{j,r}| =$ maximum of off-diagonal elements in column r

1 $\lambda_r \equiv \max_{j \neq r} |a_{j,r}| \geq |a_{1,r}| = \lambda_1$

2 If $|a_{rr}| < \alpha\lambda_r$, then upper bound of $|a_{i,r}|, |a_{r,r}|$ holds.

Question: how to achieve lower bound of $|\det \tilde{E}|$

Partial pivoting: basic idea [6]

$$|\det \tilde{E}| = |a_{11}a_{rr} - a_{r1}^2| = |a_{11}a_{rr} - \lambda_1^2| = \begin{cases} a_{11}a_{rr} - \lambda_1^2 & \text{if } a_{11}a_{rr} > \lambda_1^2 \\ \lambda_1^2 - a_{11}a_{rr} & \text{if } a_{11}a_{rr} < \lambda_1^2 \end{cases}$$

From assumption $|a_{11}| < \alpha\lambda_1$, to keep inequality, the natural choice is $\lambda_1^2 > a_{11}a_{rr}$

Since if we add assumption $|a_{rr}| < \alpha\lambda_r$, then $|a_{11}a_{rr}| < |a_{11}|(\alpha\lambda_r)$ and moreover

If we add third assumption

3 $|a_{11}|\lambda_r < \alpha\lambda_1^2$, then $|a_{11}a_{rr}| < |a_{11}|(\alpha\lambda_r) < \alpha^2\lambda_1^2$ and then $|\det \tilde{E}| = \lambda_1^2 - a_{11}a_{rr} > (1 - \alpha^2)\lambda_1^2$

Lower bound of $|\det \tilde{E}|$ holds.

To sum up, in order to control $|\tilde{L}|_\infty$ under 2x2 pivoting, we need three conditions

$$(1) |a_{11}| < \alpha\lambda_1 \quad (2) |a_{rr}| < \alpha\lambda_r \quad (3) |a_{11}|\lambda_r < \alpha\lambda_1^2$$

$$\begin{cases} |l_{i1}| \leq \frac{\lambda_1|a_{rr}| + |a_{i,r}|\lambda_1}{|\det \tilde{E}|} < \frac{\lambda_1(\alpha\lambda_r) + \lambda_r\lambda_1}{(1 - \alpha^2)\lambda_1^2} = \frac{\lambda_r}{\lambda_1} \frac{1}{1 - \alpha} \\ |l_{ir}| \leq \frac{\lambda_1\lambda_1 + |a_{i,r}||a_{11}|}{|\det \tilde{E}|} < \frac{\lambda_1^2 + \lambda_r|a_{11}|}{(1 - \alpha^2)\lambda_1^2} < \frac{\lambda_1^2 + \alpha\lambda_1^2}{(1 - \alpha^2)\lambda_1^2} = \frac{1}{1 - \alpha} \end{cases} \longrightarrow |\tilde{L}|_\infty \leq \frac{\lambda_r}{\lambda_1} \frac{1}{1 - \alpha} \quad (\because \lambda_r \geq \lambda_1)$$

Partial pivoting: basic idea [7]

Question: does the three condition keep controllability of $\left| \tilde{A}^{(3)} \right|_{\infty}$

$$\forall i+2 \neq 1, r \text{ and } j+2 \neq 1, r \quad \left\{ \begin{array}{l} \tilde{A}_{ij}^{(3)} = a_{i+2, j+2} - \begin{pmatrix} a_{i+2,1} & a_{i+2,r} \end{pmatrix} \frac{1}{\det \tilde{E}} \begin{pmatrix} a_{rr} & -a_{r1} \\ -a_{r1} & a_{11} \end{pmatrix} \begin{pmatrix} a_{j+2,1} \\ a_{j+2,r} \end{pmatrix} \\ = a_{i+2, j+2} - \frac{1}{\det \tilde{E}} \left(a_{i+2,1} a_{rr} - a_{i+2,r} a_{r1} \quad -a_{i+2,1} a_{r,1} + a_{i+2,r} a_{11} \right) \begin{pmatrix} a_{j+2,1} \\ a_{j+2,r} \end{pmatrix} \\ = a_{i+2, j+2} - \frac{\left(a_{i+2,1} a_{rr} - a_{i+2,r} a_{r1} \right) a_{j+2,1} + \left(-a_{i+2,1} a_{r,1} + a_{i+2,r} a_{11} \right) a_{j+2,r}}{\det \tilde{E}} \end{array} \right.$$

$$\longrightarrow \left| \tilde{A}^{(3)} \right|_{\infty} \leq \mu_0 + \frac{(\lambda_1 |a_{rr}| + \lambda_r \lambda_1) \lambda_1 + (\lambda_1 \lambda_1 + \lambda_r |a_{11}|) \lambda_r}{|\det \tilde{E}|}$$

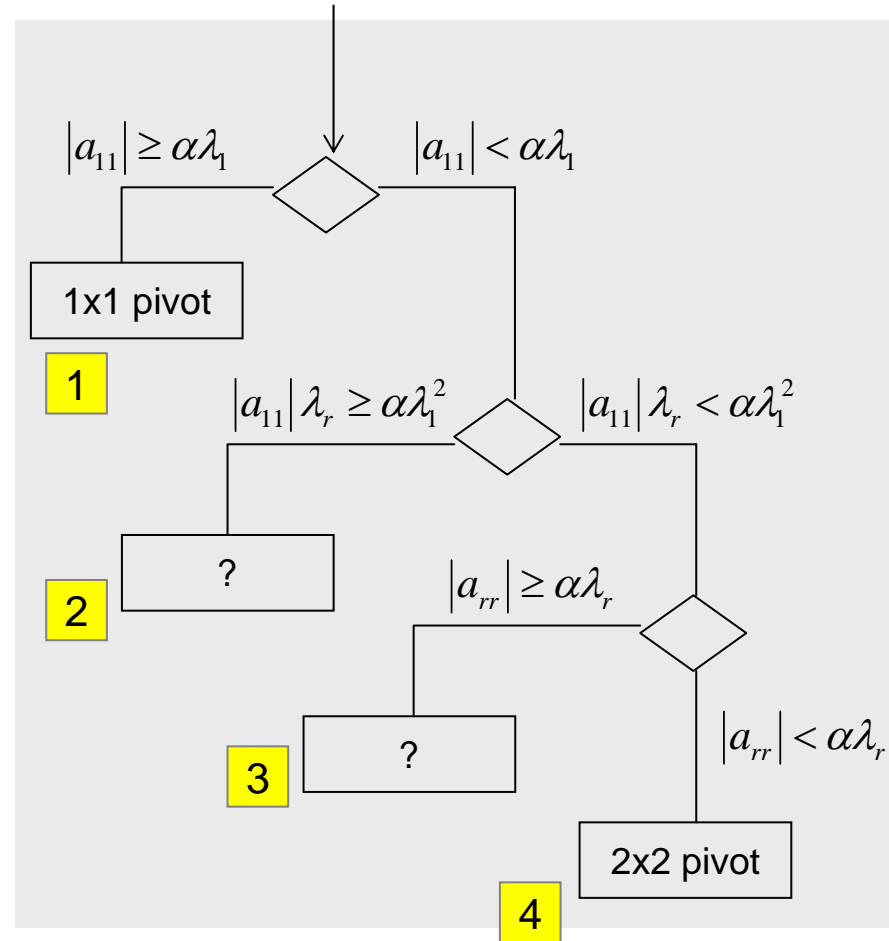
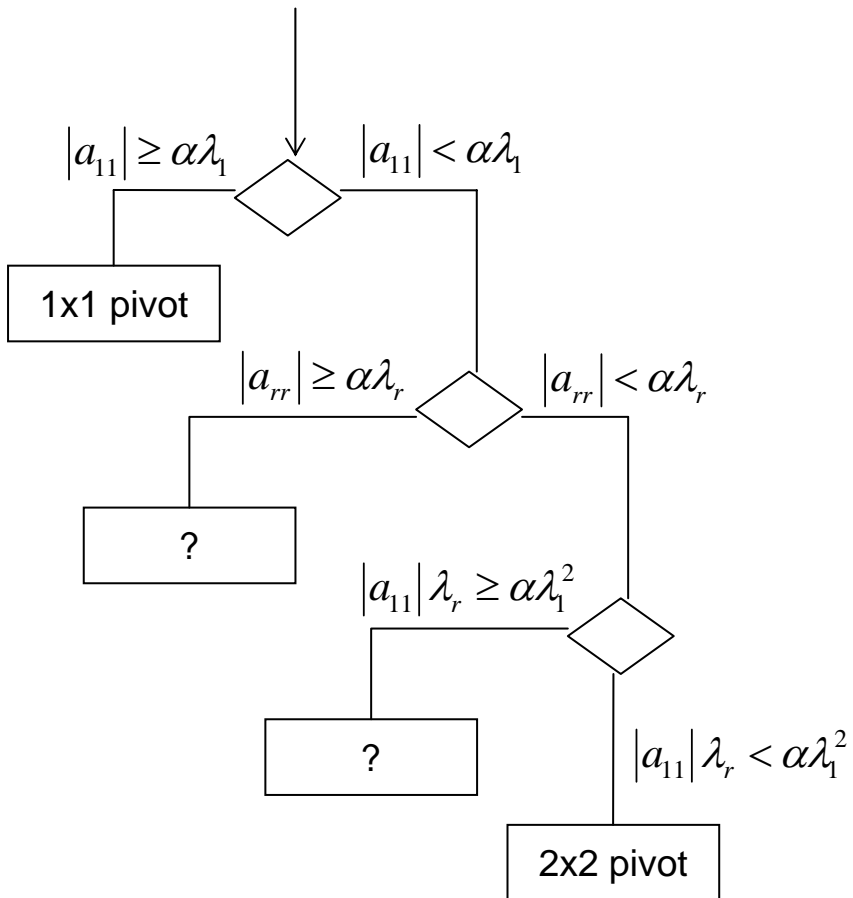
$$\xrightarrow{(2) \quad |a_{rr}| < \alpha \lambda_r} \left| \tilde{A}^{(3)} \right|_{\infty} \leq \mu_0 + \frac{(\lambda_1 \alpha \lambda_r + \lambda_r \lambda_1) \lambda_1 + (\lambda_1^2 + \lambda_r |a_{11}|) \lambda_r}{|\det \tilde{E}|}$$

$$\xrightarrow{(3) \quad |a_{11}| \lambda_r < \alpha \lambda_1^2} \left| \tilde{A}^{(3)} \right|_{\infty} \leq \mu_0 + \frac{(1+\alpha) \lambda_r \lambda_1^2 + (\lambda_1^2 + \alpha \lambda_1^2) \lambda_r}{|\det \tilde{E}|}$$

$$\xrightarrow{(1) \quad |a_{11}| < \alpha \lambda_1} \left| \tilde{A}^{(3)} \right|_{\infty} \leq \mu_0 + \frac{2(1+\alpha) \lambda_r \lambda_1^2}{(1-\alpha^2) \lambda_1^2} = \mu_0 + \frac{2\lambda_r}{1-\alpha} \leq \mu_0 \left(1 + \frac{2}{1-\alpha} \right)$$

Partial pivoting: basic idea [8]

So far, we deal with two cases in the following decision-making tree



Question: how to deal with the other two cases and what is the order of decision-making, briefly speaking which tree is correct, left or right?

Partial pivoting: basic idea [9]

$$A = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix}, \quad E = a_{11} \quad \text{and} \quad \lambda_1 = |a_{r1}| = \max |c| = \text{maximum of off-diagonal elements in column 1}$$

$$\mu_0 = \max_{1 \leq i, j \leq n} |A_{ij}| = \text{maximum elements of } A, \text{ we do not compute it explicitly.}$$

$$\mathbf{1} \quad |a_{11}| \geq \alpha \lambda_1 \quad \mathbf{1 \times 1 \text{ pivot}}$$

$$A = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E & \\ & A^{(2)} \end{pmatrix} L^T, \quad c = A(2:n, 1) = \begin{pmatrix} a_{21} \\ \vdots \\ a_{r1} \\ \vdots \\ a_{n1} \end{pmatrix}, \quad B = A(2:n, 2:n) = \begin{pmatrix} a_{22} & & & \\ a_{31} & a_{22} & & \\ \vdots & & \ddots & \\ a_{n1} & \dots & & a_{nn} \end{pmatrix}$$

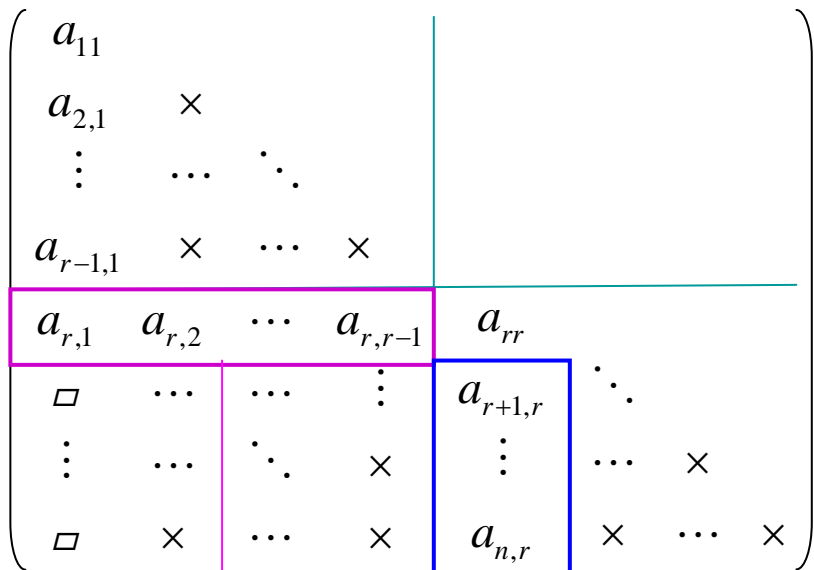
$$cE^{-1} = \frac{c}{a_{11}} \rightarrow |cE^{-1}|_\infty \leq \max_{j \neq 1} \left| \frac{a_{j1}}{a_{11}} \right| \leq \frac{1}{|a_{11}|} \max_{j \neq 1} |a_{j1}| \leq \frac{\lambda_1}{|a_{11}|} \leq \frac{1}{\alpha} \longrightarrow |L|_\infty = \max \left(1, |cE^{-1}|_\infty \right) \leq \frac{1}{\alpha}$$

$$A^{(2)} = B - cE^{-1}c^T = A(2:n, 2:n) - L(2:n, 1) [A(2:n, 1)]^T$$

$$A_{ij}^{(2)} = A_{i+1, j+1} - L_{i+1, 1} A_{j+1, 1} \longrightarrow |A^{(2)}|_\infty \leq \mu_0 + |L|_\infty \lambda_1 \leq \left(1 + \frac{1}{\alpha} \right) \mu_0$$

Partial pivoting: basic idea [10]

define $\lambda_r \equiv \max_{j \neq r} |a_{j,r}| = \text{maximum of off-diagonal elements in column } r$



$$\lambda_r = \max_{j \neq r} |A_{j,r}| = \max \left(\left(|a_{r,1}| \quad \cdots \quad |a_{r,r-1}| \right), \begin{pmatrix} |a_{r+1,r}| \\ \vdots \\ |a_{n,r}| \end{pmatrix} \right)$$

$\lambda_r \geq |a_{r1}| = \lambda_1$

NOT contiguous memory block, **slowly**.

Remark: when case 1 is not satisfied, we must compute λ_r for remaining decision-making.

Remark: In general, λ_r may be more larger than λ_1 , that is why case 2 holds

2

 $|a_{11}| \lambda_r \geq \alpha \lambda_1^2$

Partial pivoting: basic idea [11]

2 $|a_{11}| \lambda_r \geq \alpha \lambda_1^2$ [under $|a_{11}| < \alpha \lambda_1$] 1×1 pivot

$$A = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E & \\ & A^{(2)} \end{pmatrix} L^T, \quad c = A(2:n,1) = \begin{pmatrix} a_{21} \\ \vdots \\ a_{r1} \\ \vdots \\ a_{n1} \end{pmatrix}, \quad B = A(2:n,2:n) = \begin{pmatrix} a_{22} & & & \\ a_{31} & a_{22} & & \\ \vdots & & \ddots & \\ a_{n1} & \cdots & & a_{nn} \end{pmatrix}$$

$$cE^{-1} = \frac{c}{a_{11}} \rightarrow |cE^{-1}|_\infty \leq \max_{j \neq 1} \left| \frac{a_{j1}}{a_{11}} \right| \leq \frac{\lambda_1}{|a_{11}|} = \frac{\lambda_1 \lambda_r}{|a_{11}| \lambda_r} \leq \frac{\lambda_r}{\lambda_1} \frac{1}{\alpha} \longrightarrow |L|_\infty = \max\left(1, |cE^{-1}|_\infty\right) \leq \frac{\lambda_r}{\lambda_1} \frac{1}{\alpha}$$

$$A^{(2)} = B - cE^{-1}c^T = A(2:n,2:n) - L(2:n,1)[A(2:n,1)]^T$$

$$A_{ij}^{(2)} = A_{i+1,j+1} - L_{i+1,1}A_{j+1,1} \longrightarrow |A^{(2)}|_\infty \leq \mu_0 + |L|_\infty \lambda_1 \leq \mu_0 + \left(\frac{\lambda_r}{\lambda_1} \frac{1}{\alpha}\right) \lambda_1 \leq \left(1 + \frac{1}{\alpha}\right) \mu_0$$

Remark: bound on lower triangle matrix is NOT good since it is proportional to $\frac{\lambda_r}{\lambda_1}$

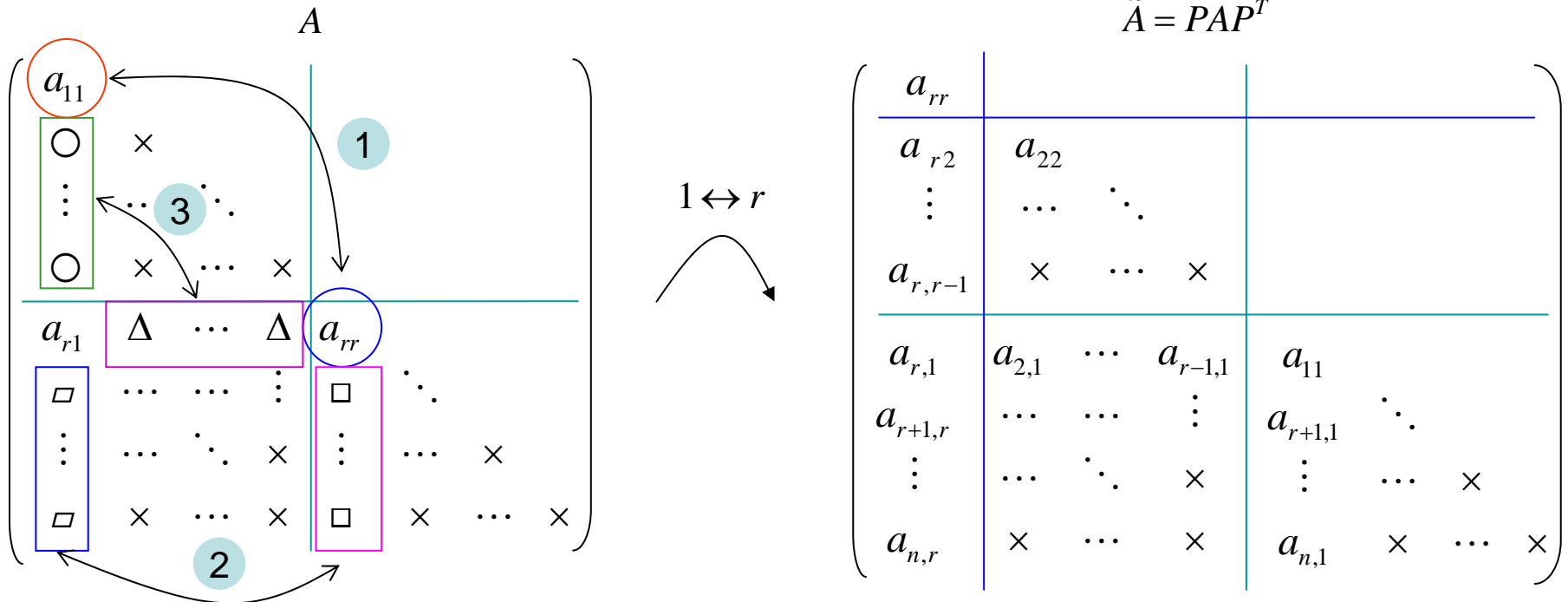
however, the bound of reduced matrix $A^{(2)}$ is good.

Partial pivoting: basic idea [12]

3 $|a_{rr}| \geq \alpha \lambda_r$ under $|a_{11}| < \alpha \lambda_1$, $|a_{11}| \lambda_r < \alpha \lambda_1^2$ 1×1 pivot

Clearly, this is the same as case 1 if we interchange row/column $1 \leftrightarrow r$

define permutation $P = (r, 2:r-1, 2, r+1:n)$, change a_{rr} to a_{11}



Partial pivoting: basic idea [13]

Then do LDL^T on \tilde{A} with 1×1 pivot, $\tilde{A} = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix} = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E & \\ & A^{(2)} \end{pmatrix} L^T$, $E = a_{rr}$

$$c = \begin{pmatrix} A(r, 2:r-1) \\ a_{r,1} \\ A(r+1:n, r) \end{pmatrix} = \begin{pmatrix} a_{r,2} \\ \vdots \\ a_{r,r-1} \\ \hline a_{r,1} \\ \hline a_{r+1,r} \\ \vdots \\ a_{n,r} \end{pmatrix} = \begin{pmatrix} a_{2,r} \\ \vdots \\ a_{r-1,r} \\ \hline a_{1,r} \\ \hline a_{r+1,r} \\ \vdots \\ a_{n,r} \end{pmatrix}$$

$B = \tilde{A}(2:n, 2:n), A^{(2)} = B - cE^{-1}c^T$

$$cE^{-1} = \frac{c}{a_{rr}} \rightarrow |cE^{-1}|_{\infty} \leq \max_{j \neq r} \left| \frac{a_{jr}}{a_{rr}} \right| \leq \frac{1}{|a_{rr}|} \max_{j \neq r} |a_{jr}| \leq \frac{\lambda_r}{|a_{rr}|} \leq \frac{1}{\alpha} \longrightarrow |L|_{\infty} = \max\left(1, |cE^{-1}|_{\infty}\right) \leq \frac{1}{\alpha}$$

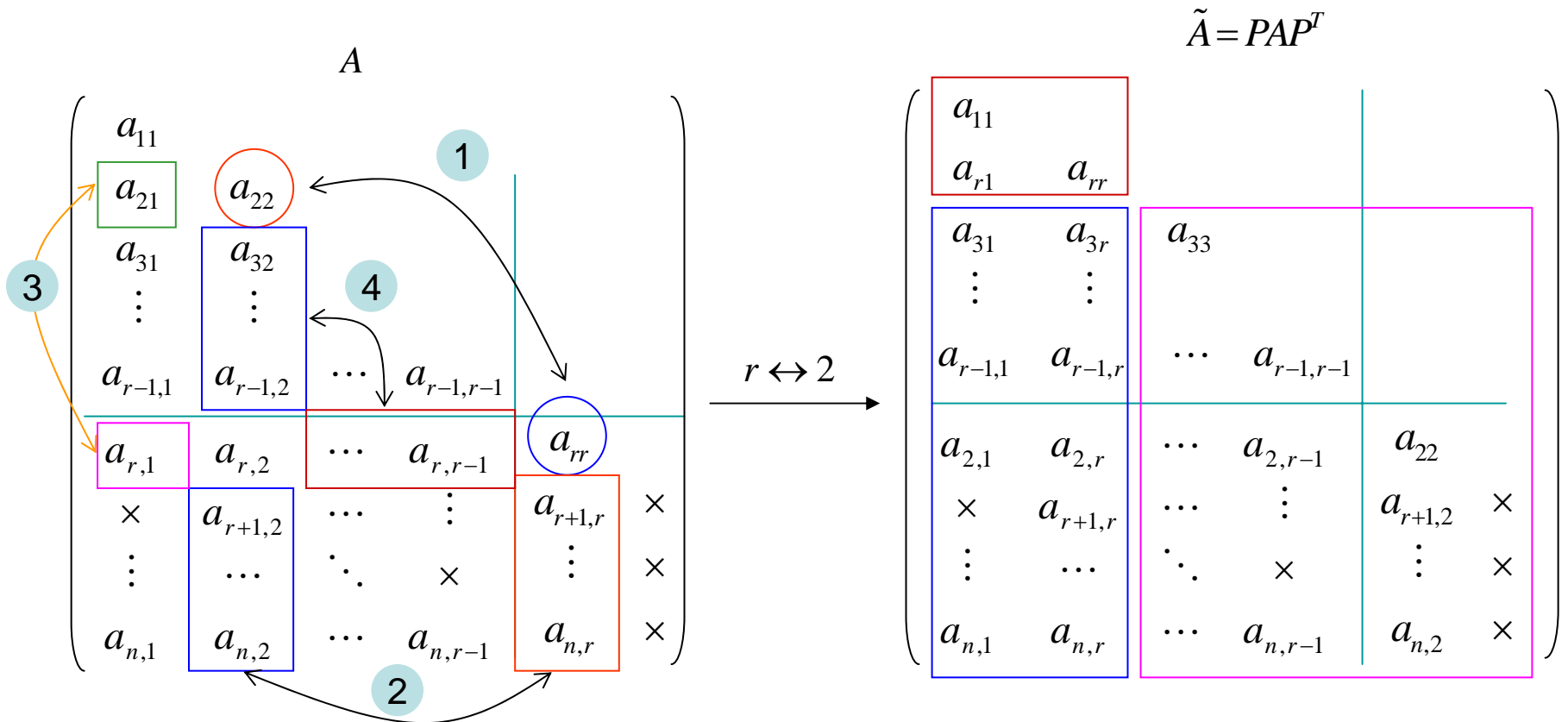
$$A^{(2)} = B - cE^{-1}c^T = \tilde{A}(2:n, 2:n) - L(2:n, 1) \left[\tilde{A}(2:n, 1) \right]^T$$

$$\left| A^{(2)} \right|_{\infty} \leq \mu_0 + |L|_{\infty} |c|_{\infty} \leq \mu_0 + \frac{1}{\alpha} \lambda_r \leq \left(1 + \frac{1}{\alpha} \right) \mu_0$$

Partial pivoting: basic idea [14]

4 $|a_{rr}| < \alpha \lambda_r$ under $|a_{11}| < \alpha \lambda_1$, $|a_{11}| \lambda_r < \alpha \lambda_1^2$ 2x2 pivot

define permutation $P = (1, r, 3:r-1, 2, r+1:n)$, change a_{r1} to a_{21}



Partial pivoting: basic idea [15]

Then do LDL^T on \tilde{A} with 2×2 pivot, $\tilde{A} = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix} = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E & \\ & A^{(3)} \end{pmatrix} L^T$

$$E = \begin{pmatrix} a_{11} & a_{r1} \\ a_{r1} & a_{rr} \end{pmatrix}, \quad \boxed{|\det E| = |a_{11}a_{rr} - a_{r1}^2| \geq (1 - \alpha^2)\lambda_1^2} \quad L = \begin{pmatrix} I_2 & \\ (l_1 | l_r) & I_{n-2} \end{pmatrix}$$

$$\forall i \neq 1, r \quad \begin{cases} l_{i1} = \frac{1}{\det \tilde{E}} (a_{i,1}a_{rr} - a_{i,r}a_{r1}) \\ l_{ir} = \frac{1}{\det \tilde{E}} (-a_{i,1}a_{r1} + a_{i,r}a_{11}) \end{cases} \longrightarrow \begin{cases} |l_{i1}| \leq \frac{\lambda_r}{\lambda_1} \frac{1}{1 - \alpha} \\ |l_{ir}| \leq \frac{1}{1 - \alpha} \end{cases} \longrightarrow \boxed{|L|_\infty \leq \frac{\lambda_r}{\lambda_1} \frac{1}{1 - \alpha}}$$

$$\forall i+2 \neq 1, r \text{ and } j+2 \neq 1, r \quad A_{ij}^{(3)} = a_{i+2, j+2} - \frac{(a_{i+2,1}a_{rr} - a_{i+2,r}a_{r1})a_{j+2,1} + (-a_{i+2,1}a_{r1} + a_{i+2,r}a_{11})a_{j+2,r}}{\det \tilde{E}}$$

$$\boxed{|A^{(3)}|_\infty \leq \mu_0 \left(1 + \frac{2}{1 - \alpha} \right)}$$

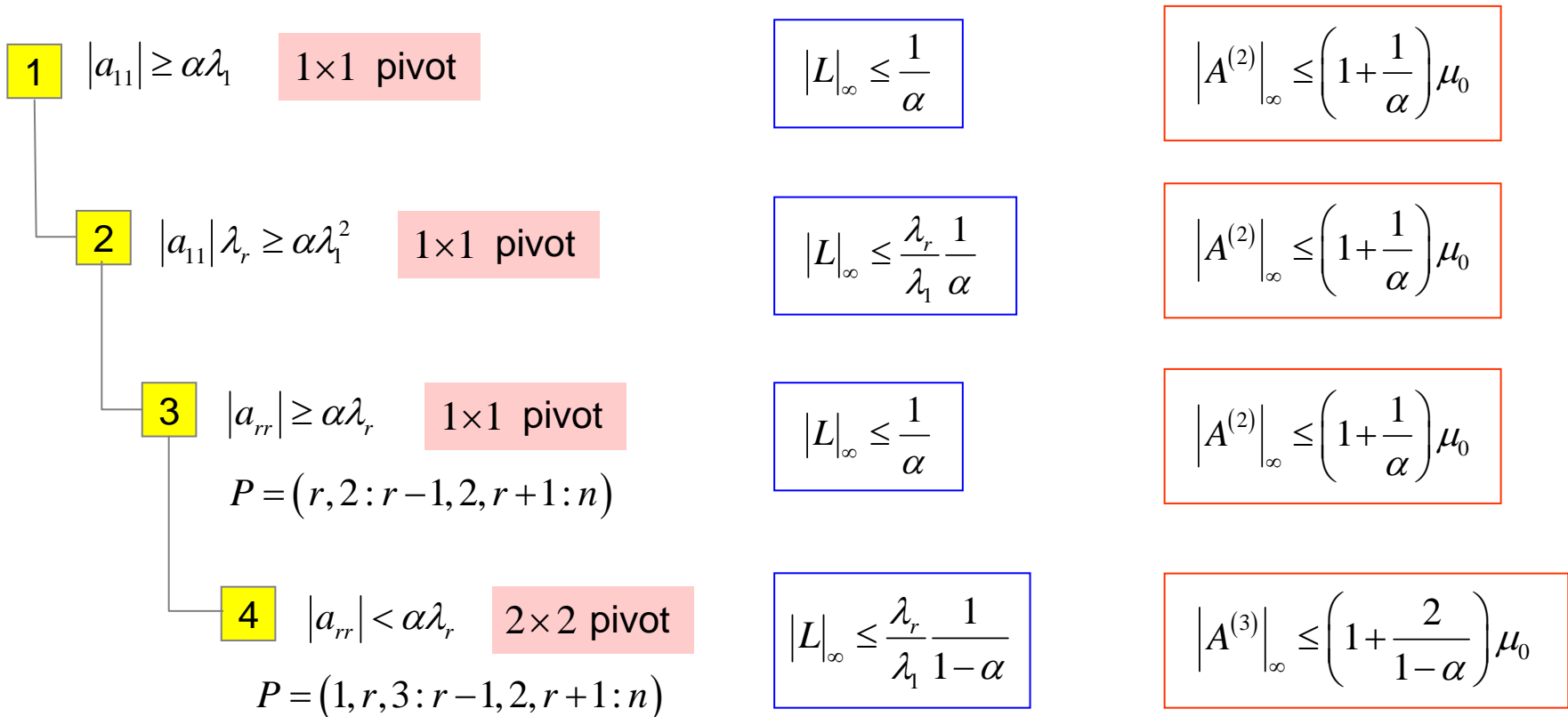
Remark: bound on lower triangle matrix is NOT good since it is proportional to $\frac{\lambda_r}{\lambda_1}$
 however, the bound of reduced matrix $A^{(3)}$ is good.

Partial pivoting: basic idea [16]

To sum up,
$$A = \begin{pmatrix} E & c^T \\ c & B \end{pmatrix} = \begin{pmatrix} 1 & \\ cE^{-1} & I \end{pmatrix} \begin{pmatrix} E \\ A^{(2,3)} \end{pmatrix} L^T$$

$\lambda_1 = |a_{r1}| = \max |c| =$ maximum of off-diagonal elements in column 1

$\lambda_r \equiv \max_{j \neq r} |a_{j,r}| =$ maximum of off-diagonal elements in column r



Partial pivoting: basic idea [17]

worst case analysis : choose $0 < \alpha < 1$ such that reduced matrix $A^{(2)}, A^{(3)}$ satisfies

$$\left[\text{growth rate of } 1 \times 1 \text{ pivot} + 1 \times 1 \text{ pivot} \right] \approx \left[\text{growth rate of } 2 \times 2 \text{ pivot} \right]$$

or equivalently $\left[\text{growth rate of } 1 \times 1 \text{ pivot} \right] \approx \sqrt{\left[\text{growth rate of } 2 \times 2 \text{ pivot} \right]}$

$$\left| A^{(2)} \right|_{\infty} \leq \left(1 + \frac{1}{\alpha} \right) \mu_0$$

$$\left| A^{(3)} \right|_{\infty} \leq \left(1 + \frac{2}{1-\alpha} \right) \mu_0$$

Define $B(\alpha) = \max \left(1 + \frac{1}{\alpha}, \sqrt{1 + \frac{2}{1-\alpha}} \right)$

$$\min_{0 < \alpha < 1} B(\alpha) = B(\alpha_0) = \frac{1 + \sqrt{17}}{2} \approx 2.5616 < 2.57$$

where $\alpha_0 = \frac{1 + \sqrt{17}}{8} \approx 0.6404$ satisfies $1 + \frac{1}{\alpha_0} = \sqrt{1 + \frac{2}{1-\alpha_0}}$

Remark: this optimal value is the same as we have in complete pivoting.

however, the bound of lower triangle matrix is **NOT** good.

Complete pivoting versus partial pivoting

$PAP^T = LDL^T$, growth rate of reduce matrix $A^{(k)}$ contributes to final block diagonal matrix D

complete pivoting

$$|L|_{\infty} \leq \max\left(\frac{1}{\alpha_0}, \frac{1}{1-\alpha_0}\right) = \max(1.56, 2.78) = 2.78$$

$$|D|_{\infty} \leq B(\alpha_0)^{n-1} \mu_0 \leq 2.57^{n-1} \mu_0$$

partial pivoting

$$|L|_{\infty} \leq \max_k \left(\frac{\lambda_r^{(k)}}{\lambda_l^{(k)}} \max\left(\frac{1}{\alpha_0}, \frac{1}{1-\alpha_0}\right) \right) = 2.78 \cdot \max_k \left(\frac{\lambda_r^{(k)}}{\lambda_l^{(k)}} \right)$$

$$|D|_{\infty} \leq B(\alpha_0)^{n-1} \mu_0 \leq 2.57^{n-1} \mu_0$$

Remark: Bunch in [1] only deal with controllability of reduced matrix $A^{(k)}$

However Ashcraft in [2] point out the importance of growth rate of L

Reference: [1] James R. *Bunch* and Linda *Kaufman*, Some Stable Methods for Calculating Inertia and Solving Symmetric Linear Systems, Mathematics of Computation, volume 31, number 137, January 1977, page 163-179

[2] Cleve Ashcraft, Roger G. Grimes, and John G. Lewis, Accurate Symmetric Indefinite Linear Equation Solvers, SIAM J. MATRIX ANAL. APPL. Vol. 20, No. 2, 1998, pp. 513-561

OutLine

- Review Bunch-Parlett diagonal pivoting
- Partial pivoting: basic idea
- **Implementation of partial pivoting**
- Example

Algorithm ($PAP' = LDL'$, partial pivot) [1]

Given symmetric indefinite matrix $A \in R^{n \times n}$, construct initial lower triangle matrix $L = I$

use permutation vector P to record permutation matrix $P^{(k)}$

let $A^{(1)} := A$, $L^{(0)} = I$, $P^{(0)} = (1, 2, 3, \dots, n)$ and $\text{pivot} = \text{zero}(n)$, $\alpha = \frac{1 + \sqrt{17}}{8} \approx 0.6404$

$k = 1$

while $k \leq (n-1)$

we have compute $P^{(k-1)} A (P^{(k-1)})^T = L^{(k-1)} A^{(k)} (L^{(k-1)})^T$

$$A^{(k)} = \left(\begin{array}{ccc|ccc} D_1 & 0 & \dots & 0 & \dots & 0 \\ 0 & \ddots & & & & \\ \vdots & & D_s & \dots & \dots & 0 \\ \hline \vdots & & 0 & a_{k,k}^{(k)} & \dots & a_{n,k}^{(k)} \\ \vdots & & \vdots & \vdots & & \vdots \\ 0 & \dots & 0 & a_{n,k}^{(k)} & \dots & a_{nn}^{(k)} \end{array} \right) \quad \text{update original matrix } A, \text{ where } D_i : 1 \times 1 \text{ or } 2 \times 2$$

$$L^{(k-1)} = \left. \left(\begin{array}{c|c} \overbrace{\left(\begin{array}{c|c} W & O \\ \hline M & I \end{array} \right)}^{k-1} \right) \right\} k-1 \quad \text{combines all lower triangle matrix and store in } L$$

Algorithm ($PAP' = LDL'$, partial pivot) [2]

1 compute $\lambda_1 = \max_{k+1 \leq j \leq n} |A_{j1}| = |A_{r1}|, \quad r \geq k$

Case 1: $|a_{kk}| \geq \alpha \lambda_1$ 1x1 pivot no interchange

2 do 1x1 pivot : $A^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & c^T \\ \hline & c & B \end{array} \right) = \left(\begin{array}{c|cc} I & & \\ \hline & 1 & \\ \hline & c/a_{kk}^{(k)} & I \end{array} \right) \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & \\ \hline & & B - cc^T/a_{kk}^{(k)} \end{array} \right) \left(L^{(k)} \right)^T$

$$\left\{ \begin{array}{l} L(k+1:n, k) \leftarrow c / a_{kk}^{(k)} \\ A(k+1:n, k+1:n) \leftarrow B - cc^T / a_{kk}^{(k)} \end{array} \right. \quad \text{then } A = L^{(k-1)} L^{(k)} A^{(k+1)} L^{(k)} \left(L^{(k-1)} \right)^T$$

3 $k \leftarrow k+1$ and $\text{pivot}(k) = 1$

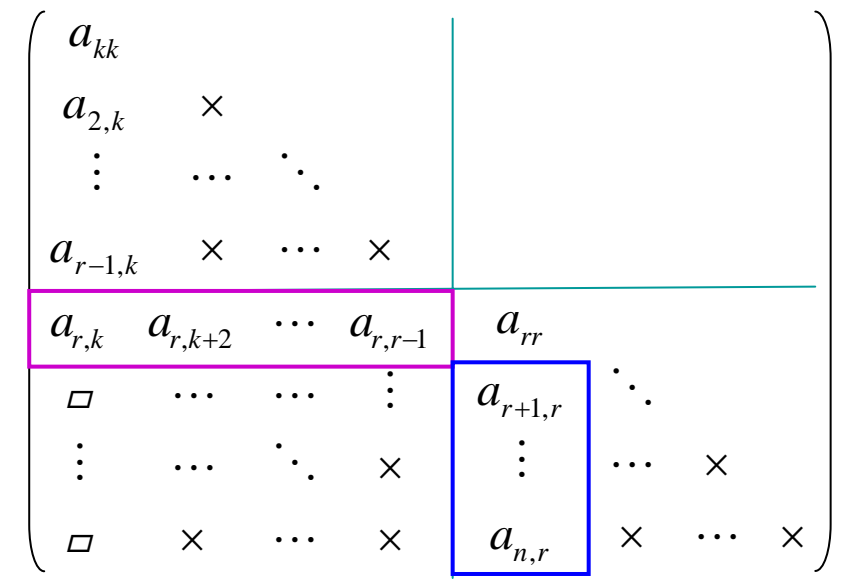
When case 1 is not satisfied, we compute

$$\lambda_r \equiv \max_{j \neq r} |a_{j,r}| = \text{maximum of off-diagonal elements in column } r$$

under lower triangular part of matrix A is used.

Algorithm (PAP' = LDL', partial pivot) [3]

- 4 $\lambda_r = \max(\max |A(r, k : r-1)|, \max |A(r+1 : n, r)|)$
 $\lambda_r \geq \lambda_1 > 0?$



Case 2: $|a_{kk}| \lambda_r \geq \alpha \lambda_1^2$ 1x1 pivot no interchange

- 5 do 1x1 pivot : $A^{(k)} = \begin{pmatrix} D_{k-1} & & \\ & a_{kk}^{(k)} & c^T \\ & c & B \end{pmatrix} = \begin{pmatrix} I & & \\ & 1 & \\ c/a_{kk}^{(k)} & & I \end{pmatrix} \begin{pmatrix} D_{k-1} & & \\ & a_{kk}^{(k)} & \\ & & B - cc^T/a_{kk}^{(k)} \end{pmatrix} (L^{(k)})^T$

{

then $A = L^{(k-1)} L^{(k)} A^{(k+1)} (L^{(k)})^T (L^{(k-1)})^T$

- 6 $k \leftarrow k+1$ and $pivot(k) = 1$ The same as code in case 1

Algorithm ($PAP' = LDL'$, partial pivot) [4]

Case 3: $|a_{rr}| \geq \alpha \lambda_r$ 1×1 pivot do interchange

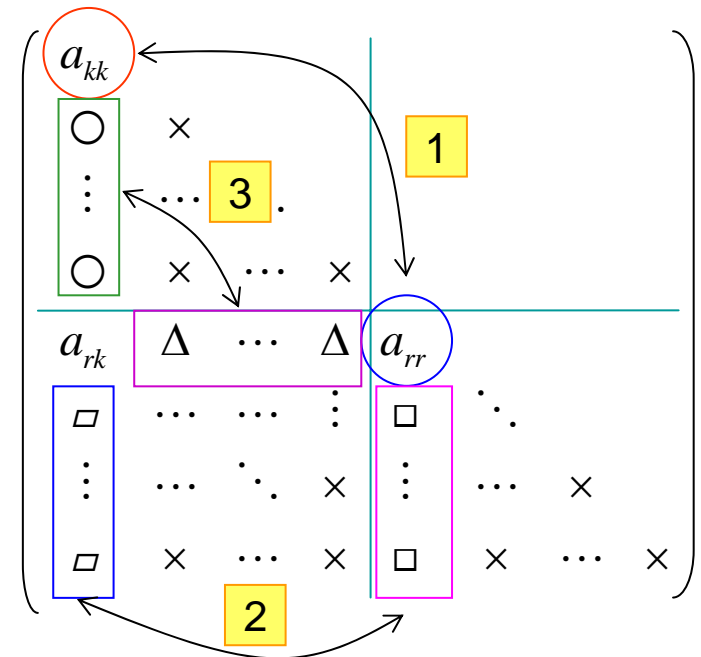
define permutation $P = (1:k-1, r, k+1:r-1, k, r+1:n)$ to do symmetric permutation

7 $P(k) \leftrightarrow P(r)$

To compute $\tilde{A}^{(k)} = P_k A^{(k)} P_k^T$, we only update lower triangle of $A^{(k)}$

- 8
- 1 $A(k, k) \leftrightarrow A(r, r)$
 - 2 $A(r+1:n, k) \leftrightarrow A(r+1:n, r)$
 - 3 $A(k+1:r-1, k) \leftrightarrow A(r, k+1:r-1)$

then $\tilde{A}^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & c^T \\ & c & B \end{array} \right), a_{kk}^{(k)} := a_{rr}$



Algorithm ($PAP' = LDL'$, partial pivot)

[5]

To compute $\tilde{L}^{(k-1)} = P_k L^{(k-1)} P_k^T$

9 We only update lower triangle matrix L

$$L(k, 1:k-1) \leftrightarrow L(r, 1:k-1)$$

then

$$P^{(k)} A (P^{(k)})^T = \tilde{L}^{(k-1)} \tilde{A}^{(k)} (\tilde{L}^{(k-1)})^T$$

$$L^{(k-1)} = \left(\begin{array}{cccc|cccc} 1 & & & & & & & \\ \times & 1 & & & & & & \\ \vdots & \dots & \ddots & & & & & \\ \times & \times & \dots & 1 & & & & \\ \hline l_{k,1} & l_{k,2} & \dots & l_{k,k-1} & 1 & & & \\ \vdots & \dots & \dots & \vdots & & 1 & & \\ \hline l_{r,1} & l_{r,2} & \ddots & l_{r,k-1} & & & \ddots & \\ \times & \times & \dots & \times & & & & 1 \end{array} \right)$$

10 do 1x1 pivot : $\tilde{A}^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & c^T \\ \hline c & & B \end{array} \right) = \left(\begin{array}{c|cc} I & & \\ \hline & 1 & \\ \hline c/a_{kk}^{(k)} & & I \end{array} \right) \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & \\ \hline & & B - cc^T / a_{kk}^{(k)} \end{array} \right) (L^{(k)})^T$

$$\begin{cases} L(k+1:n, k) \leftarrow c / a_{kk}^{(k)} \\ A(k+1:n, k+1:n) \leftarrow B - cc^T / a_{kk}^{(k)} \end{cases}$$

then $P^{(k)} A (P^{(k)})^T = \tilde{L}^{(k-1)} L^{(k)} A^{(k+1)} (L^{(k)})^T (\tilde{L}^{(k-1)})^T$

11 $k \leftarrow k+1$ and $pivot(k) = 1$

Algorithm ($PAP' = LDL'$, partial pivot) [6]

Case 4: $|a_{rr}| < \alpha \lambda_r$ 2x2 pivot do interchange

define permutation $P = (1:k, r, k+2:r-1, k+1, r+1:n)$, change a_{rk} to $a_{k+1,k}$

12 $P(k+1) \leftrightarrow P(r)$

To compute $\tilde{A}^{(k)} = P_k A^{(k)} P_k^T$, we only update lower triangle of $A^{(k)}$

13 do interchange row/col $k+1 \leftrightarrow r$

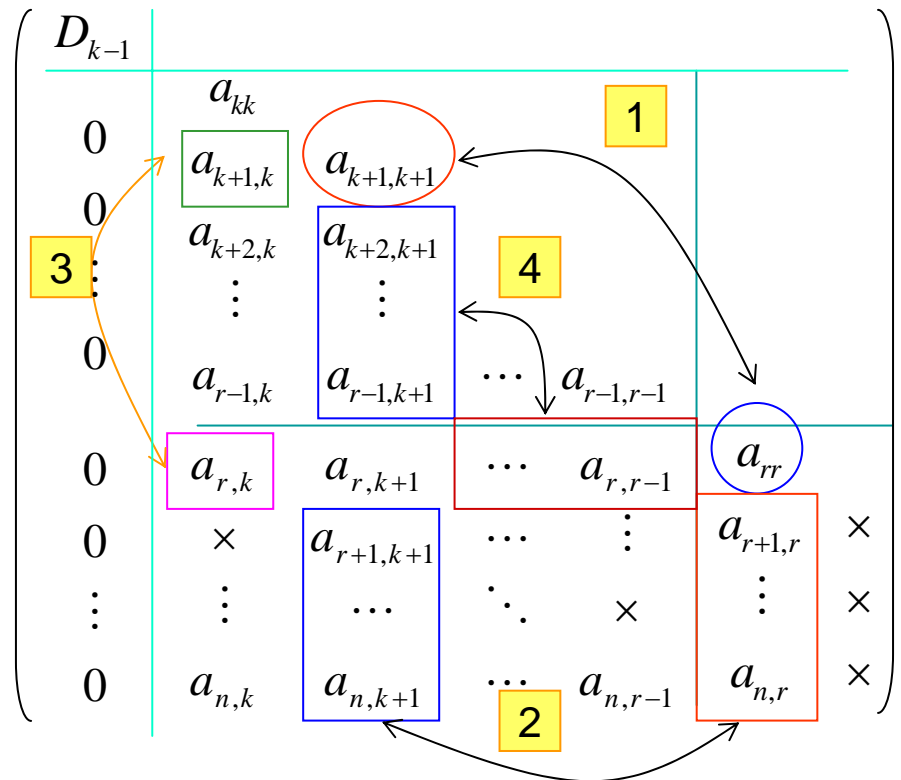
1 $A(k+1, k+1) \leftrightarrow A(r, r)$

2 $A(r+1:n, k+1) \leftrightarrow A(r+1:n, r)$

3 $A(k+1, k) \leftrightarrow A(r, k)$

4 $A(k+2:r-1:k+1) \leftrightarrow A(r, k+2:r-1)$

then
$$\tilde{A}^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & E & c^T \\ & c & B \end{array} \right), \quad E = \begin{pmatrix} a_{kk}^{(k)} & a_{r,k}^{(k)} \\ a_{r,k}^{(k)} & a_{rr}^{(k)} \end{pmatrix}$$



Algorithm ($PAP' = LDL'$, partial pivot) [7]

14 do interchange row $k+1 \leftrightarrow r$

$$L(k+1, 1:k-1) \leftrightarrow L(r, 1:k-1)$$

then

$$P^{(k)} A (P^{(k)})^T = \tilde{L}^{(k-1)} \tilde{A}^{(k)} (\tilde{L}^{(k-1)})^T$$

$$\left(\begin{array}{cccc|cccc} 1 & & & & & & & \\ \times & 1 & & & & & & \\ \vdots & \dots & \ddots & & & & & \\ l_{k,1} & l_{k,2} & \dots & 1 & & & & \\ \hline l_{k+1,1} & \dots & l_{k+1,k-1} & 0 & 1 & & & \\ \vdots & \dots & \dots & \vdots & & 1 & & \\ \hline l_{r,1} & \dots & l_{r,k-1} & 0 & & & \ddots & \\ \times & \times & \dots & 0 & & & & 1 \end{array} \right)$$

15 do 2x2 pivot : $\tilde{A}^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & E & c^T \\ \hline & c & B \end{array} \right) = \left(\begin{array}{c|cc} I & & \\ \hline & I & \\ \hline & cE^{-1} & I \end{array} \right) \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & E & \\ \hline & & B - cE^{-1}c^T \end{array} \right) (L^{(k)})^T$

$$\left\{ \begin{array}{l} L(k+2:n, k:k+1) \leftarrow cE^{-1} \\ A(k+2:n, k+2:n) \leftarrow B - cE^{-1}c^T \end{array} \right. \quad \text{then } P^{(k)} A (P^{(k)})^T = \tilde{L}^{(k-1)} L^{(k)} A^{(k+2)} (L^{(k)})^T (\tilde{L}^{(k-1)})^T$$

16 $k \leftarrow k+2$ and $\text{pivot}(k) = 2$

endwhile

Question: recursion implementation

normal {

- Initialization
 - check algorithm holds for $k=1$
- Recursion formula
 - check algorithm holds for k or $k+1$, if $k-1$ is true
- Termination condition
 - check algorithm holds for $k=n-1$

abnormal {

- Breakdown of algorithm
 - check which condition $PAP'=LDL'$ fails

Extension of algorithm {

- No extension: algorithm works only for square, symmetric indefinite matrix.

OutLine

- Review Bunch-Parlett diagonal pivoting
- Partial pivoting: basic idea
- Implementation of partial pivoting
- Example

Example (partial pivoting) [1]

$\alpha \approx 0.6404$

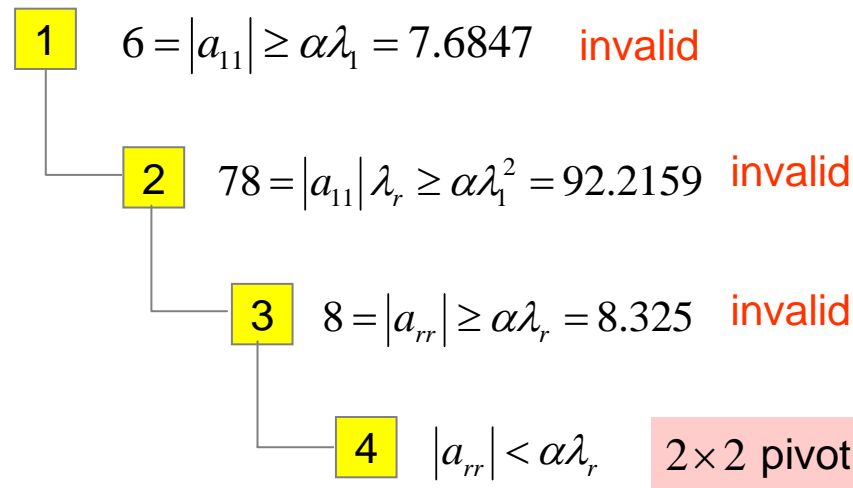
iteration 1: $k = 1$

$$\lambda_1 = \max |A(2:4,1)| = |A_{21}| = 12 \quad r = 2$$

$$\lambda_r = \max |(12, -13, 4)| = 13$$

$A^{(1)} = A$

6	12	3	-6
12	-8	-13	4
3	-13	-7	1
-6	4	1	6



12 $P(k+1) \leftrightarrow P(r)$, since $k+1 = r$, we don't need permutation

13 do interchange row/col $k+1 \leftrightarrow r$, since $k+1 = r$, we don't need permutation

1 $A(k+1, k+1) \leftrightarrow A(r, r)$ 2 $A(r+1:n, k+1) \leftrightarrow A(r+1:n, r)$

3 $A(k+1, k) \leftrightarrow A(r, k)$ 4 $A(k+2:r-1, k+1) \leftrightarrow A(r, k+2:r-1)$

Example (partial pivoting) [2]

- 14 do interchange row $k+1 \leftrightarrow r$, since $k+1 = r$, we don't need permutation
 $L(k+1, 1:k-1) \leftrightarrow L(r, 1:k-1)$

15 do 2x2 pivot : $\tilde{A}^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & E & c^T \\ \hline & c & B \end{array} \right) = \left(\begin{array}{c|cc} I & & \\ \hline & I & \\ \hline & cE^{-1} & I \end{array} \right) \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & E & \\ \hline & & B - cE^{-1}c^T \end{array} \right) \left(L^{(k)} \right)^T$

$$\left(\begin{array}{c} A^{(1)} \\ \left(\begin{array}{|cccc|} \hline 6 & 12 & 3 & -6 \\ 12 & -8 & -13 & 4 \\ \hline 3 & -13 & -7 & 1 \\ -6 & 4 & 1 & 6 \end{array} \right) \end{array} \right) = \left(\begin{array}{c} L^{(1)} \\ \left(\begin{array}{|cccc|} \hline 1 & & & \\ & 1 & & \\ \hline -0.6875 & 0.5938 & 1 & \\ 0 & -0.5 & & 1 \end{array} \right) \end{array} \right) \left(\begin{array}{c} A^{(3)} \\ \left(\begin{array}{|cccc|} \hline 6 & 12 & & \\ 12 & -8 & & \\ \hline & & 2.7813 & -5.5 \\ & & -5.5 & 8 \end{array} \right) \end{array} \right) \left(L^{(1)} \right)^T$$

- 16 $k \leftarrow k+2$ and $\text{pivot}(k) = 2$

$$\boxed{k=3} \quad \text{pivot} = \begin{array}{|cccc|} \hline 2 & 0 & 0 & 0 \\ \hline \end{array}$$

Example (partial pivoting) [3]

iteration 2: $k = 3$

$$\lambda_1 = \max |A(3:4, 3)| = |A_{43}| = 5.5$$

$r = 4$

$$\lambda_r = \max |(-5.5)| = 5.5$$

$$A^{(3)} = \begin{pmatrix} 6 & 12 & & \\ 12 & -8 & & \\ & & 2.7813 & -5.5 \\ & & -5.5 & 8 \end{pmatrix}$$

1 $2.7813 = |a_{33}| \geq \alpha \lambda_1 = 3.5221$ **invalid**

2 $15.2971 = |a_{11}| \lambda_r \geq \alpha \lambda_1^2 = 19.3717$ **invalid**

3 $8 = |a_{rr}| \geq \alpha \lambda_r = 3.5221$ **1x1 pivot**

7 $P(k) \leftrightarrow P(r)$ $P = (1, 2, 3, 4) \xrightarrow{3 \leftrightarrow 4} P = (1, 2, 4, 3)$

Compute $\tilde{A}^{(k)} = P_k A^{(k)} P_k^T$

- 8** {
- 1** $A(k, k) \leftrightarrow A(r, r)$
 - 2** $A(r+1:n, k) \leftrightarrow A(r+1:n, r)$
 - 3** $A(k+1:r-1, k) \leftrightarrow A(r, k+1:r-1)$

$$\tilde{A}^{(3)} = \begin{pmatrix} 6 & 12 & & \\ 12 & -8 & & \\ & & 8 & -5.5 \\ & & -5.5 & 2.7813 \end{pmatrix}$$

Example (partial pivoting) [4]

Compute $\tilde{L}^{(k-1)} = P_k L^{(k-1)} P_k^T$ 9 $L(k, 1:k-1) \leftrightarrow L(r, 1:k-1)$

$$\begin{array}{c} L^{(1)} \\ \left(\begin{array}{cccc} 1 & & & \\ & 1 & & \\ -0.6875 & 0.5938 & 1 & \\ 0 & -0.5 & & 1 \end{array} \right) \end{array} \xrightarrow{3 \leftrightarrow 4} \begin{array}{c} \tilde{L}^{(1)} \\ \left(\begin{array}{cccc} 1 & & & \\ & 1 & & \\ 0 & -0.5 & 1 & \\ -0.6875 & 0.5938 & & 1 \end{array} \right) \end{array}$$

10 do 1x1 pivot : $\tilde{A}^{(k)} = \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & c^T \\ \hline & c & B \end{array} \right) = \left(\begin{array}{c|cc} I & & \\ \hline & 1 & \\ \hline & c/a_{kk}^{(k)} & I \end{array} \right) \left(\begin{array}{c|cc} D_{k-1} & & \\ \hline & a_{kk}^{(k)} & \\ \hline & & B - cc^T/a_{kk}^{(k)} \end{array} \right) (L^{(k)})^T$

$$\begin{array}{c} \tilde{A}^{(3)} \\ \left(\begin{array}{cccc} 6 & 12 & & \\ 12 & -8 & & \\ & & 8 & -5.5 \\ & & -5.5 & 2.7813 \end{array} \right) \end{array} = \begin{array}{c} L^{(3)} \\ \left(\begin{array}{cccc} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & -0.6875 & 1 \end{array} \right) \end{array} \begin{array}{c} A^{(4)} \\ \left(\begin{array}{cccc} 6 & 12 & & \\ 12 & -8 & & \\ & & 8 & \\ & & & -1 \end{array} \right) \end{array} (L^{(3)})^T$$

Example (partial pivoting) [5]

11 $k \leftarrow k+1$ and $\text{pivot}(k)=1$

$k=4$ $\text{pivot} = \begin{bmatrix} 2 & 0 & 1 & 0 \end{bmatrix}$

iteration 3: $k=4$

issue proper termination condition.

To sum up

$PAP^T = LDL^T$ →

$P = \begin{bmatrix} 1 & 2 & 4 & 3 \end{bmatrix}$

$\text{pivot} = \begin{bmatrix} 2 & 0 & 1 & 1 \end{bmatrix}$

$L = \tilde{L}^{(1)}L^{(3)} = \begin{pmatrix} \begin{array}{cccc} 1 & & & \\ & 1 & & \\ \hline 0 & -0.5 & 1 & \\ -0.6875 & 0.5938 & -0.6875 & 1 \end{array} \end{pmatrix}$

$D = A^{(4)} = \begin{pmatrix} \begin{array}{cccc} 6 & 12 & & \\ 12 & -8 & & \\ \hline & & 8 & \\ & & & -1 \end{array} \end{pmatrix}$

Example: complete pivot versus partial pivot

$$A = \begin{pmatrix} 6 & 12 & 3 & -6 \\ 12 & -8 & -13 & 4 \\ 3 & -13 & -7 & 1 \\ -6 & 4 & 1 & 6 \end{pmatrix} \quad \alpha = \frac{1 + \sqrt{17}}{8}$$

Complete pivot

$$P = \begin{bmatrix} 2 & 3 & 4 & 1 \end{bmatrix}$$

$$pivot = \begin{bmatrix} 2 & 0 & 1 & 1 \end{bmatrix}$$

Partial pivot

$$P = \begin{bmatrix} 1 & 2 & 4 & 3 \end{bmatrix}$$

$$pivot = \begin{bmatrix} 2 & 0 & 1 & 1 \end{bmatrix}$$

$$L = \begin{pmatrix} 1 & & & \\ & 1 & & \\ 0 & -0.5 & 1 & \\ -0.6875 & 0.5938 & -0.6875 & 1 \end{pmatrix}$$

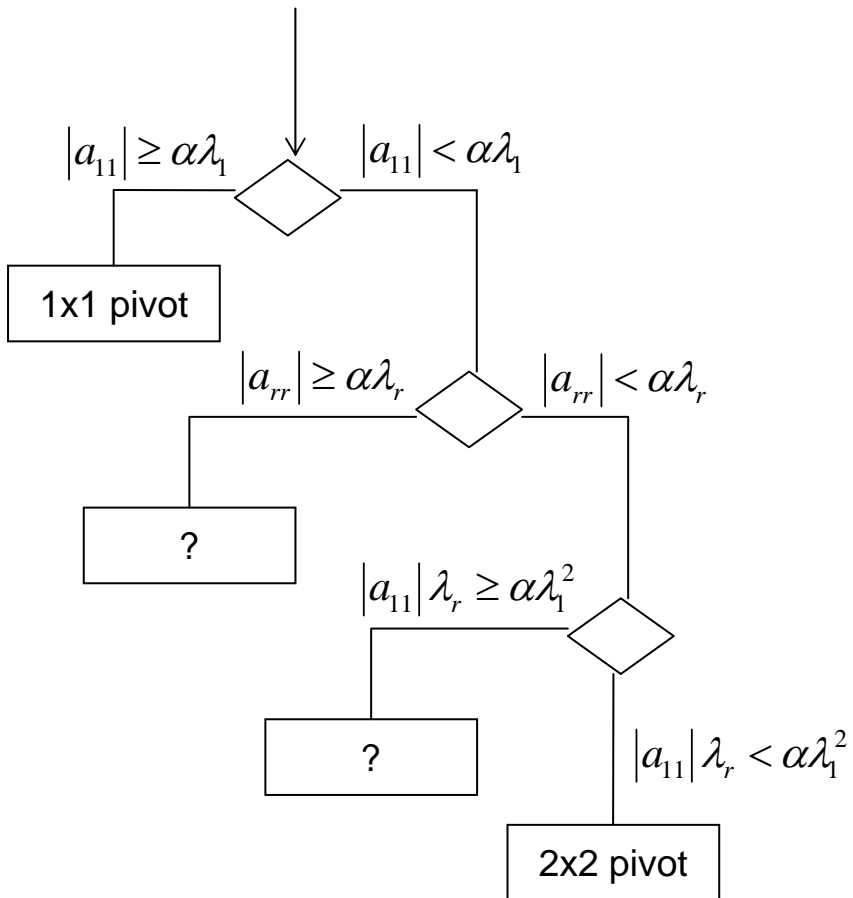
$$D = \begin{pmatrix} 6 & & & \\ 12 & -8 & & \\ & & 8 & \\ & & & -1 \end{pmatrix}$$

$$L = \begin{pmatrix} 1 & & & \\ & 1 & & \\ 0.1327 & -0.3984 & 1 & \\ 0.3982 & -1.1681 & -1.0967 & 1 \end{pmatrix}$$

$$D = \begin{pmatrix} -8 & & & \\ -13 & -7 & & \\ & & 5.8584 & \\ & & & -2.3202 \end{pmatrix}$$

Exercise

How about flow-chart of left figure?



Bunch-Kaufman proposed flow chart

